

Technical Information

PLUS+1 SC Controllers

SC0XX-1XX Controller Family



Revision history

Table of revisions

Date	Changed	Rev
June 2016	Updated Digital/Analog/Resistance/4-20 mA Current (DIN/AIN/ResIN/CrntIN) Specifications	0201
March 2015	Various text update and added tables for control of outputs	BA
December 2014	First edition	AA

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SC0XX-1XX Controller literature references

Reference literature

Literature title	Literature type	Literature number
<i>PLUS+1° SC0XX-1XX Controller Family</i>	Technical Information	L1415500
<i>PLUS+1° SC Controller SC024-110 and SC024-112</i>	Data Sheet	L1410890
<i>PLUS+1° SC Controller SC024-120 and SC024-122</i>	Data Sheet	L1410171
<i>PLUS+1° SC Controller SC050-120 and SC050-122</i>	Data Sheet	L1410421
<i>PLUS+1° SC Controller SC050-13H</i>	Data Sheet	L1407546
<i>PLUS+1° GUIDE Software User Manual</i>	Operation Manual	10100824

Technical Information (TI)

A TI is comprehensive information for engineering and service personnel to reference.

Data Sheet (DS)

A DS is summarized information and parameters that are unique to a specific model.

API Specifications (API)

An API is specifications for programming variable settings.

[API specifications are the definitive source of information regarding pin characteristics.](#)

PLUS+1° GUIDE User Manual

This user operation manual (OM) details information regarding the PLUS+1° GUIDE tool set that is used to build PLUS+1° applications. This OM covers the following broad topics:

- How to use the GUIDE graphical application development tool to create machine applications
- How to configure module input and output parameters
- How to configure module input and output parameters
- How to download GUIDE applications to target PLUS+1° hardware modules
- How to upload and download tuning parameters
- How to use the PLUS+1° Service Tool

Latest version of technical literature

Danfoss product literature is online at: <http://powersolutions.danfoss.com/literature/>

User liability and safety statements

OEM responsibility

The OEM of a machine or vehicle in which Danfoss products are installed has the full responsibility for all consequences that might occur. Danfoss has no responsibility for any consequences, direct or indirect, caused by failures or malfunctions.

- Danfoss has no responsibility for any accidents caused by incorrectly mounted or maintained equipment.
- Danfoss does not assume any responsibility for Danfoss products being incorrectly applied or the system being programmed in a manner that jeopardizes safety.
- All safety critical systems shall include an emergency stop to switch off the main supply voltage for the outputs of the electronic control system. All safety critical components shall be installed in such a way that the main supply voltage can be switched off at any time. The emergency stop must be easily accessible to the operator.

Certified SIL 2 Capable

The SC0XX-1XX Controller Family is certified SIL 2 Capable when deployed with the certified SIL 2 Capable OS that is embedded in their respective SC0XX-1XX HWD files.

The SC0XX-0XX Controller Family is designed for meeting the needs of SIL 2 applications where the OEM certifies at the machine level. The SC0XX-0XX Controller Family is not certified SIL 2 Capable as a component regardless of the HWD files with which it is deployed. The table below summarizes this information (the HWD filenames are representative, but not actual).

In all cases, the OEM/customer is responsible for the safety integrity requirement, implementation, and validation of their application.

Controller Family	HWD for the Primary Processor	HWD for the Secondary Processor	Component-Level SIL 2 Capable	Machine-Level SIL 2 Capable
SC0XX-1XX	SC0XX-1XX_HWD_Primary*	SC0XX-1XX_HWD_Secondary*	Yes	Yes
SC0XX-1XX	SC0XX-0XX_HWD_Primary	SC0XX-0XX_HWD_Secondary	No	Yes
SC0XX-0XX	SC0XX-1XX_HWD_Primary*	SC0XX-1XX_HWD_Secondary*	No	Yes
SC0XX-0XX	SC0XX-0XX_HWD_Primary	SC0XX-0XX_HWD_Secondary	No	Yes

* These HWD files incorporate the certified SIL 2 Capable OS with Safety Diagnostic Functions.

Overview

PLUS+1® Mobile Machine Modules

PLUS+1® Mobile Machine Modules are designed to provide flexible, expandable, powerful and cost effective total machine management system displays for a wide variety of vehicle applications.

PLUS+1® controller products utilize modular designs wherever possible. This modularity extends to product housings, connectors and control circuitry.

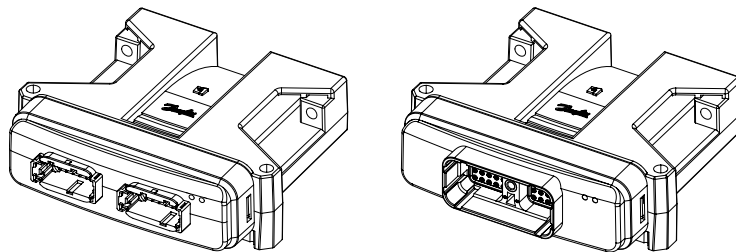
SC Controller Family

The SC0XX-1XX Controller Family has been certified as SIL 2 Capable. This means it is suitable for use in critical applications up to and including Safety Integrity Level 2. The SIL Rating reflects the level of risk reduction that the device can provide when used as part of a safety instrumented system.

The third party assessment and certification verifies that the product hardware and software design, the safety manual, as well as the processes that are used for development, testing, configuration management, quality control, etc., comply with the 250+ requirements of the IEC 61508 international standard.

