PM30

VARIABLE DISPLACEMENT PUMP
CLOSED LOOP CIRCUIT

TECHNICAL CATALOG

POCLAIN Hydraulics

OVERVIEW

PM30 is a variable displacement, axial piston pump, with swashplate system, for closed loop hydrostatic transmissions.

It provides a continuously variable flow rate between zero and maximum in forward and reverse direction. Flow rate is proportional to rotation speed and swashplate angle.

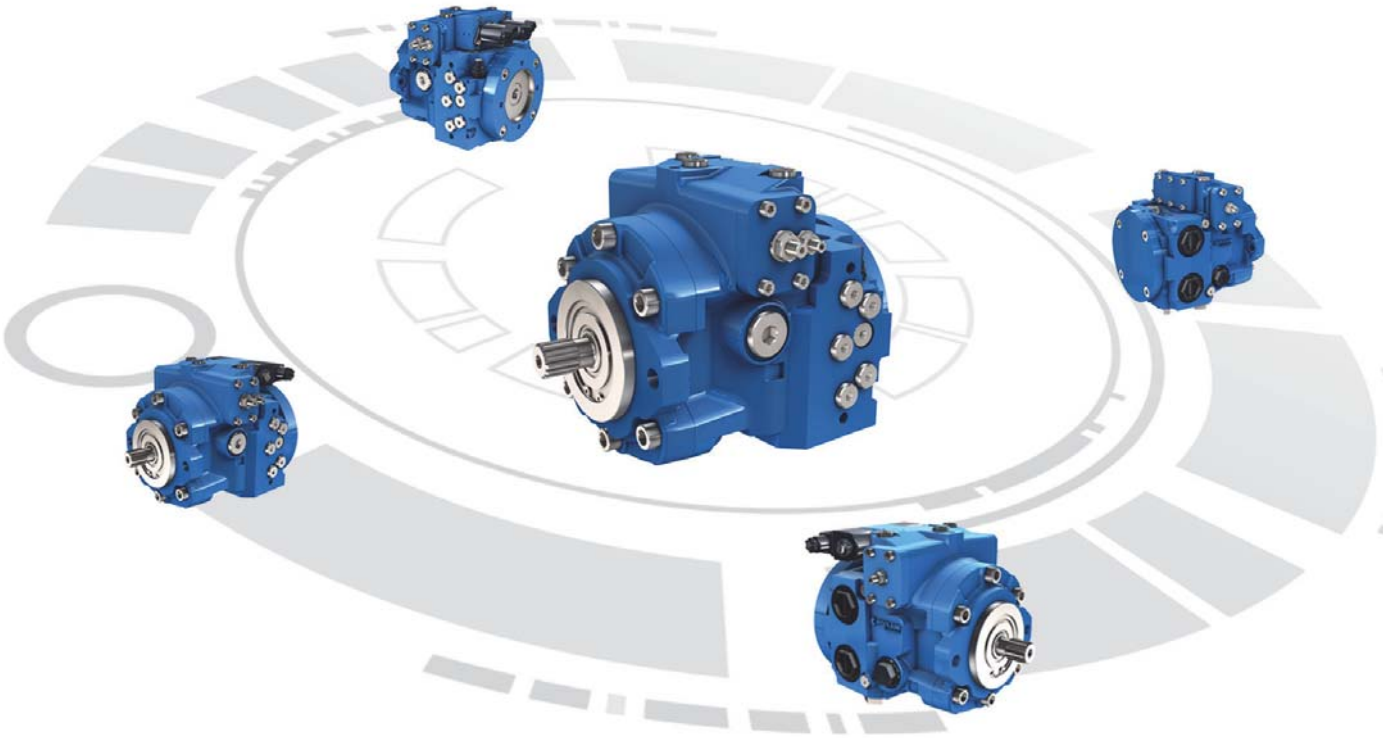
It can feature a charge pump to keep the circuit pressurised. This avoids risk of cavitations and ensures a good performance of the transmission.

It offers several types of control: Hydraulic, electrical and electro-proportional. Hydraulic and electro-proportional ones can be equipped with feed-back device.

It is equipped with high pressure relief valves and can be delivered with auxiliary gear pumps.

It is available in single or tandem versions.

As options, PM30 can be featured with flushing valve and filter on charge pressure line.



		PM30-25	PM30-28	PM30-30	PM30-35
Displacement	cm³/rev *[in³/rev.]*	25 *[1.53]*	28 *[1.71]*	30 *[1.83]*	34,2 *[2.09]*
Theoretical Flow at rated speed	L/min *[GPM]*	90 *[23.78]*	100,8 *[26.63]*	108 *[28.53]*	123,12 *[32.52]*
Max. Theoretical absorbed power at 320 bar *[4 641 PSI]*	kW *[hp]*	48 *[64]*	53,76 *[72]*	57,6 *[77]*	65,664 *[88]*
Theorical absorbed torque at 100 bar *[1 450 PSI]*	N.m *[in.lbf]*	39,8 *[352]*	44,6 *[395]*	47,8 *[423]*	54,5 *[482]*
Moment of inertia	kg.m² *[slug.ft²]*	0.0028 *[0.0018]*			
Mounting flange		SAE B, SAE BB			
Controls		Servo hydraulic, electrical, electro-proportional, servo mechanical, automotive			
Mass	kg *[lb]*	29 *[63.8899]*			
Rotation		Clockwise or Counterclockwise			

CONTENT

MODEL

P	M	3	0	1	2	3	4	5	6

1

Displacement cm³/rev *[in³/rev]*	
25 *[1.53]*	**25**
28 *[1.71]*	**28**
30 *[1.83]*	**30**
35 *[2.14]*	**35**

2

Mounting flange and shaft	
SAE B; splined shaft z =13, 16/32'' D.P.	**S3**
SAE BB; splined shaft z =15, 16/32'' D.P.	**S4** (Standard)

3

Control	
Mechanical servo control with feedback	**A**
Direct hydraulic servo control	**S**
Hydraulic servo control with feedback	**T**
Hydraulic automotive control 12V	**D12**
Hydraulic automotive control 24V	**D24**
Electrical on-off servo control with return spring without electrovalve	**B00**
Electrical on-off servo control with return spring and electrovalve 12V	**B12**
Electrical on-off servo control with return spring and electrovalve 24V	**B24**
Electro-proportional servo control 12V	**P12**
Electro-proportional servo control 24V	**P24**
Electrical on-off servo control without electrovalve	**C00**
Electrical on-off servo control with electrovalve 12V	**C12**
Electrical on-off servo control with electrovalve 24V	**C24**
Electro proportional servo control 12V with feedback	**Q12**
Electro proportional servo control 24V with feedback	**Q24**

4

Restrictor mm *[in]*	
Without restrictor	**00**
Ø 0,6 *[dia. 0.023]*	**06**
Ø 0,7 *[dia. 0.027]*	**07**
Ø 0,8 *[dia. 0.031]*	**08**
Ø 0,9 *[dia. 0.035]*	**09**
Ø 1,0 *[dia. 0.039]*	**10**
Ø 1,2 *[dia. 0.047]*	**12**

5

High pressure relief valve setting Max. system pressure (bar *[PSI]*)	
Without valve (only check valve)	**00**
150 *[2 175]*	**15**
200 *[2 900]*	**20**
250 *[3 625]*	**25**
300 *[4 351]*	**30**
350 *[5 076]*	**35**
370 *[5 366]*	**37**
400 *[5 801]*	**40**

6

Rotation	
Clockwise	**R**
Counter clockwise	**L**

CODE

7 8 9 10 11

7

Charge relief valve setting bar *[PSI]*	
Without charge relief valve	**00**
20 *[290]*	**20**
25 *[363]*	**25**
30 *[435]*	**30**

8

Charge pump displacement cm^3/rev *[in^3/rev]*	
Without charge pump	**00**
8 *[0.49]*	**08**
11 *[0.67]*	**11**
15,8 *[0.96]*	**16**

9

Auxiliary mounting pad	
Without auxiliary mounting pad	**S**
SAE A flange; z = 9	**A**
SAE A flange; z = 11	**E**
SAE B flange; z = 13	**B**
SAE BB flange; z = 15	**C**
Tandem (without charge pump)	**T**

10

Gear pump cm^3/rev *[cu.in/rev]*		
Without gear pump		**00**
SAE A flange (if digit 9 = A)	4,0 *[0.24]*	**04**
	6,0 *[0.37]*	**06**
	8,5 *[0.52]*	**08**
	11,0 *[0.67]*	**11**
	14 *[0.85]*	**14**
	16,5 *[1.00]*	**17**
	19,5 *[1.19]*	**20**
	22,5 *[1.37]*	**22**
	26 *[1.59]*	**26**

Different gear pump (group 3, SAE B pad) can be provided. Contact your Poclain Hydraulics application engineer for available displacements.

11

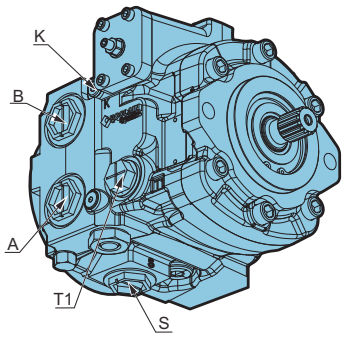
Options	
Without option	**00**
Roller bearing	**CR**
Customized indentification plate	**DP**
Mechanical inching	**IC**
External inching	**HI**
Filter on pressure line without clogging indicator	**F0**
Filter on pressure line with clogging indicator	**F2**
External connections for filter	**F3**
SAE flange ports	**FS**
UNF threads ports	**FU**
Finishing coat	**PA**
Flushing valve	**VS**
Neutral position switch	**MI**
Safety valve	**VPU**
Fluorinated elastomer seals	**EV**
Anti-stall valve	**SD**
Speed sensor	**SS**
Brake inching	**B1**
Brake inching	**B2**

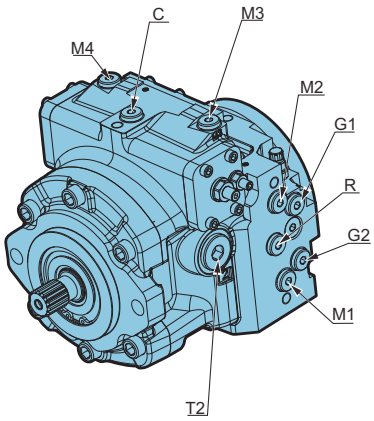
In case of request for a combination of several options, please contact your Poclain Hydraulics application engineer for further information.

The pressure filter options F0, F2, F3 aren´t available with Hydraulic automotive control (D12, D24) or Anti-stall valve (SD).

TECHNICAL

Port characteristics





Port	Function	ISO 1179-1 (standard)
A/B	Services	1'' GAS
C	Case pressure	1/4'' GAS
G1/G2	Auxiliary/Charge pressure	1/4'' GAS
M1/M2	A/B pressure	1/4'' GAS
M3/M4	Servo control	1/4'' GAS
K	External servo pilot	1/8'' GAS
R	Servo pilot pressure	1/4'' GAS
S	Suction	1'' GAS
T1/T2	Drain	3/4'' GAS

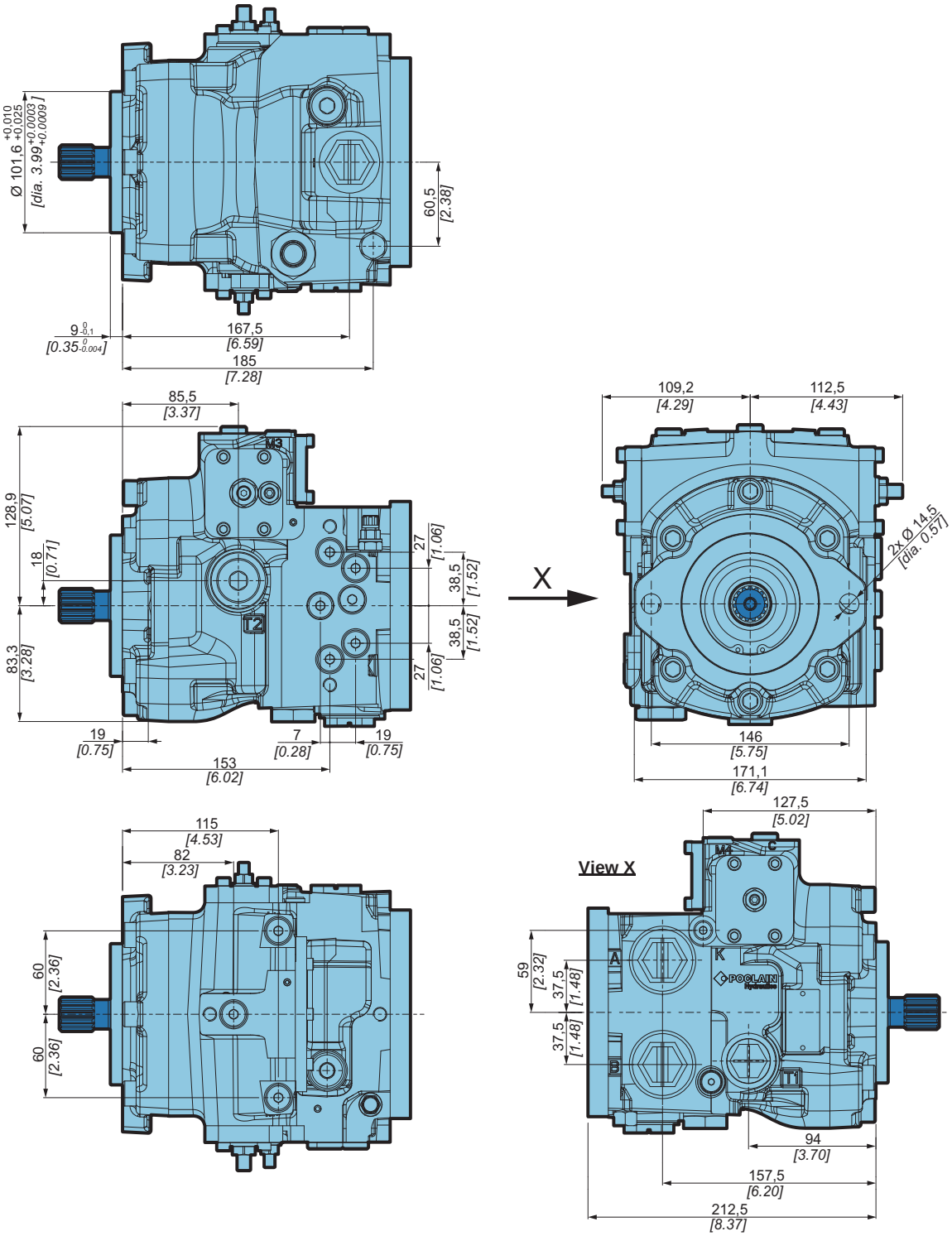
See options FS and FU on page 43 for SAE and UNF port sizes.

