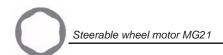
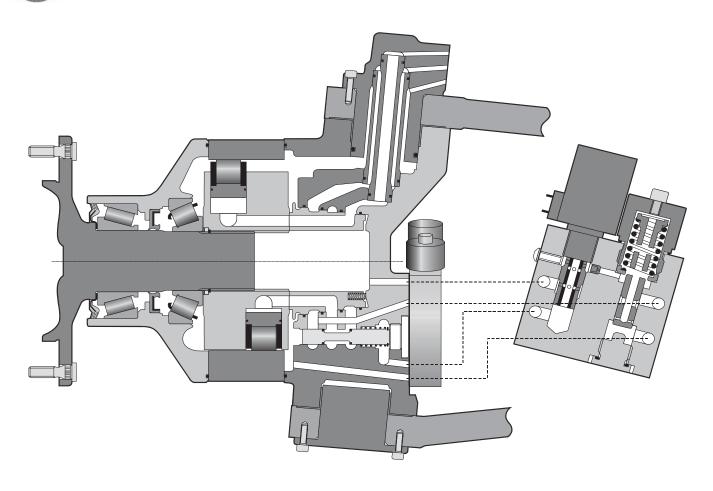
MG21 STEERABLE WHEEL MOTOR



TECHNICAL CATALOG







Motor Inertia 0.1 kg.m²

		0	2		retical que 1 1 at 1000 PSI	0	Max.power 2 preferred	2 non-preferred	Max. speed	Max. pressure
		cm³/tr [cu.in/rev.]	cm³/tr [cu.in/rev.]		[lb.ft]	kW [HP]	kW [HP]	kW [HP]	tr/min <i>[RPM]</i>	bar [PSI]
	8	1 674 [102,1]	837 [51,0]	2 662	[1 354]		80 [107] 53 [71] 40 [54]		138	
/ith bes	9	1 885 [115,0]	943 [57,5]	2 997	[1 524]			122		
Cams with equal lobes	0	2 096 [127,8]	1 048 [63,9]	3 333	[1 695]	80 [107]		40 [54]	110	
Car	1	2 294 [139,9]	1 147 [70,0]	3 647	[1 855]				100	
	2	2 519 [153,6]	1 260 [76,8]	4 005	[2 037]				91	400 [*] [5 800]
Cams with unequal lobes	N	1 885 [115,0]	837 [51,0] 1 048 [63,9]	2 997	[1 524]	80 [107]	53 [71]	40 [54]	115	

First displacement

Second displacement



* Max. pressure available under certain condition of use. Consult your Poclain Hydraulics application engineer to check these conditions.

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Model code

Characteristics

Options

CONTENT

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OPTIONS 13

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Methodology:

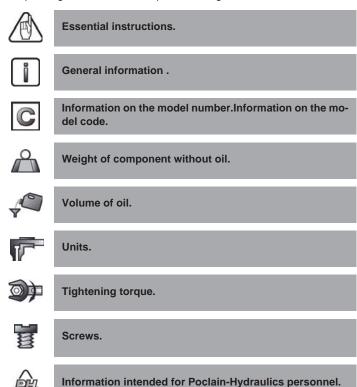
This document is intended for manufacturers of machines that incorporate Poclain Hydraulics products. It describes the technical characteristics of Poclain Hydraulics products and specifies installation conditions that will ensure optimum operation.

This document includes important comments concerning safety. They are indicated in the following way:

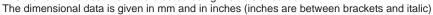


Safety comment.

This document also includes essential operating instructions for the product and general information. These are indicated in the following way:



The views in this document are created using metric standards.