Use of certified devices makes it much easier to design and implement a safety system. It can significantly reduce cost over the long term and provides an important measure of quality and reliability.

24 and 50 Pin SC Controllers



P200147

The SC Controller Family comes in the same sized blue housing.

These modules communicate with one another and other intelligent systems over a machine Controller Area Network (CAN) data bus. PLUS+1® hardware products are designed to be equally effective in a distributed CAN system, with intelligence in every node, or as stand-alone control for smaller machine systems. PLUS+1® systems are incrementally expandable: additional modules can be easily added to the machine CAN bus to increase system capabilities or computational power.

Inputs/outputs types and specifications

PLUS+1® modules have input or output pins that support multiple functions. Pins that support multiple input or output types are user-configurable using PLUS+1® GUIDE software. Refer to product data sheets for the input/output (I/O) content of individual modules.

Inputs

Input types

- Digital or Analog (DIN/AIN)
- Analog Input Offset
- A/D Refresh Rate
- Digital/Analog/Frequency (DIN/AIN/FreqIN)
- Digital/Analog/Resistance/4-20 mA Current (DIN/AIN/ResIN/CrntIN)
- Digital/Analog/1.6 Vdc Sensor Power (DIN/AIN/SnsrPwr1.6Vdc)
- Digital/Analog/3.6 Vdc Sensor Power (DIN/AIN/SnsrPwr3.6Vdc)

Each PLUS+1[®] module input pin supports one of the above functional types. For pins with multiple functions, input configurations are user programmable using PLUS+1[®] GUIDE templates.

Digital/Analog (DIN/AIN), A/D Refresh Rates

Multifunction pins that are configured to be DIN are subject to the same update rates as the analog input function for that pin. Debounce is not used, as hysteresis is built into the function. The time to recognize a transition is dependent on the timing of the switch activation and the sample rate.

General

Description	Comment
Response to input below minimum voltage	Non-damaging, non-latching; reading saturates to the low limit.
Response to input above maximum voltage	Non-damaging, non-latching; reading saturates to the high limit.
Response to input open	Pin configuration dependent: No pull up/ no pull down = floating Pull up to 5 Vdc = 5 Vdc Pull down = 0 Vdc Pull up/ pull down = 2.5 Vdc
Voltage working ranges	Programmable (see specific data sheets for ranges).

Specifications

Description	Units	Minimum	Maximum	Comment
Allowed voltage at pin	Vdc	0	36	— —
Maximum discernable voltage (high range)	Vdc	34.10	36.5	35.3 Vdc is typical.
Minimum discernable voltage (high range)	mV	0	130	— —
Maximum discernable voltage (middle range)	Vdc	5.13	5.38	5.26 Vdc is typical.
Minimum discernable voltage (low range)	mV	0	20	— —
Precision (high range)	mV	— —	9	— —
Worst case error (high range)	Vdc	— —	1.16	— —
Precision (middle range)	mV	— —	1.3	— —
Worst case error (middle range)	mV	— —	120	— —
Input impedance (pulled up to 5 Vdc or ground, middle range)	kΩ	13.9	14.3	— —
Input impedance (pulled up to 2.5 Vdc middle range)	kΩ	7.2	7.4	— —
Input impedance (no pull ups, middle range)	kΩ	230	236	— —
Input impedance (pulled up to 5 Vdc or ground, high range)	kΩ	13.0	13.4	— —
Input impedance (pulled up to 2.5 Vdc high range)	kΩ	6.9	7.1	— —
Input impedance (no pull ups, high range)	kΩ	108	112	— —

Inputs

A/D refresh rates for SC Controllers

SC Controller	A/D refresh rate
SC024-110/112	All: 1.0 ms
SC024-120/122	All: 1.0 ms
SC050-120/122	All: 1.0 ms
SC050-13H	All: 1.0 ms

Digital/Analog/Frequency (DIN/AIN/FreqIN)

The characteristics of Digital/Analog/Frequency pins are PLUS+1® GUIDE software controlled. The input can be digital, analog or frequency. Inputs can be pulled to 5 Vdc, pulled to ground, pulled to 2.5 Vdc, or no pull-up/pull-down.

General

Description	Comment
Response to input below minimum voltage	Non-damaging, non-latching; reading saturates to the low limit.
Response to input above maximum voltage	Non-damaging, non-latching; reading saturates to the high limit.
Expected measurement	Frequency (Hz)
	Period (0.1 µsec)
	Channel to channel phase shift (paired inputs . . .) (0.1 ms).
	PWM duty cycle (0.01%)—Duty cycle measurement only valid up to 5 kHz (FreqIN).
	Edge count.
	Quadrature count (paired inputs driven from a quadrature encoder).
Pull up/pull down configuration	No pull down/ pull up is standard with pull up or pull down programmable; failure modes are detectable.
Maximum frequency	The controller may re-boot under some high frequency load conditions above 10 kHz.