SPECIFICATIONS

Main dimensions

PM30 - SAE BB - splined shaft with hydraulic servo control with internal charge pump and without auxiliary mounting pad

1	2	3	4	5	6	7	8	9	10	11
P M 3 0	S4	S						S		



OPERATING PARAMETERS

Operating parameters

			PM30-25	PM30-28	PM30-30	PM30-35
Speed ratings	Minimum	min^{-1}(rpm)		700		
	Max. without load			3 600		
	Max. with load			3 400		
System pressure	Rated	bar *[PSI]*		300 *[4 351]*		
	Maximum			400 *[5 801]*		
	Minimum low loop			15 *[218]*		
Inlet pressure	Mini continuous	bar (abs.) *[PSI abs.]*		0,8 *[11.6]*		
	Mini (cold start)			0,5 *[7.2]*		
Case pressure	Continuous	bar *[PSI]*		2 *[29]*		
	Maximum (cold start)			3,5 *[50.7]*		
Charge pressure	Standard version	bar *[PSI]*		25 *[362.6]*		
	Max. charge pressure			30 *[435]*		
Servo case pressure	Maximum	bar *[PSI]*		30 *[435]*		

Charge pressure

A charge flow is required to maintain a positive pressure in the low pressure loop of a closed loop hydrostatic transmission. Charge pressure ensures proper lubrication and rotating group operation. It is recommended to maintain the charge pressure at a minimum of 15 bar *[218 PSI]* above case pressure. For more details, refer to charge pump paragraph, page 18.

Case pressure

Case pressure must be maintained within the limits shown in the table "Operating parameters". Ensure housing is always filled with hydraulic fluid and especially during start-up of the machine.

Pressure ratings

Maximum peak pressure
It is the maximum allowable pressure. It is equivalent to the maximum setting of the maximum high pressure relief valve. A self-propelled machine can reach the maximum peak pressure value no more than 1-2% of that work cycle.

Work cycle
A fundamental factor for ensuring correct hydrostatic transmission sizing is the machine work cycle (pressure-time ratio, seasonality, pressure vs. percentage of time at max. displacement, machine type). Part service life depends on the correct choice in relation to the work cycle.

Overloads
It is mandatory to protect parts against any possible overloads.

Speed ratings

The table "Operating parameters" gives minimum and maximum rated speeds. Note that all displacements might operate under different speed limits. Definitions of these speed limits appear below.

Maximum speed is the highest operating speed allowed. Over speeding reduces pump life time, can lead to loss of hydrostatic power and braking capacity. Never exceed the maximum speed limit under any operating conditions.

Nominal speed is the speed offering the maximal efficiency.

Inlet pressure

Charge pump inlet pressure is key for acceptable pump life and performances. A continuous inlet pressure of not less than 0,8 bar abs. *[11.6 PSI abs.]* is recommended. A continuous inlet pressure less than 0.5 bar abs. *[7.2 PSI abs.]* indicates inadequate inlet design or a restricted filter. Pressures less than 0.5 bar abs. *[7.2 PSI abs.]* can happen at cold start, but should increase with oil temperature.

Theoretical output

Theoretical output flow is a function of pump displacement and speed. It is relevant to size the rest of the circuit. Theoretical flow does not take into account losses due to leakage or variations in displacement.

Poclain Hydraulics recommendations for fluid

Poclain hydraulics recommends the use of hydraulic fluids defined by the ISO 15380 and ISO 6743-4 standards.
For temperate climates, the following types are recommended.
- HM 46 or HM 68 for fixed installations.
- HV 46 or HV 68 for mobile installations.
- HEES 46 for mobile installations.

These specifications correspond to category 91H of the CETOP standard, parts 1, 2 and 3 of the DIN 51524 standard, and grades VG32, VG 46 and VG68 of the ISO 6743-4 standards.

It is also possible to use ATF, HD, HFB, HFC or HFD type hydraulic fluid upon Poclain Hydraulics specific approval of the components' operating conditions.

Standardized designations for the fluids
- **HM :** Mineral fluids having specific antioxidant, anticorrosion and antiwear properties (HLP equivalent to DIN 51524 parts 1 and 2).
- **HV :** HM mineral fluids providing improved temperature and viscosity properties (DIN 51524 part 3).
- **HEES :** Biodegradable fluids based on organic esters.

It is also possible to use a fluid that meets the biodegradability criteria and is compatible in the event of accidental food contact. The BIOHYDRAN FG 46 fluid designed by the company Total has undergone testing of its properties and performance on our test benches. Since this type of fluid has not yet been categorized, it is the responsibility of machine manufacturers to validate its compatibility with all of the components used in order to guarantee that the intended functions will be fulfilled and this for the desired life time of all equipment items.

For biodegradable fluids, consult your Poclain Hydraulics' application engineer

During operation, the temperature of the oil must be between 0°C *[32°F]* and 80°C *[176°F]*; the minimum and maximum temperatures may be exceeded momentarily by ± 20°C *[± 68°F]* for a duration of less than 30 minutes. For all applications outside these limits, please consult with your Poclain Hydraulics' application engineer.

Pump storage

If the pump stays on stock for more than 6 months, a status verification must be performed before you install it on a machine. Pay attention to sealing condition, rust presence and free rotation of shaft.

Fluid and filtration

The contaminating particles suspended in the hydraulic fluid cause the hydraulic mechanisms moving part wear. On hydraulic pumps, these parts operate with very small dimensional tolerances. In order to reach the part life, it is recommended to use a filter that maintains the hydraulic fluid contamination class at a max. of:

9 according to NAS 1638
20/18/13 according to ISO 4406:1999

According to the type of application decided for the pump, it is necessary to use filtration elements with a filtration ratio of:

β 20 to 30 ≥ 100

Making sure that this ratio does not worsen together with the increasing of the filter cartridge differential pressure.

If these values cannot be observed, the component life will consequently be reduced and it is recommended to contact the Poclain Hydraulics Customer Service.

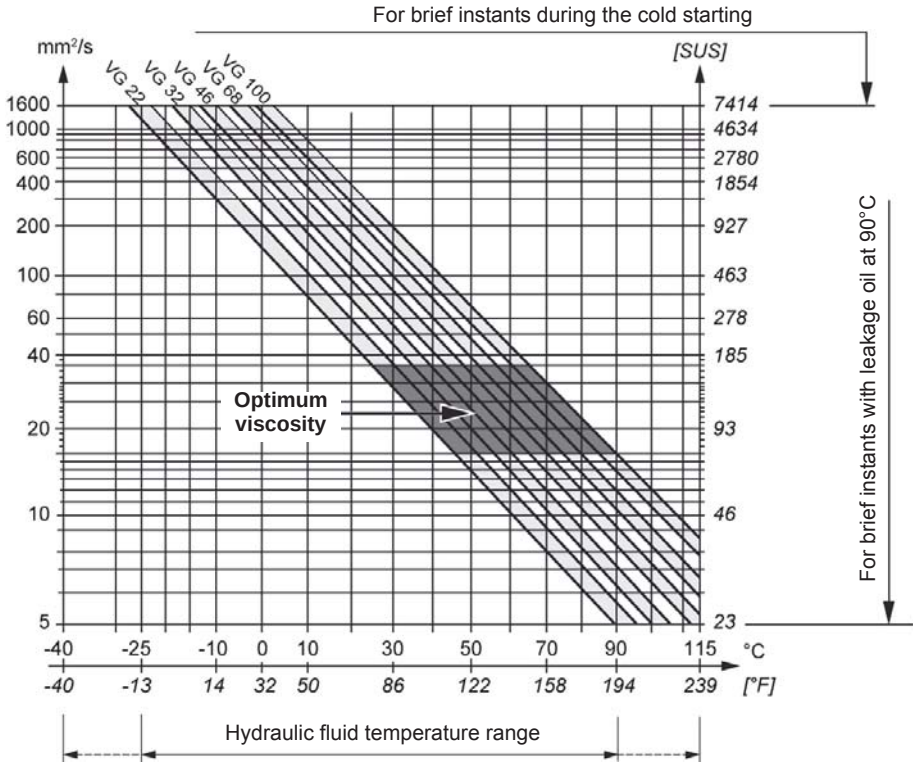
Filters on charge circuit
Filters on the charge circuit (F0-F2) are designed without by-pass. The max. pressure drop on the filtration part must not exceed 2 bar *[29 PSI]* (3 bar *[43.5 PSI]* in case of cold starting) at pump full rating. To monitor the pressure drop, It is recommended to use the clogging indicator on the filtration element (F2 option). Contact your Poclain Hydraulics Application engineer, each time the pump is not charged by its internal charge pump.
Filters on charge circuit are mounted on the pump special support.

Filters assembling
The suction filter is mounted on the suction line. Check that the pressure before the charge pump is 0.8 bar abs. *[11.6 PSI abs.]*, measured on the pump suction port (0.5 bar *[7.2 PSI]* for cold starting).

Viscosity range

For both max. efficiency and life of the unit, the operative viscosity should be chosen within the optimum range of:
√opt = optimum operating viscosity from 16 to 36 mm^2/s *[from 74.1 to 166.8 SUS]* referred to the closed loop temperature.

Working conditions: the following limits of viscosity apply
√min = 5 mm^2/s *[23 SUS]* short-duration at a max. permissible leakage oil temperature of 90° C *[194°F]*
√max = 1000 mm^2/s *[4 634 SUS]* short-duration, on cold start.



Ensure fluid temperature and viscosity limits are concurrently satisfied.

SYSTEM DESIGN PARAMETERS

Consult your Poclain Hydraulics application engineer to validate your design parameters before using the pump in your application.

Sizing equations

The following equations are helpful when sizing hydraulic pumps. Generally, the sizing process is initiated by an evaluation of the machine system to determine the required motor speed and torque to perform the necessary work function. First, the motor is sized to transmit the maximum required torque. The pump is then selected as a flow source to achieve the maximum motor speed.

SI units	**Output flow Q**	=	$\frac{V_g.n.\eta_v}{1000}$			(l/min)
	Input torque M	=	$\frac{V_g.\Delta_p}{20.\pi.\eta_m}$			(N.m)
	Input power P	=	$\frac{M.\ n.\pi}{30\ 000}$	=	$\frac{Q.\Delta_p}{600.\eta_t}$	(kW)
US units	**Output flow Q**	=	$\frac{V_g.n.\eta_v}{231}$			*[GPM]*
	Input torque M	=	$\frac{V_g.\Delta_p}{2.\pi.\eta_m}$			*[lbf.in]*
	Input power P	=	$\frac{M.n.\pi}{198\ 000}$	=	$\frac{Q.\Delta_p}{1714.\eta_t}$	*[hp]*

V_g=Displacement per revolution cm^3/tr *[in^3/rev]*
$\Delta p = p_o - p_i$ (system pressure) bar *[PSI]*
n = Speed min^{-1} *[rpm]*
η_v = Volumetric efficiency
η_m = Mechanical efficiency
η_t = Overall efficiency ($\eta v.\eta m$)

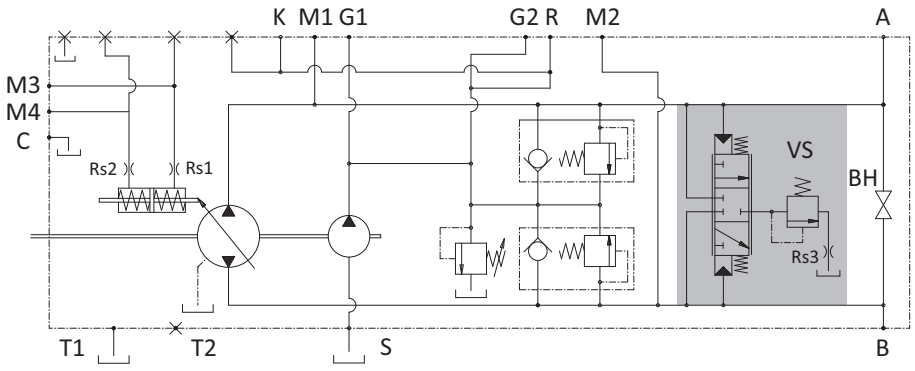
Redundant braking system requirement

Unintended vehicle or machine movement hazard.
The loss of hydrostatic drive line power, in any mode of operation (forward, neutral, or reverse) may cause the system to lose hydrostatic braking capacity. You must provide a braking system, redundant to the hydrostatic transmission, sufficient to stop and hold the vehicle or machine in the event of hydrostatic drive power loss.

Loop flushing

Closed circuit may require a flushing valve to meet temperature and cleanliness requirements. A flushing valve takes a part of hot fluid flow from the low pressure loop of the system loop for cooling and filtering.
Make sure that the charge pump provides adequate flow for the flushing valve flushing and the flushing valve does not cause charge pressure drop below recommended limits.

See option VS page 44 for more information.



Reservoir

The reservoir provides clean fluid, dissipates heat, and removes entrained air from the hydraulic fluid. It allows for fluid volume changes associated with fluid expansion and cylinder differential volumes.
Minimum reservoir capacity depends on the volume needed to perform these functions. Typically, a capacity of one half the charge pump flow (per minute) is satisfactory for a closed reservoir. Open circuit systems sharing a common reservoir require greater fluid capacity.