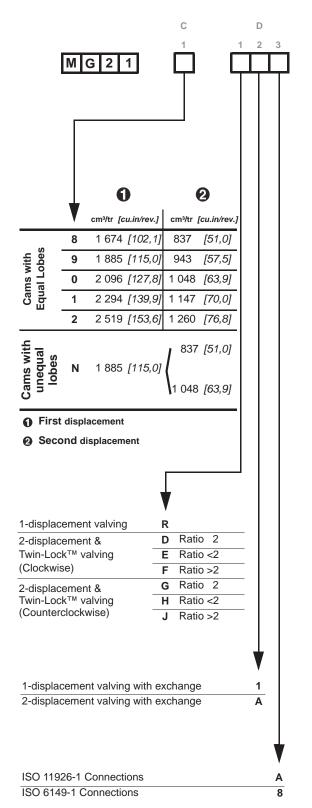


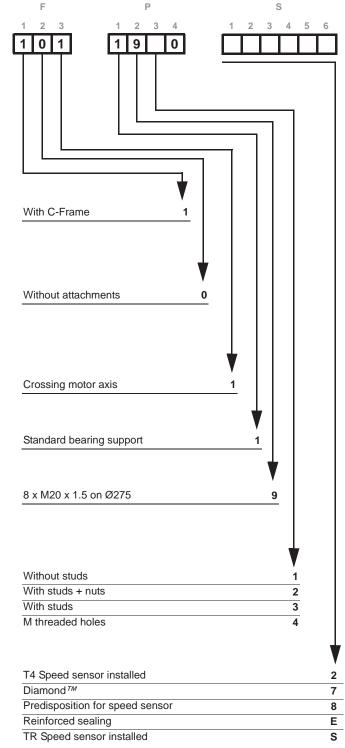


0

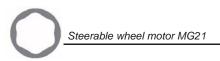
Characteristics

MODEL CODE



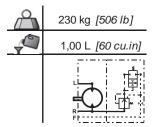


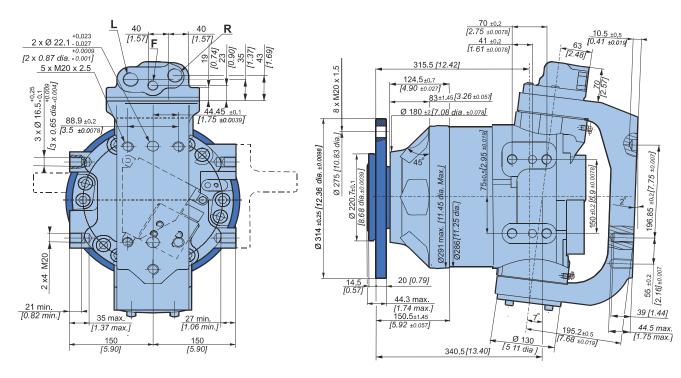
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CHARACTERISTICS

Standard (1910) single displacement motor with built-in exchange





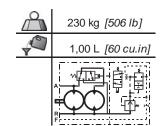
Model code

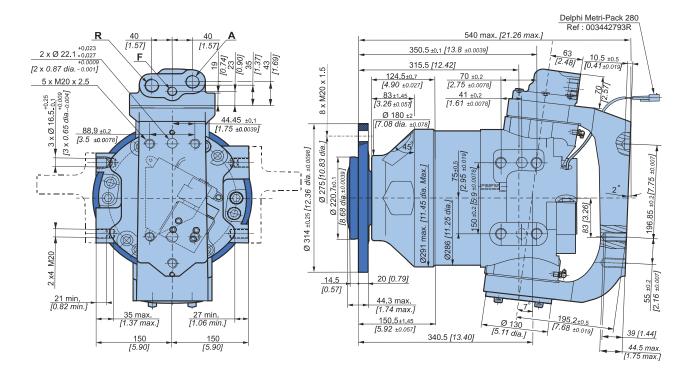
Characteristics

Options



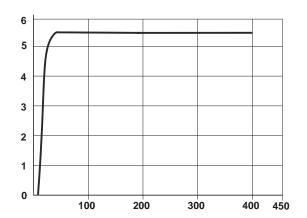
Standard (1910) 2 displacement motor with built-in exchange

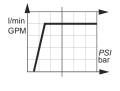


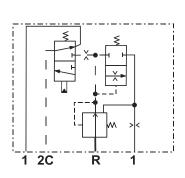


Exchange

When a coding request is made, you must specify information on the threshold of the selector and the valve.