Specifications

Description	Units	Minimum	Maximum	Comment
Allowed voltage at pin	Vdc	0	36	
Frequency range	Hz	0	10,000	In steps of 1 Hz.
Frequency input when used as quad count or phase shift	Hz	0	5000	In steps of 1 Hz.
Maximum discernable voltage (high range)	Vdc	34.1	36.5	35.3 Vdc is typical.
Minimum discernable voltage (high range)	mV	0	130	
Maximum discernable voltage (middle range)	Vdc	5.13	5.38	5.26 Vdc is typical.
Minimum discernable voltage (middle range)	mV	0	20	
Maximum discernable voltage (low range)	Vdc	0.341	0.395	0.368 Vdc is typical.
Minimum discernable voltage (low range)	mV	0	12.9	
Precision (high range)	mV	— —	9	
Worst case error (high range)	Vdc	— —	1.16	
Precision (middle range)	mV	— —	1.3	
Worst case error (middle range)	mV	— —	120	
Precision (low range)	mV	— —	90	
Worst case error (low range)	mV	— —	27	
Input impedance (pulled to 5 Vdc or ground, low range)	kΩ	13.9	14.3	

Inputs

Specifications (continued)

Description	Units	Minimum	Maximum	Comment
Input impedance (pulled to 2.5 Vdc, low range)	kΩ	7.2	7.4	
Input impedance (no pull ups, low range)	kΩ	230	236	
Input impedance (pulled to 5 Vdc or ground, middle range)	kΩ	13.9	14.3	
Input impedance (pulled to 2.5 Vdc middle range)	kΩ	7.2	7.4	
Input impedance (no pull ups, middle range)	kΩ	230	236	
Input impedance (pulled to 5 Vdc or ground, high range)	kΩ	13	13.4	
Input impedance (pulled to 2.5 Vdc high range)	kΩ	6.9	7.1	
Input impedance (no pull ups, high range)	kΩ	108	112	

This table shows the rising and falling thresholds when the input is used as a frequency input.

Specifications

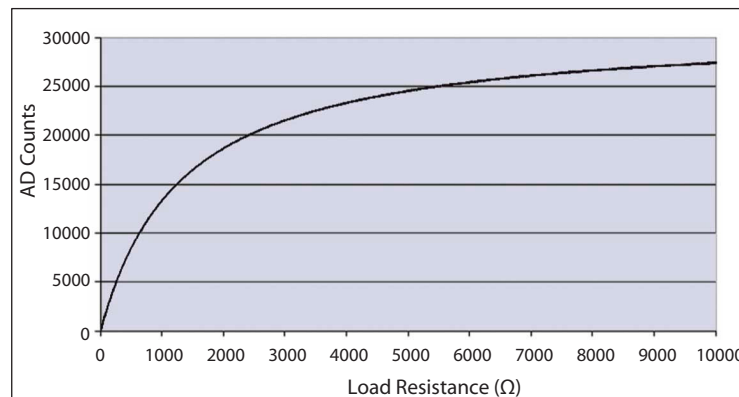
Description	Units	Minimum	Maximum	Comment
Rising voltage threshold (high range)	Vdc	11.83	26.55	Voltage required for frequency input to read high.
Falling voltage threshold (high range)	Vdc	5.61	18.89	Voltage required for frequency input to read low.
Rising voltage threshold (middle range)	Vdc	1.78	3.92	Voltage required for frequency input to read high.
Falling voltage threshold (middle range)	Vdc	0.84	2.79	Voltage required for frequency input to read low.
Rising voltage threshold (low range)	Vdc	0.11	0.30	Voltage required for frequency input to read high.
Falling voltage threshold (low range)	Vdc	0.04	0.22	Voltage required for frequency input to read low.

If the frequency goes to zero, the data will not decay over time, it will be updated once a new pulse is seen, or times out. It is possible to monitor the count of pulses to know when the frequency reading is updated.

Digital/Analog/Resistance/4-20 mA Current (DIN/AIN/ResIN/CrntIN)

When a SC Controller input pin is configured as a resistance/rheostat/temp sensor input, the device will provide up to 3.76 mA current to an external load (RL) which then can be measured. The equation for relating AD counts to a given load is: $AD\ counts = (30996 * RL) / (RL + 1322)$. This calculation is solved internally and the ohms value is available for the programmer. The following Rheostat inputs chart shows the relationship between AD counts and load resistance in ohms.

Rheostat inputs chart



P200 083

Inputs

Specifications

Description	Units	Minimum	Maximum	Comment
Allowed voltage at pin	Vdc	0	36	
Measured resistance	Ω	0	10,000	
Minimum discernable current	mA	0	0.1	
Maximum discernable current	mA	25.3	27	
Precision	μA		6	
Worst case error	μA		868	Over the full temperature range -40°C to 85°C (-40°F to 185°F)
Input impedance	Ω	198.6	202.6	
Maximum over-current protection time at start up (current ≥ 24 mA)	ms		100	
Recover time after over-current protection	s	5.4		
Maximum discernable voltage (high range)	Vdc	25.3		
Minimum discernable voltage (high range)	mV	0	130	
Precision (high range)	mV		9	
Worst case error (high range)	Vdc		1.16	Over the full temperature range -40°C to 85°C (-40°F to 185°F)
Maximum discernable voltage (middle range)	Vdc	5.13	5.38	
Minimum discernable voltage (middle range)	mV	0	20	
Precision (middle range)	mV		1.3	
Worst case error	mV		120	Over the full temperature range -40°C to 85°C (-40°F to 185°F)
Input impedance (pulled to 5 Vdc or ground high range)	KΩ	13.0	13.4	
Input impedance (pulled to 2.5 Vdc high range)	KΩ	6.9	7.1	
Input impedance (no pull ups high range)	KΩ	108	112	
Input impedance (pulled to 5 Vdc or ground middle range)	KΩ	13.9	14.3	
Input impedance (pulled to 2.5 Vdc middle range)	KΩ	7.2	7.4	
Input impedance (no pull ups middle range)	KΩ	230	236	

Outputs

Output types

- Digital (DOUT)
- Pulse Width Modulated (PWM/DOUT/PVGOUT)

Output pins available on SC Controller Family

SC Controller	DOUT (3 A)	PWMOUT/DOUT/(3 A)
SC024-110/112		4
SC024-120/122		8
SC050-120/122	6	8
SC050-13H	6	8

The power pin of a PVG valve should only be connected to a digital output.