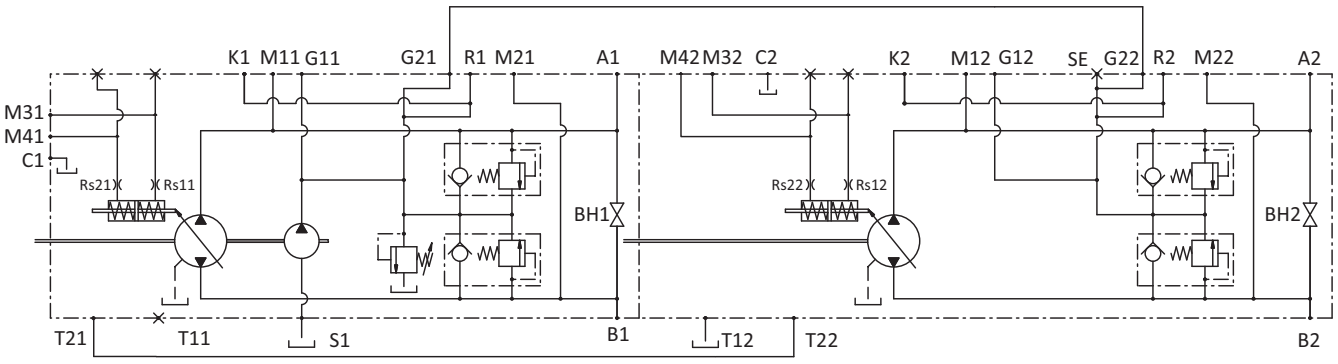
Locate the reservoir outlet (suction line) near the bottom, allowing clearance for settling foreign particles. Use a 100 - 125 µm screen covering the outlet port.

Place the reservoir inlet (return lines) below the lowest expected fluid level, as far away from the outlet as possible.
Use a baffle (or baffles) between the reservoir inlet and outlet ports to promote de-aeration and reduce fluid surging.

Case drain usage for tandem pump

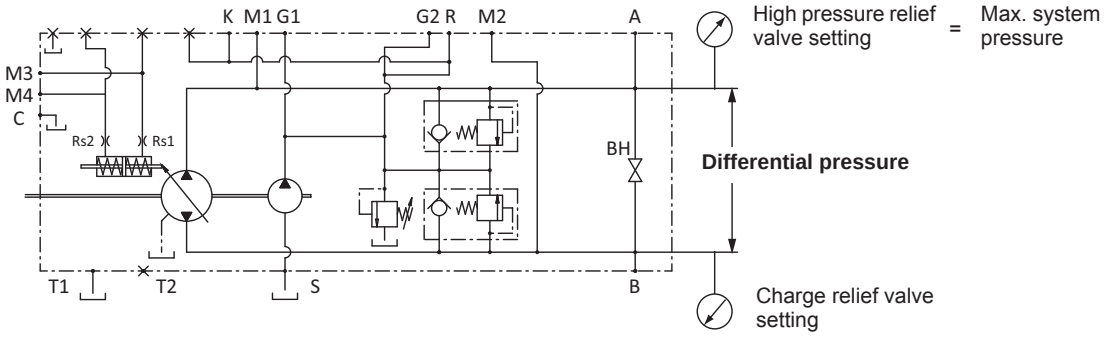
To ensure lubrification of both pumps (with only one charge pump), excess flow from the second pump charge relief valve must be routed into the housing of the first pump.

Tandem pumps with the option of opposing port endcaps do not follow the above rule.



Differential pressure

The differential pressure is the High pressure relief valve setting minus Charge relief valve setting.



Bearing life and external shaft loading

Bearing life:
Bearing life is a function of speed, pressure , swashplate angle and external loads. Oil type and viscosity impact bearing life..

Ball bearing life (B_{10} hours)	Roller bearing life (B_{10} hours)
32 400	61 000
23 000	44 000
18 700	35 000
11 800	22 000

Shaft Loads
Normal bearing life in B_{10} hours is shown in the above table. Figures have been calculated under the following operating conditions : A continuous differential pressure of 150 bar *[2 176PSI]*, 1 800 rpm shaft speed, maximum displacement, without any external shaft side load. The data is based on a 50% forward, 50% reverse duty cycle, standard charge pump size, and standard charge pressure.

PM50 pumps are designed with bearings that can accept external radial and thrust loads. The external radial shaft load limits depend on the load position, orientation, and operating conditions of the unit.

The maximum permissible radial load (Re), is based on the **maximum external moment (Me)**, and the **distance (L)** from the mounting flange to the load. It may be determined using the table and formula below. Thrust (axial) load limits are also shown.

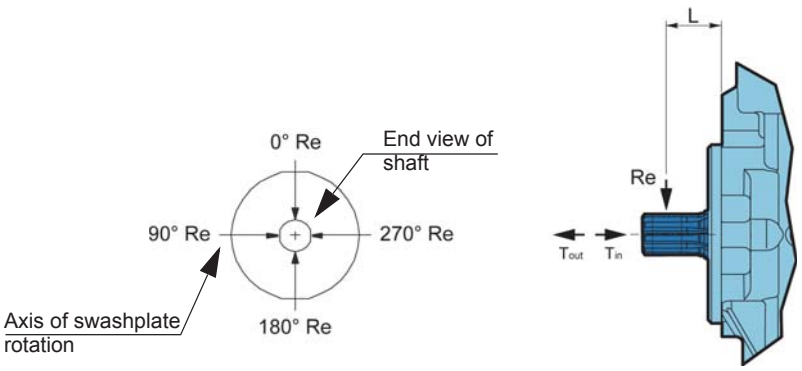
Re = Me / L

All external shaft loads affect bearing life. In applications with external shaft loads, minimize the impact by positioning the load at 90° or 270° as shown in the figure.

Contact your Poclain Hydraulics representative for an evaluation of unit bearing life if:
• Continuously applied external loads exceed 25 % of the maximum allowable radial load Re.
• The pump swashplate is positioned on one side of center all or most of the time.
• The unit bearing life (B_{10}) is critical.

	External moment (Me) N.m *[in.lbf]* (Based on shaft deflection)	**Maximum shaft thrust** N *[lbf]* (at ΔP 180 bar *[2 611 PSI]* and 3 400 rpm)
PM30-25	150 *[1 328]*	1 500 *[337]*
PM30-28	107 *[947]*	1 500 *[337]*
PM30-30	76 *[673]*	1 500 *[337]*
PM30-35	-	1 500 *[337]*

Radial and thrust load position



For an accurate calculation, consult your Poclain Hydraulics application engineer.

Hydraulic unit life

Hydraulic unit life is the life expectancy of the hydraulic components. It depends on speed and system pressure even if , system pressure is the dominant operating variable. High pressure, generated by high load, reduces hydraulic unit life.

Design the hydraulic system according to the expected machine duty cycle. Take in consideration the expected percentages of time at various loads and speeds. Ask your Poclain Hydraulics representative to calculate an appropriate pressure based your hydraulic system design. If duty cycle data is not available, input power and pump displacement are used to calculate system pressure.

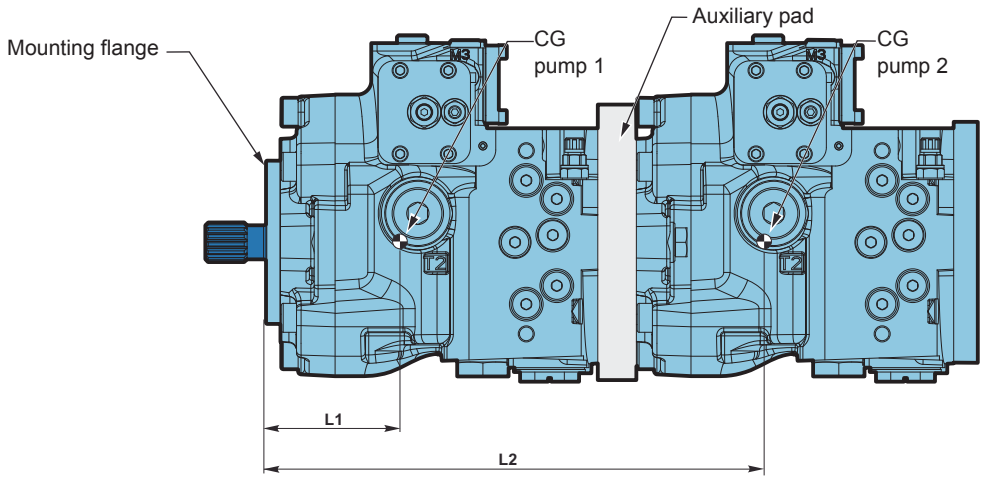
All pressure limits are differential pressures (referenced to charge pressure) , taking a normal charge pressure in consideration.

PM30 pumps will meet satisfactory life expectancy if applied within the parameters specified in this technical documentation. For more detailed information on hydraulic unit life see Operating Parameters in page 9.

Mounting flange loads

Adding tandem mounted pumps, and/or tandem auxillary pump(s), subjecting pumps to shock loads may generate excessive loads on the front mounting flange. The overhung load moment for multiple pump mounting can be estimated as shown in the figure bellow

Overhung load example



For two PM30 in tandem the approximate distances (exact values depend on pumps configuration) of gravity centers from front mounting flange are:

L1 = 109 mm *[4.29 inch]*
L2 = 331 mm *[13.03 inch]*

Estimating overhung load moments

W = Weight of pump (kg)
L = Distance from mounting flange to pump center of gravity (CG)

$M_R = G_R (W_1L_1 + W_2L_2 + ... + W_nL_n)$
$M_S = G_S (W_1L_1 + W_2L_2 + ... + W_nL_n)$

Where:

M_R = Rated load moment (N.m)
M_S = Shock load moment (N.m)
G_R*= Rated (vibratory) acceleration (G's) (m/sec²)
G_S*= Maximum shock acceleration (G's) (m/sec²)

*Calculations will be carried out by multiplying the gravity (g = 9.81 m/sec²) with a given factor. This factor depends on the application.

Allowable overhung load moment are shown in the above table**.** Exceeding these values requires additional pump support.

	Rated moment (MR) N.m *[in.lbf]*	**Shock load moment (MS)** N.m *[in.lbf]*
PM30-25	900 *[7 966]*	2 000 *[17 701]*
PM30-28	900 *[7 966]*	2 000 *[17 701]*
PM30-30	900 *[7 966]*	2 000 *[17 701]*
PM30-35	900 *[7 966]*	2 000 *[17 701]*

For an accurate values and calculations, consult your Poclain Hydraulics application engineer.

FEATURES

High pressure relief valve

The High pressure relief valves maintain circuit pressure in the proper range. The check valves allow charge flow to replenish the low pressure loop of the circuit. The high pressure relief valves ensure a high pressure protection of the high pressure loop of the circuit.

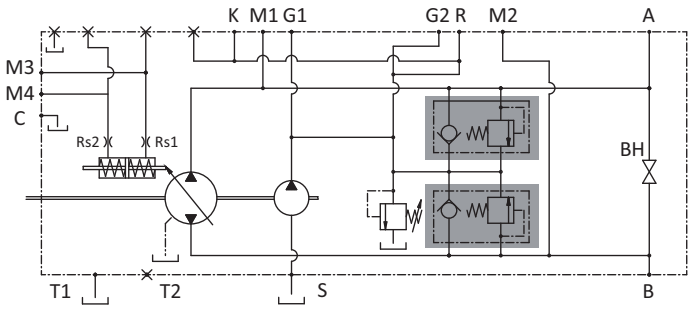
High pressure relief valves are available in a large range of settings. They are not adjustable.

When high pressure relief valves are not desired, pumps may be equipped with charge circuit check valves only.

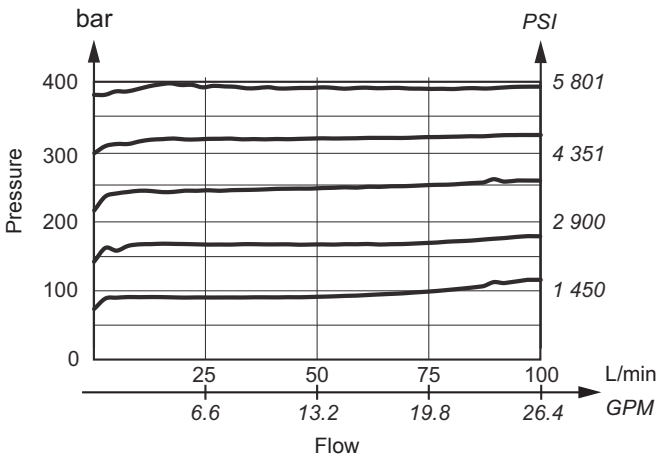
High pressure relief valves are intended for transient overpressure protection and are not intended for continuous pressure control. Flow over relief valves for extended periods of time may result in severe heat build up. High flows over relief valves may result in pressure levels exceeding the nominal valve setting and potential damage to system components.

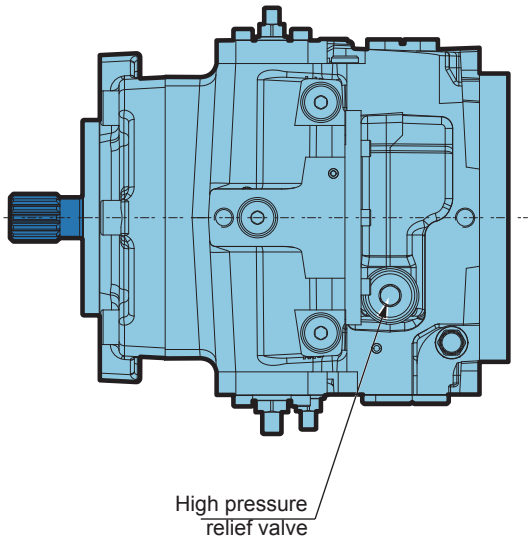
P	M	3	0	1	2	3	4	5	6	7	8	9	10	11

Hight pressure relief valve	Available setting bar *[PSI]*	
Without	-	00
With	150 *[2 175]*	15
	200 *[2 900]*	20
	250 *[3 625]*	25
	300 *[4 351]*	30
	350 *[5 076]*	35
	370 *[5 366]*	37
	400 *[5 801]*	40



ISO VG46 hydraulic fluid at 50°C *[122°F]*





To check close loop pressure use ports M1-M2.

Charge relief valve

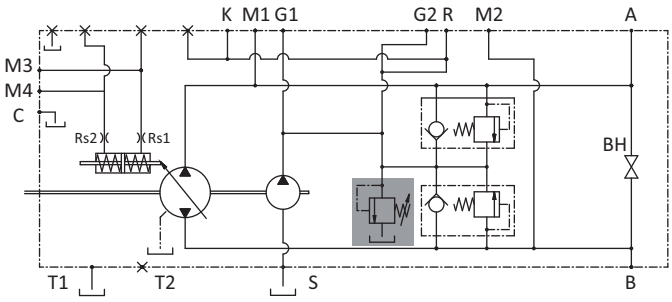
The charge pressure relief valve provides a relief outlet for charge circuit. This valve is used to set the charge pressure of the circuit. Flow through the valve is ported to case.