The exchange flow rate indicated on the basis of the supply pressure (P = 50 bar [725 PSI]) is constant (Q = 5.5 l/min [1.45 GPM]).

0

Load curves



The given load curves correspond to the conditions specified below. For load curves corresponding to your specifications, contact a Poclain Hydraulics engineer.

Permissible radial loads

Service life of bearings

Test conditions:

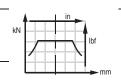
Test conditions:

Static:

- 150 bar [2 175 PSI],code 9 displacement
- Max. axial stress = 15% of Fr
- Load radius = 719 mm [28.31 in]

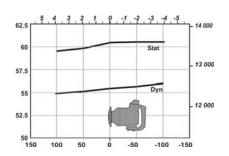
Dynamic:

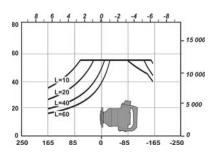
- 450 bar [6 527 PSI],code 9 displacement
- Max. axial stress = 15% of Fr
- Load radius = 719 mm [28.31 in]



L: Millions B10 revolutions at 150 bars (average pressure), with 25 cSt fluid, code 9 displacement, without axial load.

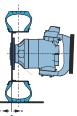








The service life of the components is influenced by the pressure. You must check that the combination of forces applied (Axial load / Radial load) is compatible with the permissible loads for the components, and that the resulting service lives of these components complies with the application's specifications. For an accurate calculation, consult your Poclain Hydraulics application engineer. \mathcal{T}

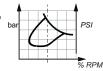


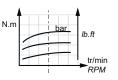
Efficiency

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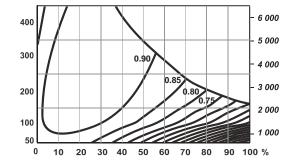
Overall efficiency

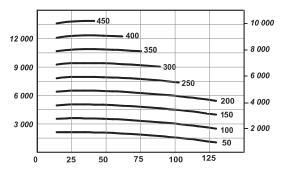
Average values given for guidance for code 0 displacement after 100 hours of operation with HV46 hydraulic fluid at 50°C [122°F].





Actual output torque







For a precise calculation, consult your Poclain Hydraulics application engineer.

9

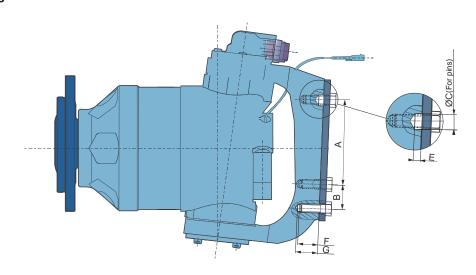


Wheel rim mountings

		Classe	9	(*)		
			N.m	[lb.ft]		
	8xM20x1.5	12,9	690	[509]		

(*) The tightening torques are given for the indicated loads.

Chassis mounting





Take care over the immediate environment of the connections.

A (1)	B (1)	2xØC (2)	E(3)	F m ax.	G (4)
mm <i>[in]</i>	mm <i>[in]</i>	mm [in]	mm [in]	mm [in]	mm <i>[in]</i>
196,85 [7,75]	55 [2,17]	22,1 [0,87]	10,5 [0,41]	39 [1,54]	

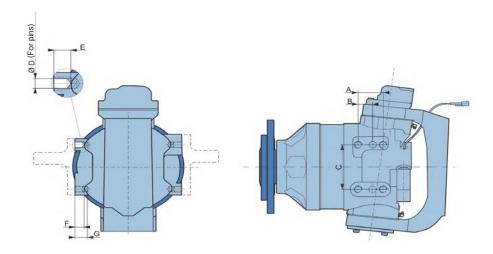
	Classe	N.m [lb.ft]
5xM20x2.5	12.9	690 [509]

- (1) + 0.2 [+0.0078] - 0.2 [- 0.0078]
- (2) +0.023 [+0.0009] -0.0027 [- 0.0010]
- (3) + 0.5 [+0.019] - 0.5 [- 0.019]
- (*) The tightening torques are given for the indicated loads.



Pins are used to take tangential stress.