PLUS+1® control modules feature user-configurable output pin parameters. Output pin parameters are configured using PLUS+1® GUIDE templates.

Refer to module data sheets for maximum output current ratings of individual modules. The total output current for any PLUS+1® module must not exceed the maximum allowable current specified in the module data sheet.

Warning

Unintended movement of the machine or mechanism may cause injury to the technician or bystanders. The module will be powered up if battery voltage is applied to the module's output pin. To protect against unintended movement, secure the machine.

Caution

Warranty will be voided if module is damaged by significant current driven back through an output pin.

Digital (DOUT)

Digital outputs can source up to 3 A.

General

Description	Comment
Configuration	Sourcing only.
Type	Linear switching.
Short circuit to ground protection	Non-damage, current/thermal limit with status indication; automatic latch off /resume.
Open circuit detection	Fault indication provided. The GUIDE Pin Status requires a load of 0.22 A to be connected or an open fault will be declared.
Parallel operation	Digital outputs from the same module are capable of being connected together such that the net current rating is the sum of the individual ratings; timing is resolved by the operating system; diagnostic capability is maintained.
Shut off	Processor control with hardware WatchDog override.

Outputs

Specifications

Description	Units	Minimum	Maximum	Comment
Output voltage, energized state	Vdc	Vbatt-1.0	Vbatt	Over all load conditions.
Output voltage, off state	Vdc	0	0.1	At Rload=200 Ω
Output current range for a status bit to read OK	A	0.22	3	

Do not connect a digital output to battery+ (back drive) without a series diode.

For each digital output there are two switches in series. One switch is controlled and monitored by the secondary controller, and one is controlled and monitored by the primary processor. The secondary controller can monitor the condition of the redundant switch under its control with a digital voltage feedback signal. Any output can be disconnected from its supply voltage at any time by the secondary controller with this redundant switch. When the redundant switch is disabled it must remain disabled by the kernel for 250 milliseconds before the secondary controller's application is allowed to re-enable the redundant switch. When the redundant switch controlled by the secondary controller is enabled then the digital outputs can be enabled/disabled as commanded by the primary processor. The primary processor can monitor the condition of its switch with a digital voltage feedback signal.

Control of DOUT

DOUT Status	Description	Recovery
BIT 3	Over temperature/open load	<ol style="list-style-type: none"> 1. The primary application must first command the output to the off-state. 2. The BTS chip temperature must return to its valid range. 3. The kernel then clears status bit 3.
BIT 6	Safety layer failure	<ol style="list-style-type: none"> 1. The controller must be reset by performing a power cycle.
BIT 7	Safety FET disabled by secondary	<ol style="list-style-type: none"> 1. The Safety FET must be off for 250 ms. 2. The primary application must command the output to the off-state. 3. The secondary application can then re-enable the output.
BIT 8	Hardware supply power out of range	<ol style="list-style-type: none"> 1. The primary application must command ALL outputs to the off-state. 2. The supply voltage must return to its valid range. 3. The kernel then clears status bit 8.

Pulse Width Modulated (PWMOUT/DOUT)

All PLUS+1® module proportional outputs are Pulse Width Modulated (PWM). PWM frequency is software adjustable using PLUS+1® GUIDE. A low frequency dither may also be added with software to some outputs (see individual module API specifications for PWM outputs that support dither). There are two modes of PWM operation: open loop and closed loop (current control).

In open loop mode, current can be sourced or sunk (all modules are limited to 8 amps sinking), but the output is a PWM duty cycle. Current feedback may be monitored in open loop mode, but the output is a constant voltage, not a constant current. The signal line of PVG valves can be driven with an open loop PWM. The PWM driving the control signal must be set to 0 at the same time as the digital output driving the PVE power pin is set to 0.

In closed loop mode, current is sourced and a constant current is maintained by the module's operating system using internal current feedback. Load impedance must not exceed 65 ohms.

In closed loop mode, the maximum current is limited by measuring the feedback current. There is no thermal protection. If the maximum current is exceeded, the controller kernel will shut down the output and latch it. The kernel also limits how quickly the output can be repowered (250 ms). The output cannot be reset until the command goes to 0 or False (if configured as a digital output).

Refer to individual module data sheets for the maximum allowable output current for each PLUS+1 module.

Outputs

General

Description	Comment
Configuration	Sourcing or sinking.
Type (Linear vs. PWM)	PWM
Operating modes	Programmable: closed loop current or open loop voltage (duty cycle).
Dual coil PCPs	Compensated for induced currents in a non-driven coil (closed loop mode).
Short circuit to ground	Output fully protected against damage and fault detected.
Mode selection (current or voltage) and full scale current ranges	Programmable.

Do not connect a digital output to battery+ (back drive) without a series diode.

PLUS+1® PWM output circuits are not designed to be used as inputs. Output current feedback readings should be used for fault checking only.