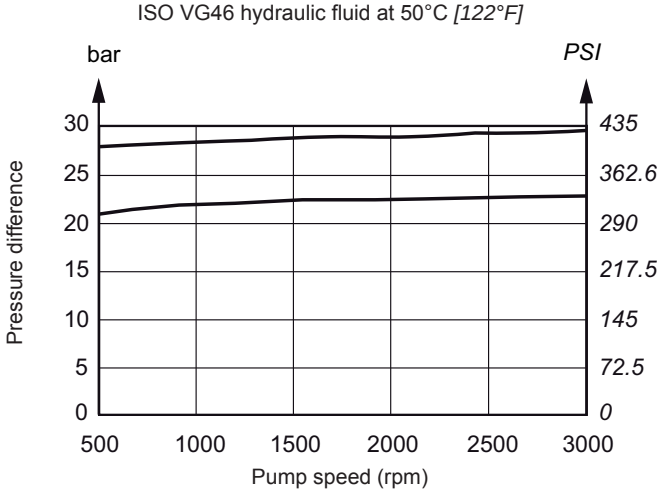
The nominal charge relief setting is referenced to case pressure.

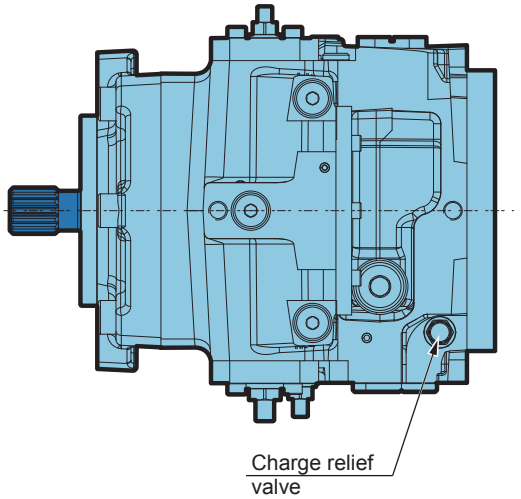
Incorrect charge pressure settings may result in the inability to build required system pressure and/or inadequate loop flushing flows. Ensure correct charge pressure under all conditions of operation to maintain pump control performance.

P	M	3	0	1	2	3	4	5	6	7	8	9	10	11
										☐				

Charge relief valve	Available setting bar *[PSI]*	
Without	-	**00**
With	*20 [290*	**20**
With (standard)	*25 [363]*	**25**
With	*30 [435]*	**30**



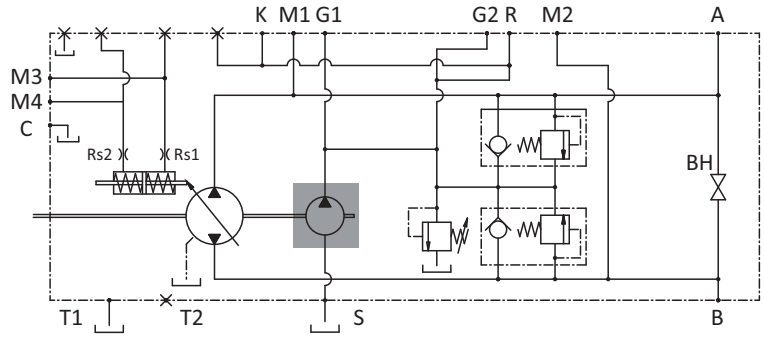




To check charge pressure use ports G1-G2.

Charge pump

Charge flow is required on all PM30 pumps used in closed circuit installations. The charge pump provides flow to make up internal leakage, maintain a positive pressure in the main circuit, provide flow for cooling and filtration, replace any leakage losses from external valving or auxiliary systems, and to provide flow and pressure for the control system.
Many factors influence the charge flow requirements. These factors include system pressure, pump speed, pump swashplate angle, type of fluid, temperature, size of heat exchanger, length and size of hydraulic lines, control response characteristics, auxiliary flow requirements, hydrostatic motor type, etc.
Unusual application conditions may require a more detailed review of charge pump sizing. Charge pressure must be maintained at a specified level under all operating conditions to prevent damage to the transmission. Poclain Hydraulics recommends testing under actual operating conditions to verify this.



Charge pump sizing / selection

In most applications a general guideline is that the charge pump displacement should be at least 20% of the main pump displacement.

P	M	3	0	1	2	3	4	5	6	7	8	9	10	11

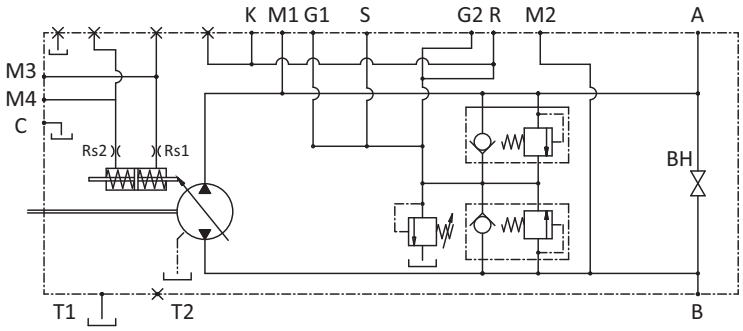
Charge pump	Displacement cm³/rev *[in³/rev]*	Rated speed (rpm)	
Without	-	-	**00**
With	8 *[0.49]*	3600	**08**
	11 *[0.67]*	3600	**11**
	15,8 *[0.96]*	3600	**16**

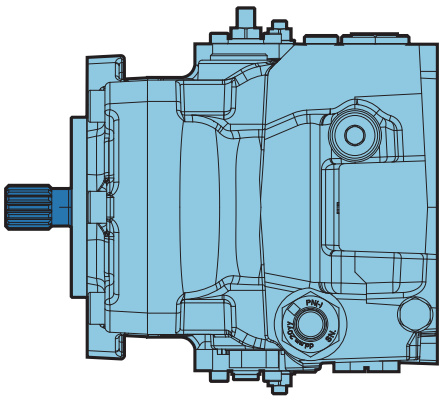
Contact your Poclain Hydraulics application engineer for more information.

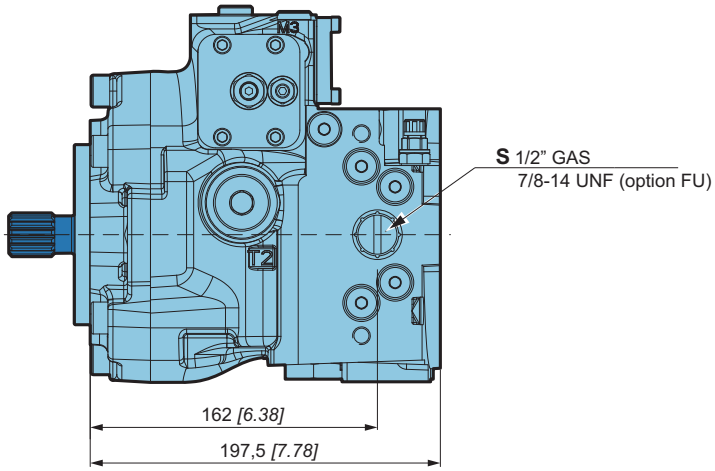
Without charge pump

1	2	3	4	5	6	7	8	9	10	11
P	M	3	0					00	S			

The external charge flow must be the same that the internal charge pump flow and connect with port S.





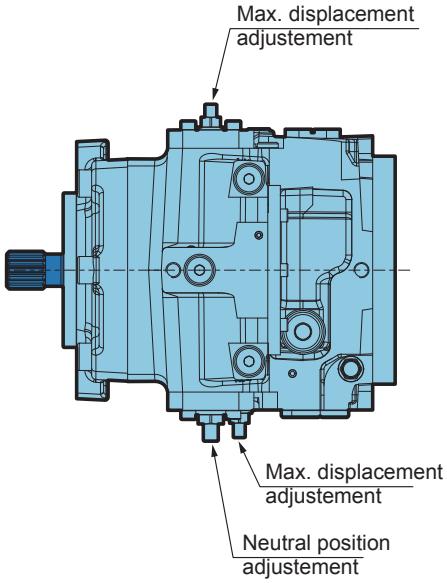


Displacement limiters

PM30 are designed with mechanical displacement (stroke) limiters. You can limit maximum displacement of the pump to a certain per-cent of its maximum displacement to near zero in both direction.

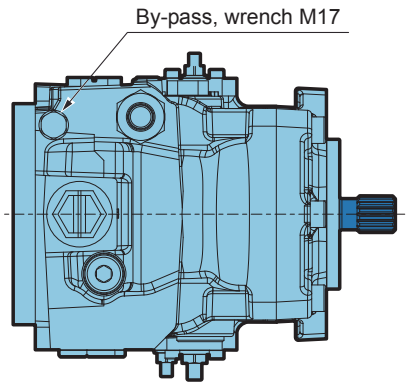
The displacement limiters are located on the both sides of the servo piston and are adjustable by screw. On request the setting of the max. displacements can be different, in this case two values must be indicated in order code (first for port A).

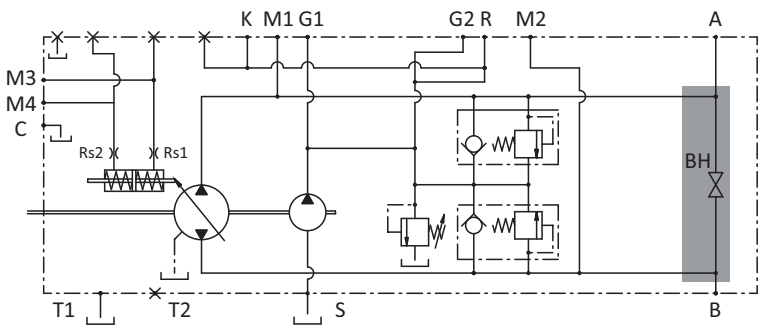
Take care in adjusting displacement limiters to avoid an undesirable condition of output flow or speed. Retorque the sealing lock nut after every adjustment to prevent an unexpected change in output conditions and to prevent external leakage during pump operation.



By-pass

PM30 features a by-pass function. By-passing Port A and Port B is achieved by unscrewing a screw located on the cover. The by-pass connect the ports A-B and must be use only in emergency case and only for short movement.





To avoid leakage, do NOT exceed two turns of the screw.

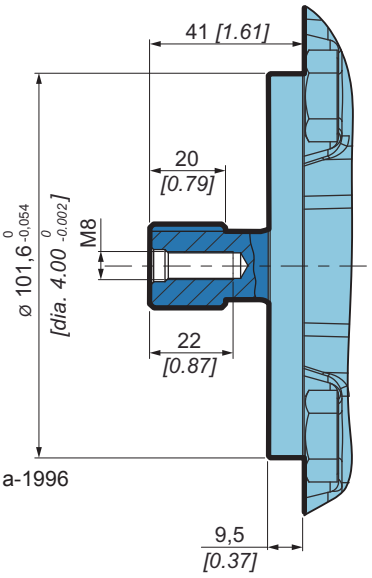
By-pass valve is intended for moving a machine for very short distances at very slow speeds. It is NOT intended as tow valve.

Mounting flange and shafts

P	M	3	0	1	2	3	4	5	6	7	8	9	10	11

S3 SAE B - Splined shaft

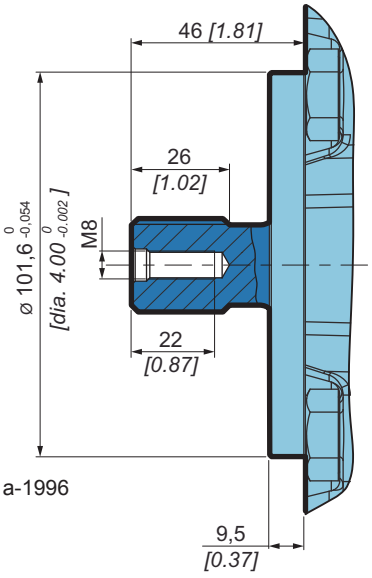
13 teeth; Max. torque: 220 Nm *[1947 in.lbf]*



Splined ANSI B92.1a-1996
Pitch 16/32" DP
Pressure angle 30°
Tolerance class: 5

S4 SAE BB - Splined shaft (standard)

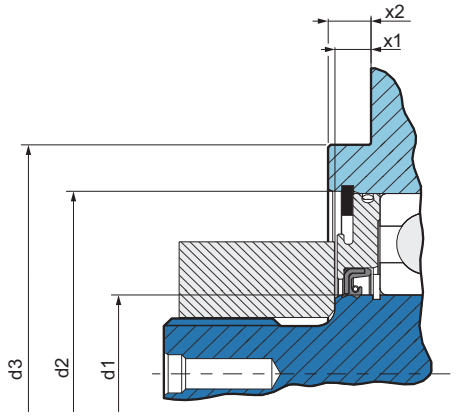
15 teeth; Max. torque: 360 Nm *[3186 in.lbf]*



Splined ANSI B92.1a-1996
Pitch 16/32" DP
Pressure angle 30°
Tolerance class: 5

Fundamental dimensions for coupling assembly

To avoid the contact between rotating and fixed parts the below dimensions for coupling must be observed.



Size	Ød$_1$	Ød$_2$	Ød$_3$	x$_1$	x$_2$
PM50	30 *[1.18]*	73 $^{+0,1}$ *[2.87 $^{+0.004}$]*	101,6 *[3.99]*	8 *[0.31]*	9 $_{-0,1}$ *[0.35 $_{-0.004}$]*

For precise info regarding coupling assembly contact your Poclain Hydraulics application engineer.