Steering attachment



	A (1)	B (1)	C (1)	3x ØD (2)	E	F	G
	mm <i>[in]</i>	mm <i>[in]</i>	mm <i>[in]</i>	mm [in]	mm [in]	mm <i>[in]</i>	mm <i>[in]</i>
,	70 [2,76]	41 [1,61]	150 <i>[5,91]</i>	16,5 <i>[0,65]</i>	27 [1,06]	21 [0,83]	35 [1,38]

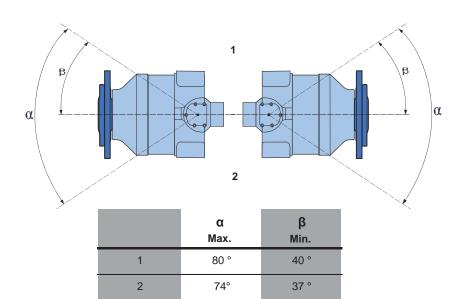
	Classe	(*)		
		N.m	[lb.ft]	
8x M20x2.5	12,9	690	[509]	

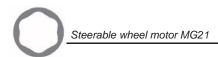
- (1) + 0.2 [+0.0078] - 0.2 [- 0.0078]
- (2) + 0.25 [+0098] - 0.1 [- 0.0039]
- (*) The tightening torques are given for the indicated loads.



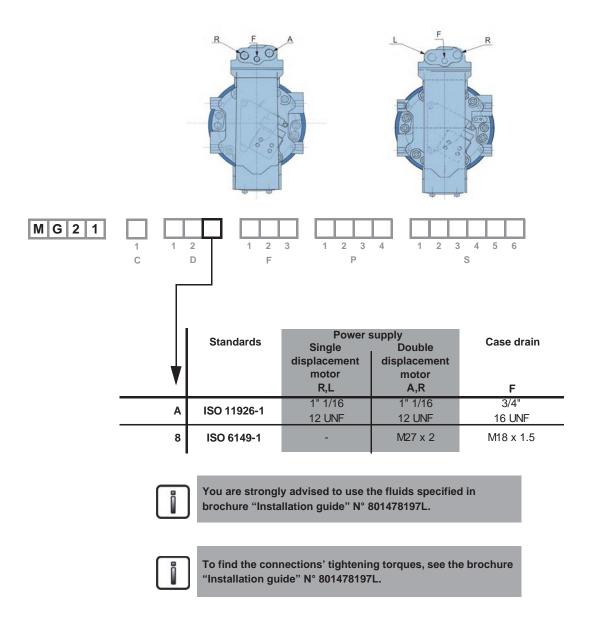
Pins are used to take tangential stress.

Steering angle





Hydraulic connections



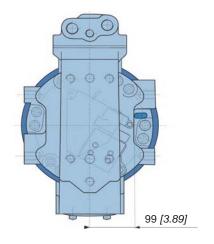


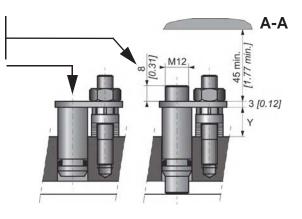


You can accumulate more than one optional part. Consult your Poclain Hydraulics sales engineer.

2 - S - Q - 8 - Installed speed sensor or predisposition

Designation	
T4 Speed sensor (without rotation direction)	2
TR Speed sensor (digital rotation direction)	S
TD speed sensor (two phase shifted frequencies)	Q
Predisposition for speed sensor	8





Max. length Y= 13.5 Standard number of pulses per revolution= 56



Look at the "Mobile Electronic" N° A01889D technical catalogue for the sensor specifications and its connection.



To install the sensor, see the "Installation guide" brochure No. 801478197L.

7 - Diamond™

Special treatment of the motor core which considerably increases its strength, making the motor much more tolerant to temporary instances of the operating conditions being exceeded.

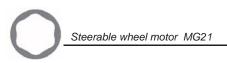
E - Reinforced sealing

Requires reinforcement of shaft bearings.

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Characteristics

Model code



Steerable wheel motor MG21



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