Warning

Unintended movement of the machine or mechanism may cause injury to the technician or bystanders. The module will be powered up if battery voltage is applied to the module's output pin. To protect against unintended movement, secure the machine.

Caution

Warranty will be voided if module is damaged by significant current driven back through an output pin.

Specifications

Description	Units	Minimum	Maximum	Comment
Full scale proportional current output	mA	10	3000	The current may accidentally be exceeded in open loop mode. If the current exceeds the trip point, the output will be latched off.
Output voltage, 100% duty cycle	Vdc	0	Vbatt-1	
Output resolution of 3 A	mA		0.25	
Repeatability of full range	% of full scale		0.5	
Absolute accuracy of full range	% of full scale		0.3	
Output settling time	ms		100	Depends on load characteristics.
PWM frequency	Hz	33	4000 and 20,000	
Dither frequency	Hz	40	250	Increased in steps, see module API.
Dither amplitude	A	0	0.5	Increased in steps, see module API.
Over-current trip point	A	5	7.3	There is over-current protection built into each output driver. If the instantaneous current exceeds the trip point, the driver is latched off. GUIDE application software can reset the latch and attempt to drive current again.

For each PWM output there are two switches in series for sourcing current/voltage (the high-side of the half bridge has two switches). One switch is controlled and monitored by the secondary controller, and the other is controlled and monitored by the primary processor. The secondary controller can monitor the condition of the redundant switch under its control with a digital voltage feedback signal. Each sourcing PWM output can be disconnected from its supply voltage at any time by the secondary controller with this redundant switch. When the redundant switch is disabled it must remain disabled by the kernel for 250 ms before the secondary controller's application is allowed to re-enable the redundant switch. When the switch controlled by the secondary controller is enabled then the PWM outputs are

Outputs

allowed to source current as commanded by the primary processor. The primary processor can monitor the condition of its switch with the analog current feedback measurement.

Control of PWMOUT/DOUT

PWMOUT/DOUT Status	Description	Recovery
BIT 4	Overload	<ol style="list-style-type: none"> 1. The kernel will automatically disable the output. 2. The primary application must set the output to the off-state for a minimum of 250 ms. 3. The kernel then clears status bit 4 and re-enables the output.
BIT 5	Incorrect selected output mode	<ol style="list-style-type: none"> 1. The primary application must select a valid output mode. 2. The kernel then clears status bit 5.
BIT 6	Safety layer failure	<ol style="list-style-type: none"> 1. The controller must be reset by performing a power cycle.
BIT 7	Safety FET disabled by secondary	<ol style="list-style-type: none"> 1. The Safety FET must be off for 250 ms. 2. The primary application must command the output to the off-state. 3. The secondary application can then re-enable the output.
BIT 8	Hardware supply power out of range	<ol style="list-style-type: none"> 1. The primary application must command ALL outputs to the off-state. 2. The supply voltage must return to its valid range. 3. The kernel then clears status bit 8.

LEDs

There are two LEDs on every PLUS+1® module, one red and one green. Both are under application software control of the primary processor. Before the primary processor's application software starts running, the green LED will be on and the red LED will be off.

Each LED light pipe will have an alternate yellow color which the application software will not have access to. These alternate yellow colors will be used to indicate low-level software and/or hardware failures. The yellow LED shared with the green LED light pipe will be controlled by the primary processor, and the yellow LED shared with the red LED light pipe will be controlled by the secondary controller. When either yellow LED is enabled the signal will override its shared green or red LED.

Controller Area Network specifications

CAN (Controller Area Network)

There are two channels fully dedicated to CAN communications on the 50 pin hardware. One channel routed to the primary processor only, and the other channel is routed to both the primary and secondary processors.

There is one channel fully dedicated to CAN communications on the 24 pin hardware. This channel is routed to both the primary and secondary processors.

Baud rate	Up to 1 MBps
Termination	No internal termination

CAN system design

All PLUS+1[®] modules have CAN ports that conform to CAN 2.0B specifications, including CAN shield.

Warning

Unintended movement of the machine or mechanism may cause injury to the technician or bystanders. Machine performance may be impaired if CAN communications are disrupted by electrical fields in excess of 30 V/m between 20 and 30 MHz. To prevent potential unintended machine movement and to meet EMC requirements, a shielded CAN bus must be used to achieve 100 V/m immunity.

Specifications for terminating resistor

Each end of the main backbone of the CAN bus must be terminated with an appropriate resistance to provide correct termination of the CAN_H and CAN_L conductors. This termination resistance should be connected between the CAN_H and CAN_L conductors.

Specifications

Description	Units	Minimum	Maximum	Nominal	Comment
Resistance	Ω	110	130	120	Minimum power dissipation 400 mW (assumes a short of 16 Vdc to CAN_H).
Inductance	μH		1		

Notes on CAN Bus installation

Total bus impedance should be 60 Ω.

The CAN transceiver will be damaged by any voltage outside of allowable range, (-7 to +36 Vdc), even with a very short pulse.

If using shielded cable, the shield must be grounded to the machine ground at one point only; preferably at the mid-point of the CAN bus. Each PLUS+1[®] module CAN shield pin must be connected to the cable shield.

Expansion module CAN Bus loading

System designers incorporating PLUS+1[®] expansion modules in their applications should be aware of PLUS+1[®] CAN bus loading and controller memory usage during system design. Each expansion module is associated with a PLUS+1[®] controller and uses part of the controller's memory resources for inter-module communications. The table below can be used to estimate system CAN bus loading and the memory impact of I/O modules on their associated controller.