Auxiliary mounting pad

SAE A flanges

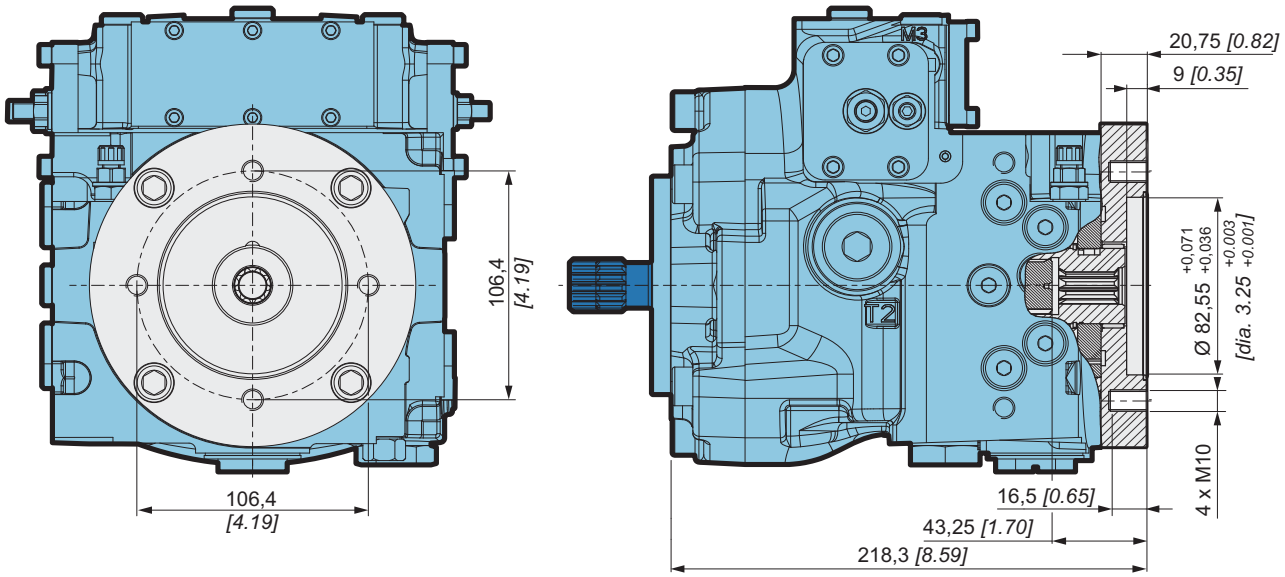
P	M	3	0	1	2	3	4	5	6	7	8	9	10	11

Flange type	Number of teeth	Pitch	Max. torque *N.m [in.lbf]*	
SAE A	9	5/8'' pitch 16/32'' DP	80 *[708]*	A
	11	3/4'' pitch 16/32'' DP	160 *[1 416]*	E

00	Without charge pump

8	With charge pump: 8,0 cm^3/rev *[0.49 in^3/rev]*
11	With charge pump: 11,0 cm^3/rev *[0.67 in^3/rev]*
16	With charge pump: 15,8 cm^3/rev *[0.96 in^3/rev]*

Splined ANSI B92.1a-1996
Pressure angle 30°
Tolerance class: 5



O-ring: OR-1.78-85.34-NBR70
P/N: A44937U

Do not rotate the thru shaft cover.

SAE-B and SAE-BB flanges

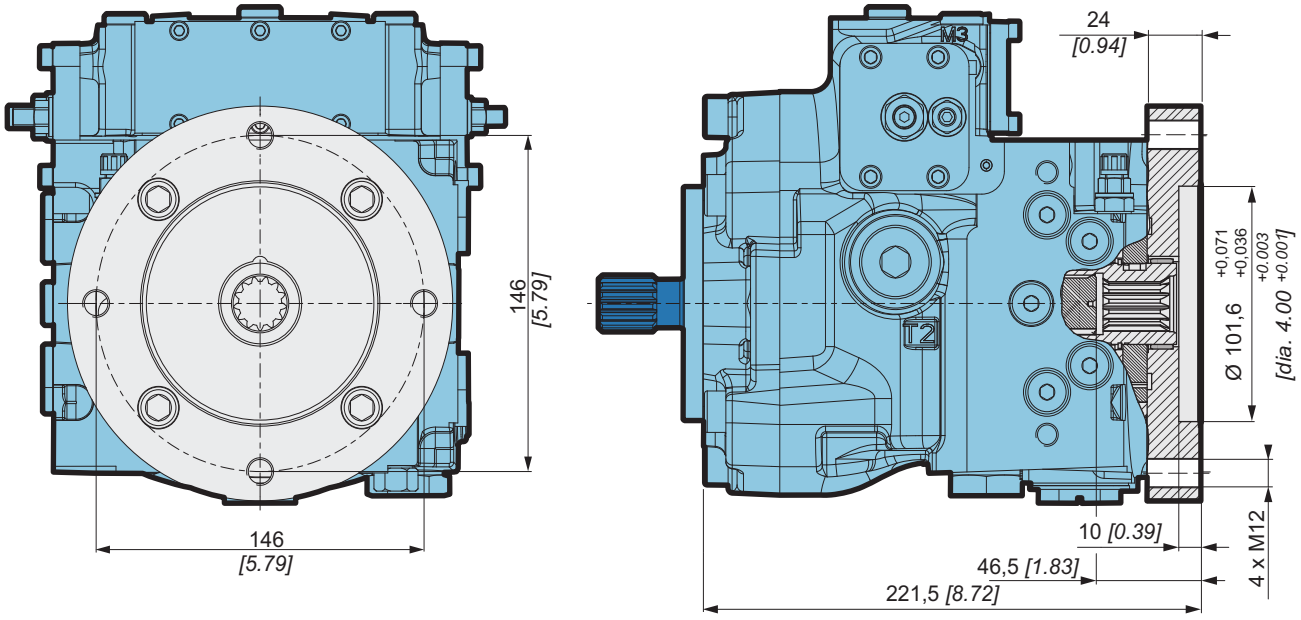
P	M	3	0	1	2	3	4	5	6	7	8	9	10	11

Flange type	Number of teeth	Pitch	Max. torque N.m [in.lbf]	
SAE B	13	7/8" pitch 16/32" DP	220 *[1 950]*	B
SAE BB	15	1" pitch 16/32" DP	360 *[3 186]*	C

00	Without charge pump

8	With charge pump: 8,0 cm^3/rev *[0.49 in^3/rev]*
11	With charge pump: 11,0 cm^3/rev *[0.67 in^3/rev]*
16	With charge pump: 15,8 cm^3/rev *[0.96 in^3/rev]*

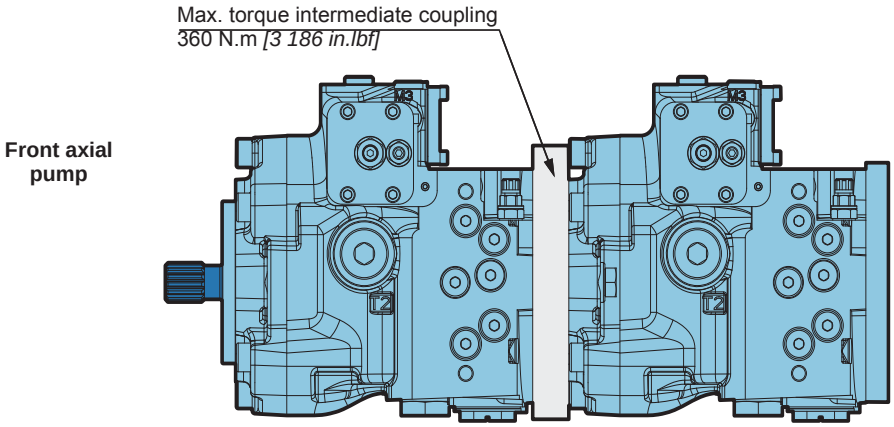
Splined ANSI B92.1a-1996
Pressure angle 30°
Tolerance class: 5



O-ring: OR-1.78-101.32-NBR70
P/N: A47888C

Do not rotate the thru shaft cover.

Tandem pumps



M_e imput torque
M_{e1} for the first pump
M_{e2} for the second pump
M_{e3} for the next pump

Torque required by auxiliary pumps is additive.
Ensure requirements don't exceed shaft torque ratings.

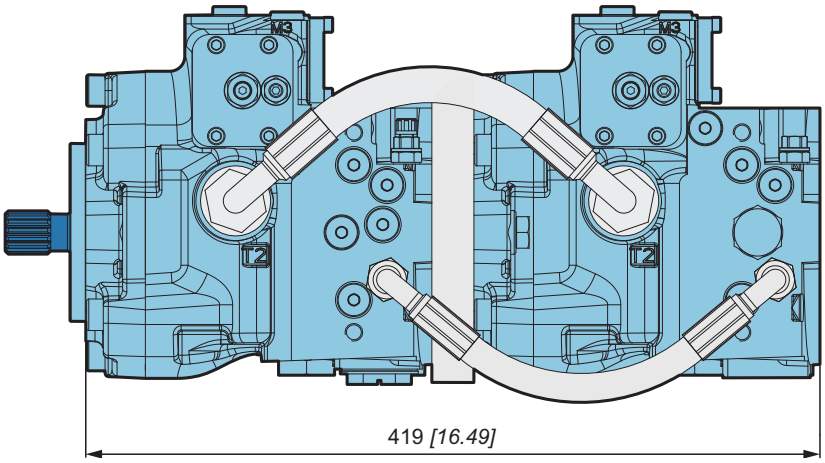
	1	2	3	4	5	6	7	8	9	10	11
Front axial pump	P	M	3	0									
+													
Rear axial pump	P	M	3	0		S4							

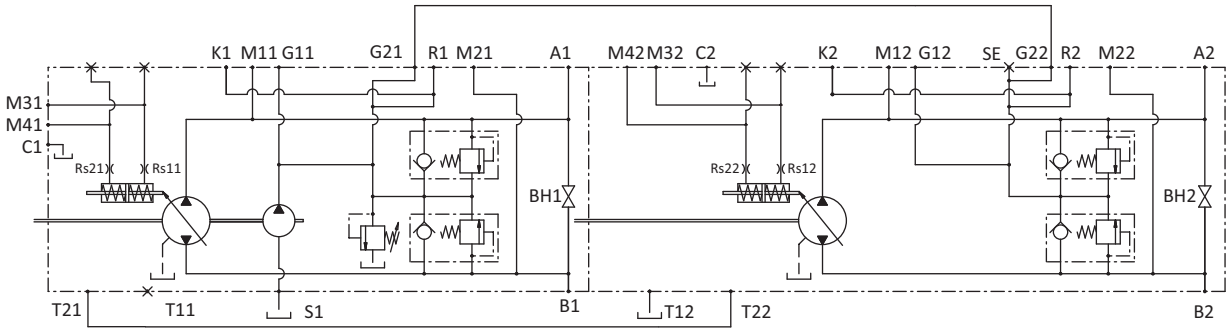
Number of charge pump in the tandem	Axial pump	Mounting flange and shaft		Charge pump		Auxiliary mounting flange		Total axial lenght mm *[inch]*
0 charge pump	**Front**	SAE BB; 15 teeth	**S4**	Without	**00**	Tandem fitting	**T**	
	Rear	SAE BB; 15 teeth	**S4**	Without	**00**	Without fitting	**S**	419,0 *[16.49]*
						SAE A; 9 teeth	**A**	439,8 *[17.31]*
						SAE A; 11 teeth	**E**	439,8 *[17.31]*
						SAE B; 13 teeth	**B**	443 *[17.44]*
						SAE BB; 15 teeth	**C**	443 *[17.44]*
1 charge pump	**Front**	SAE BB; 15 teeth	**S4**	With	**08** or **11** or **16**	Tandem fitting	**T**	
	Rear	SAE BB; 15 teeth	**S4**	Without	**00**	Without fitting	**S**	419,0 *[16.49]*
						SAE A; 9 teeth	**A**	439,8 *[17.31]*
						SAE A; 11 teeth	**E**	439,8 *[17.31]*
						SAE B; 13 teeth	**B**	443 *[17.44]*
						SAE BB; 15 teeth	**C**	443 *[17.44]*
2 charge pumps	**Front**	SAE BB; 15 teeth	**S4**	With	**08**	SAE BB; 15 teeth	**C**	
	Rear	SAE BB; 15 teeth	**S4**	With	**11** or **16**	Without fitting	**S**	419,0 *[16.49]*
						SAE A; 9 teeth	**A**	439,8 *[17.31]*
						SAE A; 11 teeth	**E**	439,8 *[17.31]*
						SAE B; 13 teeth	**B**	443 *[17.44]*
						SAE BB; 15 teeth	**C**	443 *[17.44]*

Gear pumps are always delivered flanged on the axial pump. They can not be sold alone.

Example of tandem configuration with 1 charge pump

		1	2	3	4	5	6	7	8	9	10	11
Front axial pump	P M 3 0		S4							T		
+												
Rear axial pump	P M 3 0		S4						00	S		

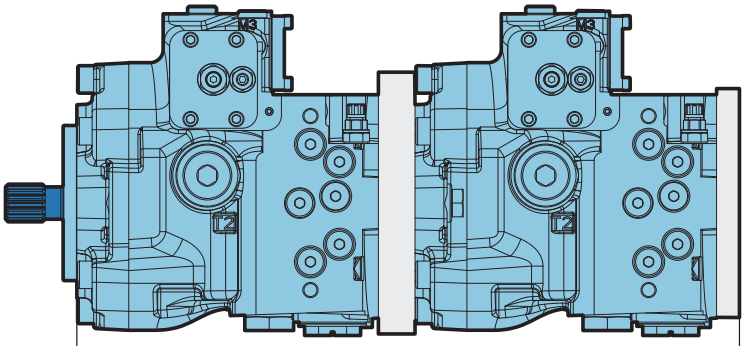


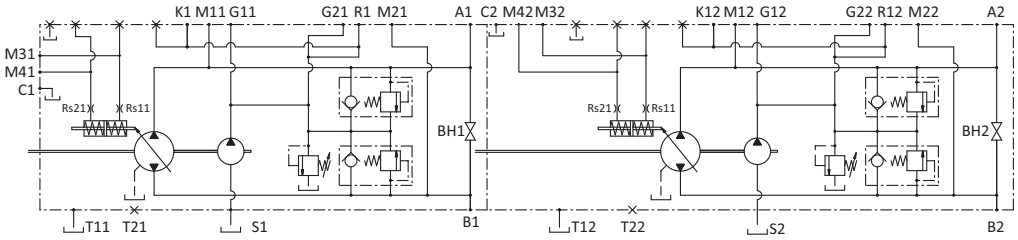


Ports T and G of the first pump must be connectedwith ports T and G of the second pump.

Example of tandem configuration with 2 charge pumps

		1	2	3	4	5	6	7	8	9	10	11
Front axial pump	P M 3 0		S4							C		
+												
Rear axial pump	P M 3 0		S4							S		



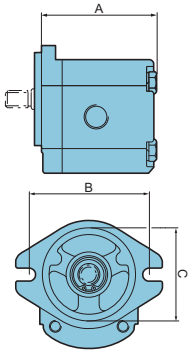


Gear pumps

		1	2	3	4	5	6	7	8	9	10	11
	P M 3 0									A		

A

SAE A flange



	Displacement	Pressure			Dimension			Mass	Efficiency
		Continuous max. pressure	Max. intermittent pressure	Max. peak pressure	A	B	C		
	cm³/rev [cu.in/rev]	bar [PSI]	bar [PSI]	bar [PSI]	mm [in]	mm [in]	mm [in]	Kg [lb]	%
04	4,0 [0.24]	250 [3 625]	270 [3 915]	290 [4 205]	93 [3.66]			2,30 [5.07]	
06	6,0 [0.37]	250 [3 625]	270 [3 915]	290 [4 205]	96,3 [3.79]			2,45 [5.40]	
08	8,5 [0.52]	250 [3 625]	270 [3 915]	290 [4 205]	100,5 [3.96]			2,60 [5.73]	
11	11,0 [0.67]	250 [3 625]	270 [3 915]	290 [4 205]	104,6 [4.12]			2,70 [5.95]	
14	14 [0.85]	250 [3 625]	270 [3 915]	290 [4 205]	109,6 [4.31]	101,6 [3.99]	82,5 [3.25]	2,80 [6.17]	95*
17	16,5 [1.00]	230 [3 335]	240 [3 480]	250 [3 625]	113,8 [4.48]			2,95 [6.51]	
20	19,5 [1.19]	210 [3 045]	220 [3 190]	230 [3 335]	118,8 [4.68]			3,10 [6.84]	
23	22,5 [1.37]	190 [2 755]	200 [2 900]	210 [3 045]	123,8 [4.87]			3,25 [7.17]	
26	26 [1.59]	170 [2 465]	180 [2 610]	190 [2 755]	129,6 [5.10]			3,40 [7.50]	

* Value collected during the testing at 1500 rpm

CONTROLS

Mechanical servo control with feedback

	1	2	3	4	5	6	7	8	9	10	11
P	M	3	0			A						

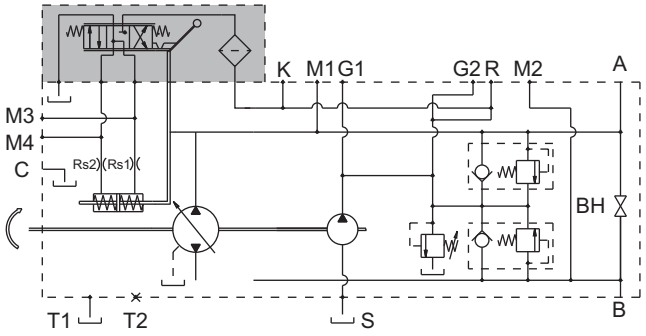
The variation in pump displacement is obtained by rotating the drive lever situated on the servo control. An internal channel, linked to the charge pump, feeds a hydraulic servo valve which supplies oil into the cylinder which is in turn linked to the pump swashplate.
The maximum rotation of the lever, with respect to 0 is 40° for both rotation directions; thus permitting the optimum control of the displacement.

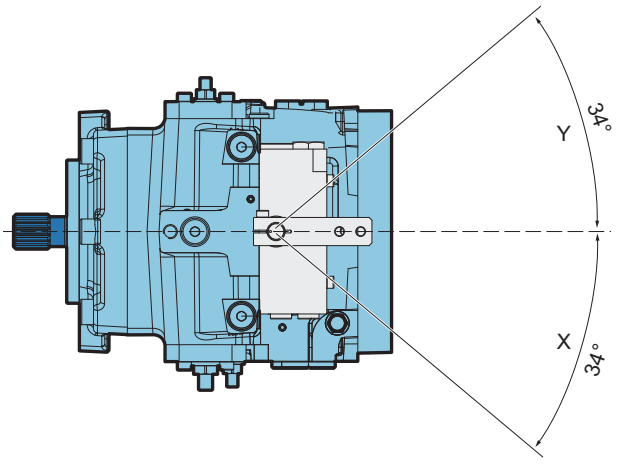
The feedback function is obtained by a lever that connects the swashplate and the servo piston.
To avoid sudden accelerations and stoppages w introduce restrictors (Rs_1 and Rs_2) between the servo piston and the servo control.

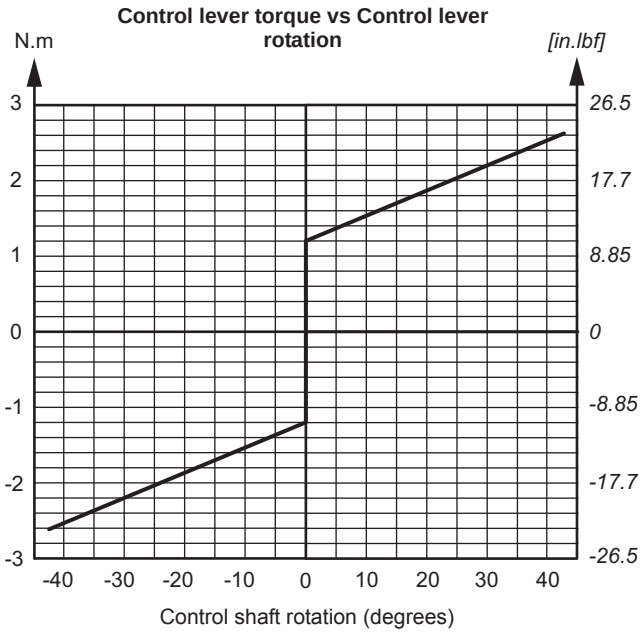
The effort of moving the lever is independent of the pressure and rpm.

Flow rate determination

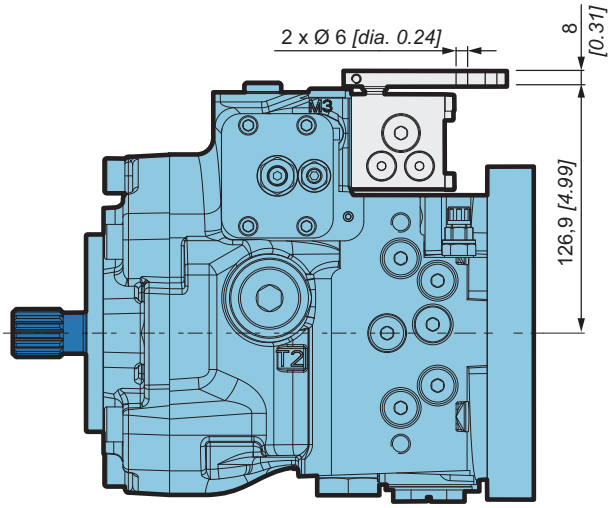
Rotation	Control	Output	Input
Clockwise (R)	X	A	B
	Y	B	A
Counter clockwise (L)	X	B	A
	Y	A	B

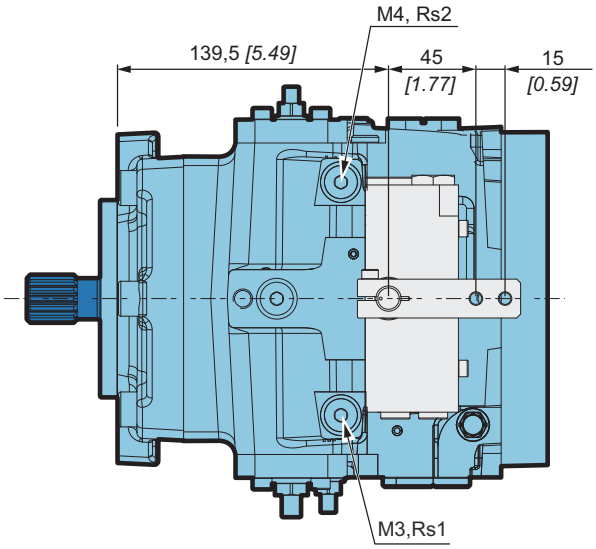






Dimensions with control A





See page 7 for other dimensions
and page 6 for port characteristics.

Hydraulic servo control

		1	2	3	4	5	6	7	8	9	10	11
P	M	3	0										
				S								

The variation in pump displacement is obtained by adjusting the pressure on the M3 and M4 servo control connections by means of a hydraulic proportional joystick (containing pressure reduction valves).

The joystick supply can by obtained by taking pressure from the auxiliary pump (R connection).

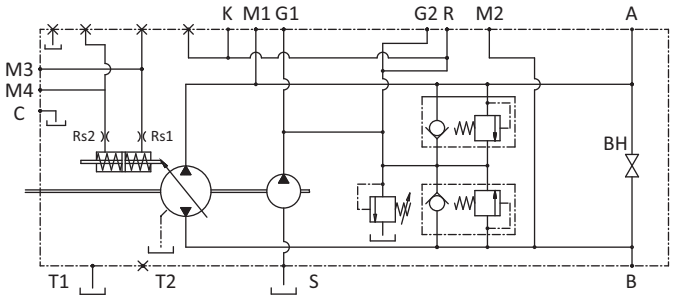
The servo control response time can be adjusted by inserting a restrictor (Rs1 and Rs2) on the joystick supply line (from 0,6 to1,2 mm *[from 0.02 to 0.05 in]*.

The servo control operation pressure in both control directions goes from 4,5 to 15 bar *[from 65 to 218 PSI]*. The adjustment curve of the hydraulic control system has to be wider (from 4 to 16 bar *[from 58* to *232 PSI]*).

Other curves can be used in relation to valve plate timing. Contact your Poclain Hydraulics application engineer for furhter info.

With PM30 control S we can provide some base Joy-stick (require dedicated documentation).

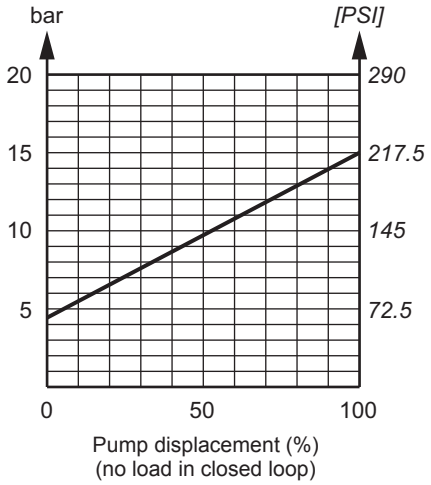
For the selection of the regulation curve (with or without step) of the Joystick contact your Poclain Hydraulics application engineer.



Flow rate determination

Rotation	M3	M4
Clockwise (CW)	A	B
Counter clockwise (CCW)	B	A

Servo pressure vs Displacement



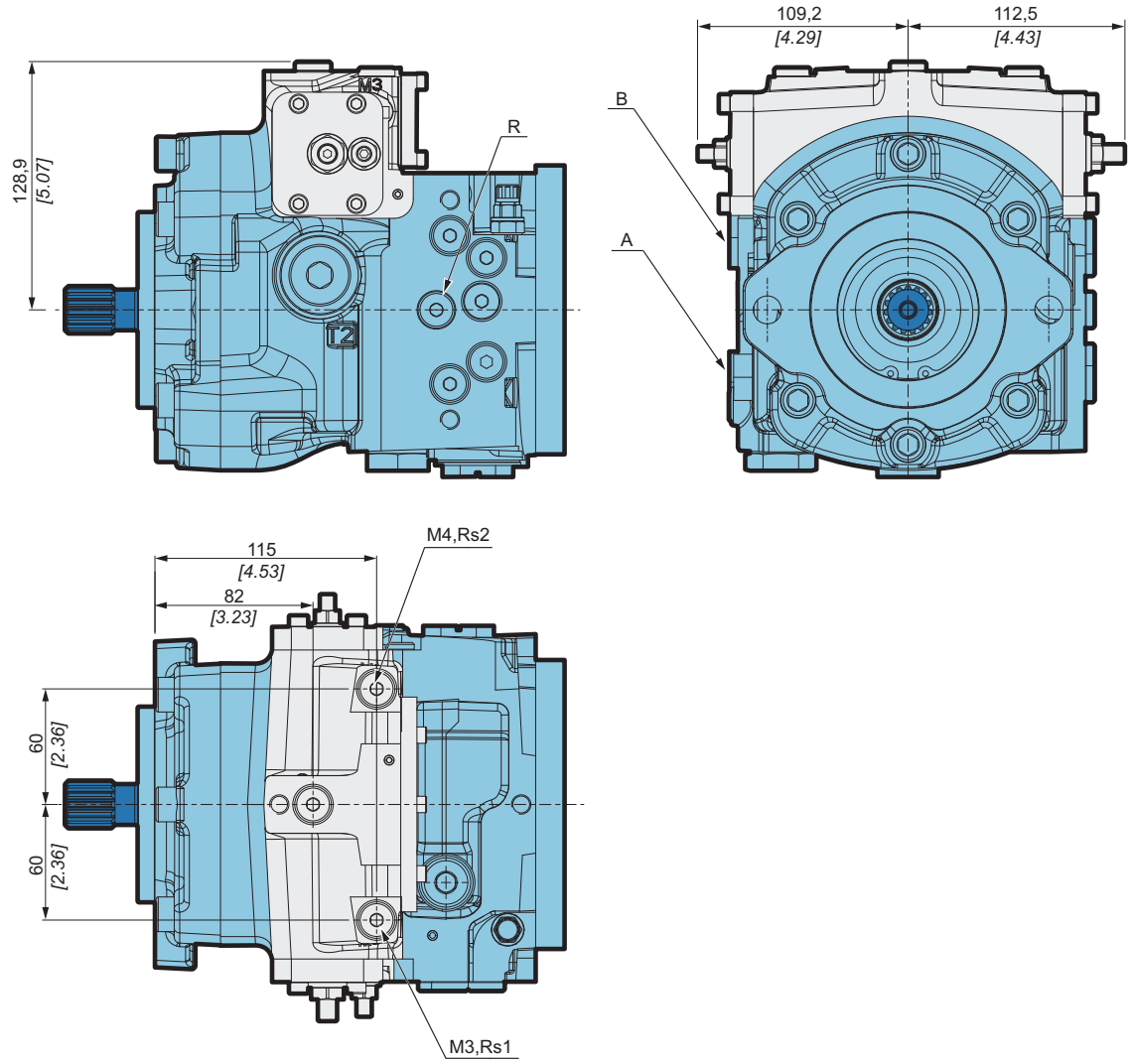
The spring return feature in the control unit is not a safety device.