Controller Area Network specifications

Estimated usage of memory and communication resources

Description	IX012-010	IX024-010	OX012-010	OX024-010	IOX012-010	IOX024-20
Estimated module bus load (using default update and 250K bus speed)	4%	10%	11%	27%	11%	27%
Estimated module bus load (using 70 ms updates and 250K bus speed)	2%	5%	3%	8%	4%	8%
RAM usage on SC024-110/112, SC024-120/122	9%	12%	9%	14%	9%	17%
RAM usage on SC050-120/122	1%	1%	1%	2%	1%	2%
RAM usage on SC050-13H	1%	1%	1%	2%	1%	2%
ROM usage on SC024-110/112, SC024-120/122	8%	11%	12%	18%	10%	20%
ROM usage on SC050-120/122	3%	4%	4%	6%	3%	8%
ROM usage on SC050-13H	2%	2%	2%	3%	2%	4%

Internal processor-to-processor UART

There are two UART channels fully dedicated to diagnostic communication between processors. One channel is dedicated to processor diagnostics, and the other is dedicated to CAN_1 message send and receive diagnostics.

The hardware and low-level software provide a basic framework for communication on each channel, however the specific data structure is not predefined because the data to be transferred is application dependent.

Baud rate	Up to 7.5 MBps
Termination	N/A

The secondary processor:

- Has access to all inputs including sensor power and battery measurements, PWM output currents, as well as one external CAN channel.
- Can control and check all redundant sourcing output stages.
- Has access to a digital signal indicating that the internal power supplies are within acceptable limits.
- Can communicate application specific data through a dedicated serial bus.
- Has the ability to disable sourcing (disconnect high-side switch) of each output individually in the event that any of these signals indicates there is a fault condition as defined by the application.

Product ratings

Power

Battery power must be supplied to designated power-up digital inputs, since the controller's 3 to 12 Vdc regulated power supply is not available when the controller is in lower power mode.

Module supply voltage/maximum current ratings

PLUS+1® modules are designed to operate with a nominal 7 to 36 Vdc power supply. The modules will survive with full functionality if the supply voltage remains below 36 Vdc.

Specifications

Description		Units	Minimum	Maximum	Comment
Allowed voltage at pin		Vdc	0	36	
Allowed module current		A	0		Consult module data sheets for maximum allowable current.
SRon	Minimum voltage rise rate for power turn-on	V/ms	1	—	The voltage applied to the power pins must exceed this value to guarantee the device will power-up.
Ton	Turn-on time	ms	—	250	From applied battery power to application software start.

Caution

PCB damage may occur. To prevent damage to the module all module power supply + pins must be connected to the vehicle power supply to support advertised module maximum output current capacity. DO NOT use module power supply + pins to supply power to other modules on a machine.

Lower power mode

This feature gives OEM designers the ability to implement automotive-like features in their machine control system design. If the lower power mode feature is not implemented, this controller has the same operating characteristics as any other PLUS+1® controller.

When used as a lower power mode controller, supply power to the module is connected directly to the battery. Lower power mode initiation is defined by the controller's application software: PLUS+1® GUIDE programmers define the conditions under which the controller is to be put into lower power mode. When in lower power mode, controller outputs are set to zero, sensor power supply is off and the controller consumes a small amount of current.

Controller lower power mode current consumption

Supply voltage	Lower power mode current consumption
12 Vdc	20 mA
24 Vdc	20 mA

Either of two conditions will wake up the controller:

- The power supplies can be re-energized by cycling battery power.
- Generating a positive/rising edge on one of several inputs:
 - SC024-110/112: C1p5, C1p6, C1p7, C1p10, C1p11, C1p12, C2p1, C2p7, C2p8
 - SC024-120/122: C1p5, C1p6, C1p7
 - SC050-120/122: C1p5, C1p6, C1p7, C1p19, C1p20, C1p23, C1p24, C1p31, C1p32
 - SC050-13H: C1p5, C1p6, C1p7, C1p19, C1p20, C1p23, C1p24, C1p31, C1p32

Product ratings

Specifications

Description		Units	Minimum	Maximum	Comment
Power-up pin threshold		Vdc	2	36	To wake up by cycling input power.
Power-up pin threshold		Vdc	4.5	36	To wake up by digital input.
Power-up time delay		mSec	250	500	
SRon	Minimum voltage rise rate for power turn-on	V/ms	—	—	The voltage applied to the input pins must exceed this value to guarantee the device will power-up.
Toff	Turn-off time	ms	150	400	From software commanded shutdown to micro reset.

Sensor power supply ratings

PLUS+1® modules that support sensor inputs are provided with dedicated, software adjustable, regulated sensor power supply and ground pins. Refer to individual product data sheets for sensor power supply current ratings.

General

Description	Comment
Short circuit to ground	Output is not damaged and fault is detected.
Short circuit to battery +	Output is not damaged and fault is detected.

Specifications

Description	Units	Minimum	Maximum	Comment
Output short circuit voltage	Vdc		36	
Sensor output voltage	Vdc	3	12	
Output current	mA	0	500	The maximum power must be limited to 2.5 Watts for Vout greater than 5 Vdc.
Output Load Capacitance	µF		10	
Hold up time after power loss	ms	5	15	

SC Controllers feature two additional levels of regulated power: 1.6 Vdc and 3.3 Vdc. The PLUS+1® GUIDE application developer can detect open and short digital inputs, when these power supplies are used in conjunction with DIN/AIN inputs.