Hydraulic joystick can be with or without step.

The back pressure of the return line of the joystick and the drive line of the pump hasve an influence on Servo pressure vs Displacement values.

Above graph is just an example that shows the relationship between servo pressure and displacement.

Dimensions with control S



See page 7 for other dimensions
and page 6 for port characteristics.

Hydraulic servo control with feed back

P	M	3	0	1	2	T	4	5	6	7	8	9	10	11

The variation in pump displacement is obtained by adjusting the pressure on the M5 and M6 feed back system connections by means of a hydraulic proportional joystick (containing pressure reduction valves).

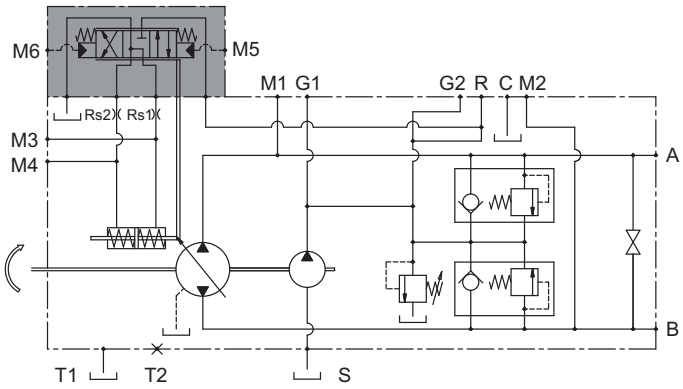
The feedback function is obtained by a lever that connects the swashplate and the servo piston.
To avoid sudden accelerations and stoppages w introduce restrictors (Rs_1 and Rs_2) between the servo piston and the servo control.

The joystick supply can by obtained by taking pressure from the auxiliary pump (R connection).
The servo control feedback time can be adjusted by inserting a restrictor between the control block and the servo-control piston.

The servo control operation curve in both control directions goes from 6 to 15 bar *[87 to 218 PSI]*.

The adjustment curve of the hydraulic control system has to be wider (5 ÷ 16 bar).

The feed-back system between swash plate and servo piston permit to mantain costant the displacement of the pump if change the pressure between pump and hydraulic motor.

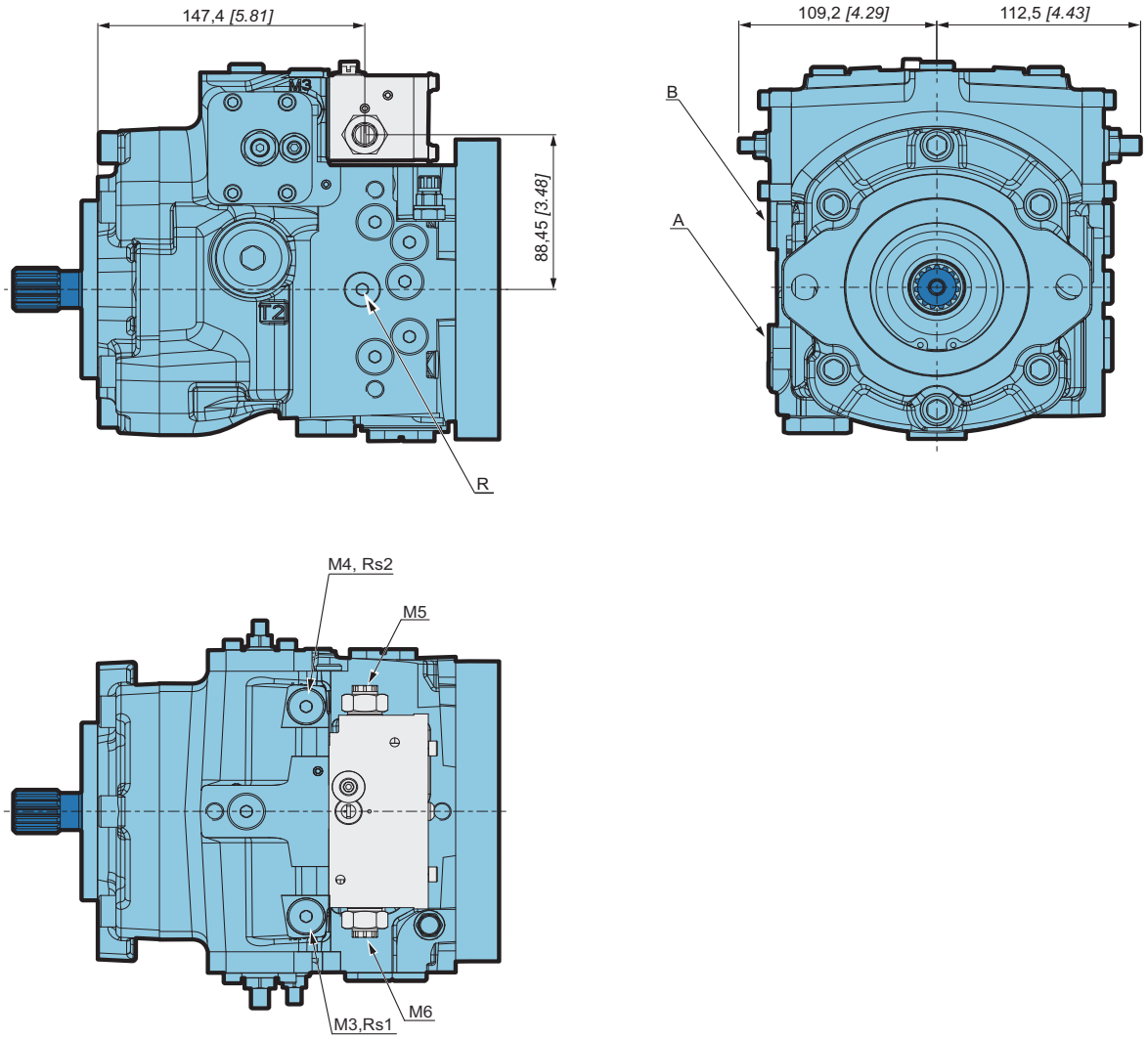


The spring return feature in the control unit is not a safety device.

Hydraulic joystick can be with or without step.

Contact your Poclain Hydraulics application engineer in case of special needs of the control.

Dimensions with control T



See page 7 for other dimensions
and page 6 for port characteristics.

Hydraulic automotive control

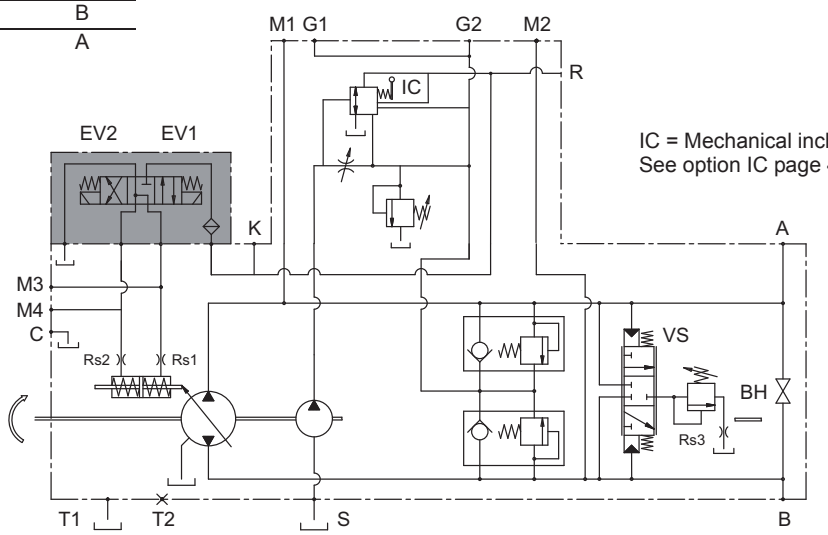
P	M	3	0	1	2	3	4	5	6	7	8	9	10	11

In relation to the input rotation rate, the pump swashplate positioning cylinder is actuated by the pressure of the automotive valve progressively positioning the swashplate and a 4/3 electro-hydraulic valve determine the direction. This provides a continuously variable pump displacement. The direction of the supplied flow is determined by which of the two solenoids is energized.
The pilot pressure increases proportionally to the rotation pump. A pump displacement increase corresponds to the higher pilot pressure.
In case the engine is overloaded, the rotation rate decreases and the pilot pressure is reduced causing a pump displacement reduction with a corresponding drop in absorbed power.
An "Inching" lever is available to reduce the pilot pressure independently of the pump rotation speed (See option IC on page 41).

Supply voltage	
12V	D12
24V	D24

Flow rate determination

Rotation	Pressure	Output	Input
Clockwise (R)	EV1	B	A
	EV2	A	B
Counter clockwise (L)	EV1	A	B
	EV2	B	A

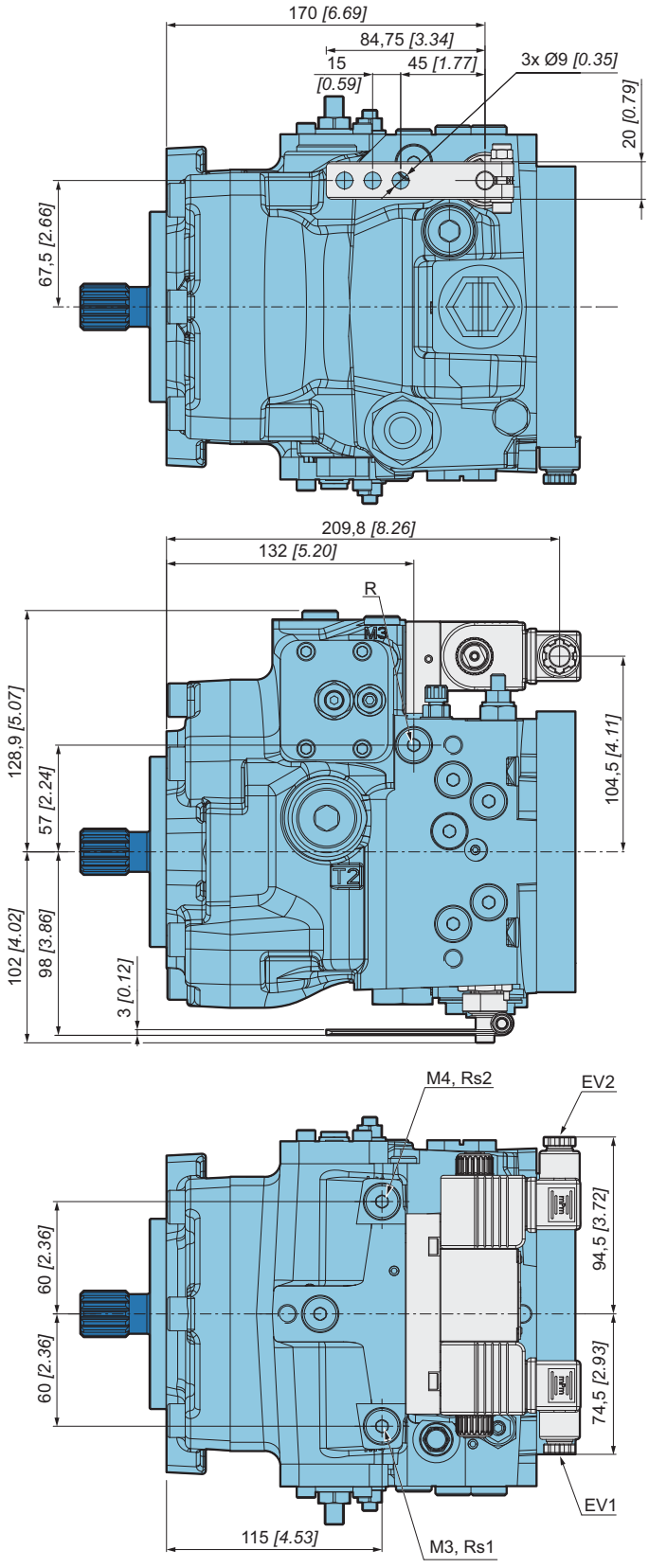


IC = Mechanical inching.
See option IC page 41.

For automotive valve setting are necessary power and torque curve of the engine.

IC rotation angle controls pump destroke. Angle of regulation is 30°.

Dimensions with control D



See page 7 for other dimensions
and page 6 for port characteristics.

Electrical on-off servo control

Control with return spring

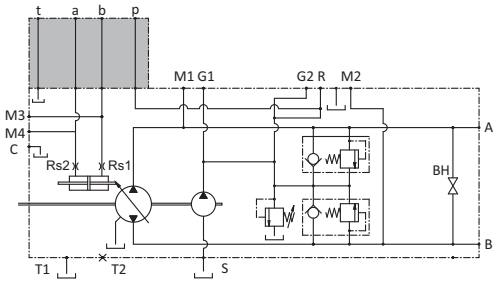
P	M	3	0	1	2	3	4	5	6	7	8	9	10	11
						☐								

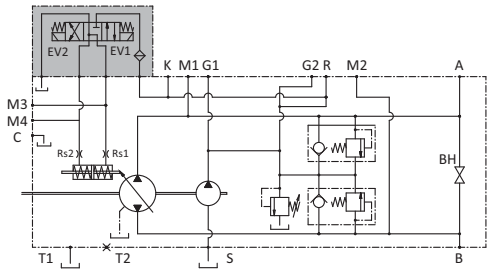
The reaching of the maximum displacement in a time defined by the restrictors (Rs) which are positioned between the electrovalve and two chambers of servo housing are obtained by the continuous starting of an On-Off electrovalve with an open-circuit CETOP 2 connection.

If the electro-valve motion is stopped, the pump goes back to “0” position thanks to the servo control springs.

The pump can be supplied either without electrovalve (B00) or with electrovalve (B12, B24).

Supply voltage	
without	**B00**
12V	**B12**
24V	**B24**





The center of the on-off electrovalve is open

Control without return spring

P	M	3	0	1	2	3	4	5	6	7	8	9	10	11
						☐								

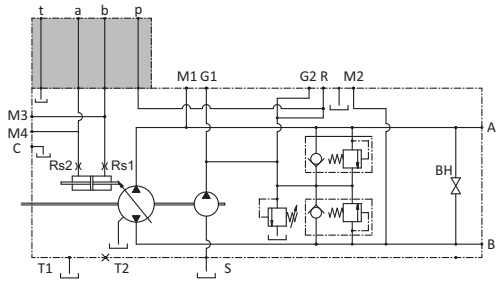
The variation in pump displacement is obtained by the energizing of an ON-OFF electro-valve with a closed center CETOP 2 connection.