Specifications

Description	Units	Minimum	Maximum	Comment
Output short circuit voltage	Vdc		36	
Output voltage, sensors	Vdc	3	12	Sensor power supply drops below minimum if controller power supply is less than 7 Vdc.
Output voltage, DIN diagnostics	Vdc	1.58	1.76	Nominal 1.6
Output voltage, DIN diagnostics	Vdc	3.21	3.45	Nominal 3.3

EEPROM Write/Erase ratings

To prevent unexpected memory writes, care must be taken to ensure memory with a high number of read/write cycles is either U32 or S32 data types.

Product ratings

Specifications

Description	Minimum	Maximum	Comment
EEPROM write/erase cycles	1 million		Minimum valid over entire operating temperature range.

EEPROM used in PLUS+1[®] controllers is rated for one million read/write cycles per sector. Sector size is 32 bits. When a value is written to EEPROM, all 32 bits in a particular sector are always written, regardless of the size of the saved value. If the value being saved in a sector is less than 32 bits (such as U8, S16, BOLL) adjacent bits in the same EEPROM sector are rewritten with their previous value. The implication of this memory property is that if two values are being written to the same memory sector, the useful life of the sector is determined by the value being written most frequently. If that value exceeds 1 million read/write cycles, all values in the sector may be compromised if the useful life is exceeded.

Environmental testing criteria

General product ratings

Description	Units	Minimum	Maximum	Comment
Operating temperature	°C [°F]	-40 [-40]	85 [185]	
Storage temperature	°C [°F]	-40 [-40]	85 [185]	
Allowable module supply voltage	Vdc	7	36	
Module sensor supply voltage	Vdc	3	12	Sensor voltage drops below the minimum value if module supply voltage < 7 Vdc. See Sensor power supply ratings on page 19.
Analog input voltage levels	Vdc		36	
Allowable output load current (per pin)	A			See individual module data sheets.
Module allowable total output current	A			See individual module data sheets.
All modules Ingress Protection (IP) rating*				IP 67
All modules CE rating				CE compliant.

* The PLUS+1[®] modules IP 67 rating is only valid when the module mating connector is in place and unused connector pin positions have sealing plugs installed.

SC Controller Family environmental testing criteria

Climate environment

Description	Applicable standard	Comment
Storage temperature	IEC 60068-2-1, test Ab, IEC 60068-2-2 test Bb	
Operating temperature	IEC 60068-2-1, test Ab, IEC 60068-2-2 test Bd	
Thermal cycle	IEC 60068-2-2, test Na, IEC 60068-2-38 (partial)	
Humidity	IEC 60068-2-78, IEC 60068-2-30 test Db	Damp heat steady state and cyclic.
Degree of protection	IEC 60529	

Product ratings

Chemical environment

Description	Applicable standard	Comment
Chemical resistance	ISO 16750-5	

Mechanical environment

Description	Applicable standard	Comment
Vibration	IEC 60068-2-6 test Fc, IEC 6008-2-64 test Fh	
Bump	IEC 60068-2-29 test Eb	
Shock	IEC 60068-2-27 test Ea	
Free fall	IEC 60068-2-32 test Ed	

Electrical/electromagnetic

Description	Applicable standard	Comment
EMC emission	EN ISO 14982, ISO 13766	Electromagnetic compatibility for earth moving machinery.
EMC immunity	EN ISO 14982, ISO 13766	Electromagnetic compatibility for earth moving machinery.
Electrostatic discharge	EN 60-1 000-4-2	
Auto electrical transients	ISO 7637-2, ISO 7637-3	
Short circuit protection	Danfoss test	Inputs and outputs survive continuous short circuit. Normal function resumes when short is removed.
Reversed polarity protection	Danfoss test	Survives reverse polarity at supply voltage for at least five minutes.

Modules housing

PLUS+1® module housings feature a snap together assembly that is tamper-proof. Once assembled at the factory, the housing cannot be opened for service.

Opening the modules housing will void the factory warranty.

Product installation and start-up

General comments

Mating connectors

The SC Controller Family use Deutsch® connectors. Danfoss has assembled a mating connector kit, referred to as a bag assembly, for the 24 and 50 pin module housings. Mating connector bag assembly ordering information is found in the product data sheet for each module.

Deutsch® mating connector part information

Description	24 pin module	50 pin module
Crimp tool	HDT48-00 (solid contacts) (20 to 24 AWG)	HDT48-00 (solid contacts) (20 to 24 AWG)
	DTT20-00 (stamped contacts) (16 to 20 AWG)	DTT20-00 (stamped contacts) (16 to 20 AWG)
Contacts	Solid: 0462-201-2031 (20 to 24 AWG)	Solid: 0462-201-2031 (20 to 24 AWG)
	Stamped: 1062-20-0144 (16 to 20 AWG)	Stamped: 1062-20-0144 (16 to 20 AWG)
Connector plug	Gray A-Key DTM 06-12SA Black B-Key DTM 06-12SB	DRC26-50S01
Wedge	WM-12S	Not required
Strip length	3.96 to 5.54 mm [0.156 to 0.218 in]	3.96 to 5.54 mm [0.156 to 0.218 in]
Rear seal maximum insulation OD	3.05 mm [0.120 in]	2.41 mm [0.095 in]
Sealing plugs	0413-204-2005	0413-204-2005

Danfoss mating connector part information

Description	24 pin module	50 pin module
Mating connector bag assembly (20 to 24 AWG)	10100945	10100946
Mating connector bag assembly (16 to 20 AWG)	10102023	10102024

Danfoss crimp extraction tool part information

Description	Part number
Crimp tool for 20 to 24 AWG	10100745
Crimp tool for 16 to 20 AWG	10102028
Extraction tool Deutsch 114010; 12 AWG	11068808
Extraction tool Deutsch 0144-240-2005; 16 to 20, 20 to 24 AWG	10100744

PLUS+1® module mating connectors may be mated 10 times.

Recommended torque for the Deutsch® mating connector retaining fastener on the 50 pin connector is 2.26 N·m (20 lb·in).

Product installation

Mounting

PLUS+1® modules can be mounted in one of three ways:

- End (bulkhead) installation
- Up to 3 units stacked on one another
- Individually side mounted

In each case, care must be taken to insure that the module connector is positioned so that moisture drains away from the connector. If the module is side or stack mounted, provide a drip loop in the

Product installation and start-up

harness. If the module is mounted vertically, the connector should be on the bottom of the module. Provide strain relief for mating connector wires.

Caution

Module damage may occur. Use caution when installing modules. Due to the size of the mating connector wire bundle, it is possible to twist off the end cap of the module if excessive pressure is applied during the installation of harness strain relief.

Suggested fasteners and recommended installation torque

Mounting method	Recommended OD	Recommended torque
Bulkhead mount; multiple units stacked; single	6.0 mm (0.25 in)	49 N•m (7 ft•lb)

Machine diagnostic connector

It is recommended that a diagnostic connector be installed on machines that are controlled by PLUS+1[®] modules. The connector should be located in the operator's cabin or in the area where machine operations are controlled and should be easily accessible.

Communication (software uploads and downloads and service and diagnostic tool interaction) between PLUS+1[®] modules and personal computers is accomplished over the vehicle CAN network. The diagnostic connector should tee into the vehicle CAN bus and have the following elements:

- CAN +
- CAN -
- CAN shield

Grounding

Proper operation of any electronic control system requires that all control modules including displays, microcontrollers and expansion modules be connected to a common ground. A dedicated ground wire of appropriate size connected to the machine battery is recommended.

Hot plugging

Machine power should be off when connecting PLUS+1[®] modules to mating connectors.

Recommended machine wiring guidelines

1. All wires must be protected from mechanical abuse. Wires should be run in flexible metal or plastic conduits.
2. Use 85° C [185° F] wire with abrasion resistant insulation. 105° C [221° F] wire should be considered near hot surfaces.
3. Use a wire size that is appropriate for the module connector.
4. Separate high current wires such as solenoids, lights, alternators or fuel pumps from sensor and other noise-sensitive input wires.
5. Run wires along the inside of, or close to, metal machine surfaces where possible. This simulates a shield which will minimize the effects of EMI/RFI radiation.
6. Do not run wires near sharp metal corners. Consider running wires through a grommet when rounding a corner.
7. Do not run wires near hot machine members.
8. Provide strain relief for all wires.
9. Avoid running wires near moving or vibrating components.
10. Avoid long, unsupported wire spans.
11. All analog sensors should be powered by the sensor power source from the PLUS+1[®] controller and ground returned to the sensor ground pin on the PLUS+1[®] controller.
12. Sensor lines should be twisted about one turn every 10 cm [4 in].

Product installation and start-up

- 13.** It is better to use wire harness anchors that will allow wires to float with respect to the machine rather than rigid anchors.
- 14.** Electronic modules should be grounded to a dedicated conductor of sufficient size that is connected to the battery (-).

Electronic components welding guidelines

Remove electronic components from the machine before any arc welding. The following is recommended when welding on a machine equipped with electronic components:

- Turn the engine off.
- Disconnect the negative battery cable from the battery.
- Do not use electronic components to ground the welder.
- Clamp the ground cable for the welder to the component that will be welded as close as possible to the weld.

PLUS+1° USB/CAN Gateway

Communication (software uploads and downloads and service and diagnostic tool interaction) between PLUS+1° modules and a personal computer (PC) is accomplished using the vehicle's PLUS+1° CAN network.

The PLUS+1° CG150-2 USB/CAN gateway provides the communication interface between a PC USB port and the vehicle CAN bus. When connected to a PC, the gateway acts as a USB slave. In this configuration, all required electrical power is supplied by the upstream PC host. No other power source is required.

Refer to the *PLUS+1° GUIDE Software User Manual*, literature number **10100824**, for gateway set-up information. Refer to the *CG150-2 USB/CAN Gateway Data Sheet*, literature number **L1412468**, for electrical specifications and connector pin details.

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Local address:

Danfoss Power Solutions (US) Company
2800 East 13th Street
Ames, IA 50010, USA
Phone: +1 515 239 6000

Danfoss Power Solutions GmbH & Co. OHG
Krokamp 35
D-24539 Neumünster, Germany
Phone: +49 4321 871 0

Danfoss Power Solutions ApS
Nordborgvej 81
DK-6430 Nordborg, Denmark
Phone: +45 7488 2222

Danfoss Power Solutions Trading (Shanghai) Co., Ltd.
Building #22, No. 1000 Jin Hai Rd
Jin Qiao, Pudong New District
Shanghai, China 201206
Phone: +86 21 3418 5200

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