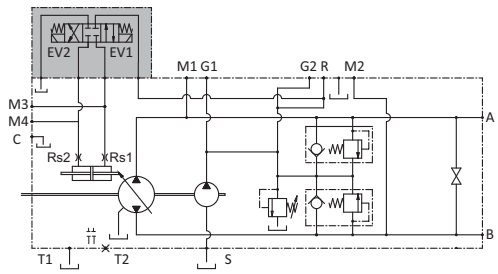
The displacement reached is in relation to the starting time of the electro-valve and to the diameter of the Rs1and Rs2 restrictors which are placed between the electrovalve and the servo-control.

The pump can be supplied either without electrovalve (C00) or with electrovalve (C12, C24).

The servo control is without springs and the setting of the pump at a certain displacement is guaranteed by the closed center of the electrovalve.

Supply voltage	
without	**C00**
12V	**C12**
24V	**C24**





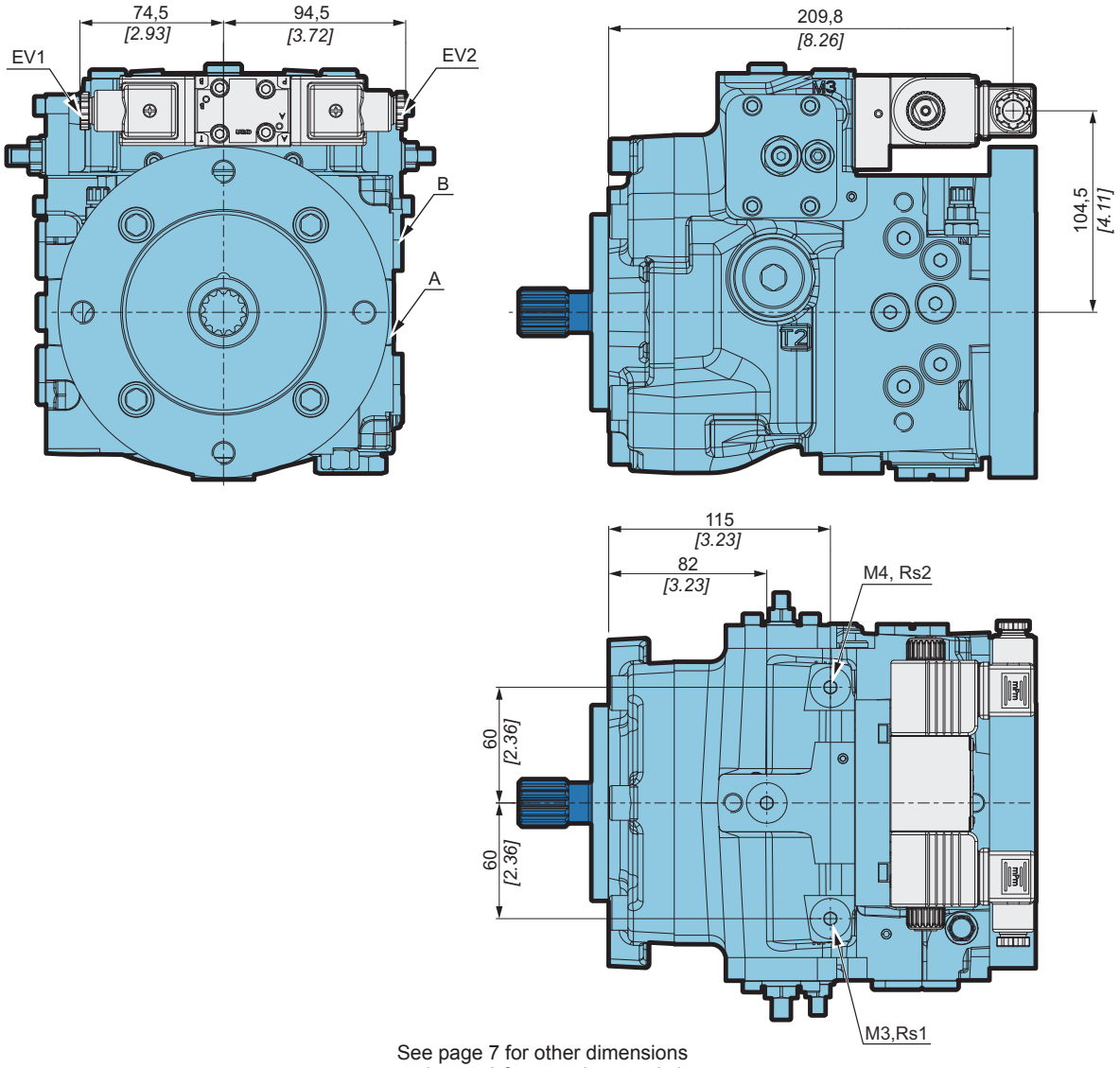
The center of the on-off electrovalve is closed

Flow rate determination

Rotation	EV1	EV2
Clockwise (CW)	A	B
Counter clockwise (CCW)	B	A

The spring return feature in the control unit is not a safety device.

Dimensions with controls B or C



See page 7 for other dimensions
and page 6 for port characteristics.

Solenoids specification		
Operating voltage	12 VDC ± 10%	24 VDC ± 10%
Current	1500 mA	750 mA
Resistance at 20°C *[68°F]*	5,3 Ω ± 7%	21,3 Ω ± 7%
Connector type	DIN 43650	
Power	27 W	
Protection	IP65	
Mass	0,215 kg *[0.47 lb]*	

Electro-proportional servo control

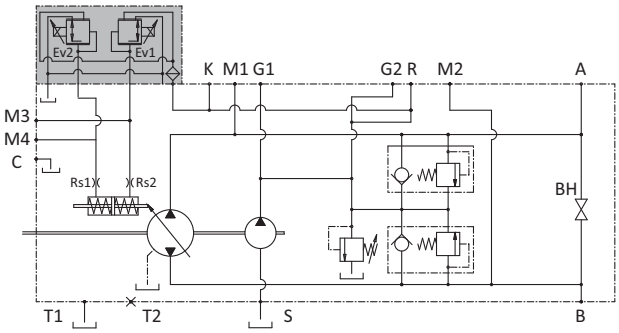
P	M	3	0	1	2	3	4	5	6	7	8	9	10	11
						↓								

By means of a potentiometer and a control card, a current signal is applied to the proportional electrovalve coils which adjust the pressure of the servo control connected to the pump swashplate.
At every position of the potentiometer lever, there is a corresponding swashplate position.
The flow rate direction depends on which coil is excited.

The reaction time can be controlled by ramps installed on the card and by restrictors (Rs) positioned between the electrovalve and the servo control.

Electro-proportional servo control combined with Electronic control unit and appropriate software functions can be used to reproduce an higher performances Automotive control.

Supply voltage	
12V	**P12**
24V	**P24**



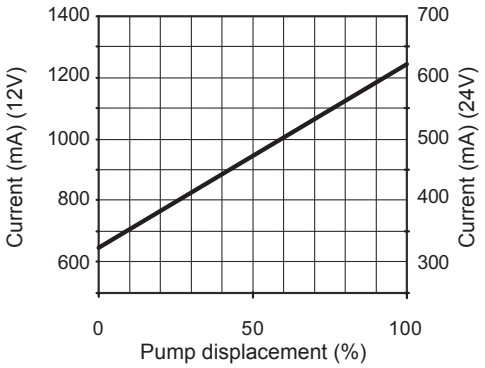
Flow rate determination

Rotation	EV1	EV2
Clockwise (CW)	A	B
Counter clockwise (CCW)	B	A

Valve plate timing and regulation curve of proportional valve influence the flow. Contact your Poclain Hydraulics application engineer for further info.

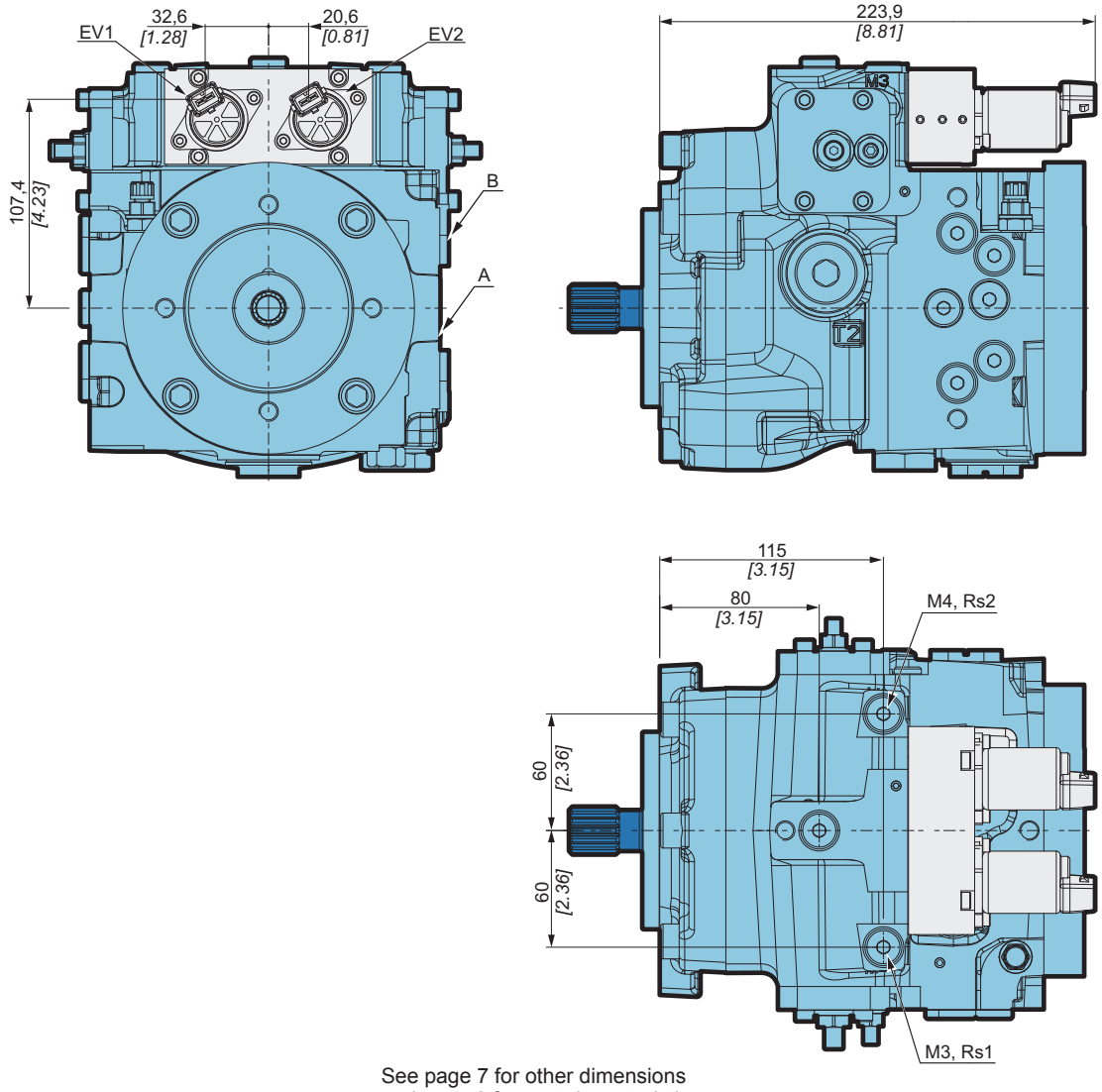
The current must not exceed 1500 mA under 12V and 800 mA under 24V.

Electrovalve current vs Displacement



The spring return feature in the control unit is not a safety device.

Dimensions with control P



See page 7 for other dimensions
and page 6 for port characteristics.

Solenoids specification		
Operating voltage	12 VDC	24 VDC
Current	1500 mA	750 mA
Resistance at 20°C *[68°F]*	5,3 Ω ± 5%	21,2 Ω ± 5%
Connector type	AMP Junior Timer (standard) Deutsch DT04-2P	
Protection	IP6K6 / IPX9K	

Electro-proportional servo control with feed back

P	M	3	0	1	2	3	4	5	6	7	8	9	10	11

Supply voltage	
12V	Q12
24V	Q24

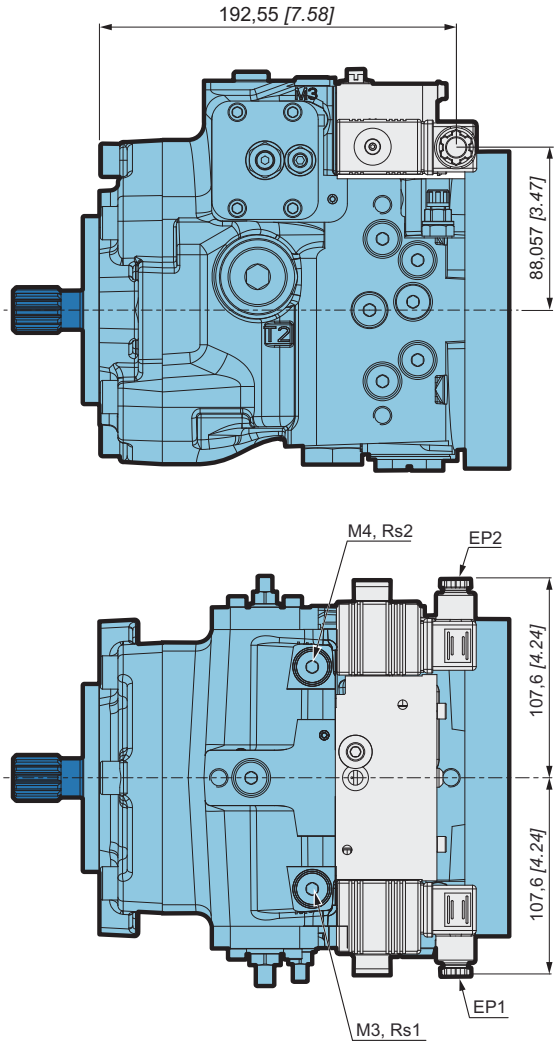
By means of a potentiometer and of a control card, a voltage signal is applied to the proportional electro-valve coils which adjust the pressure of the servo control connected to the pump swashplate.

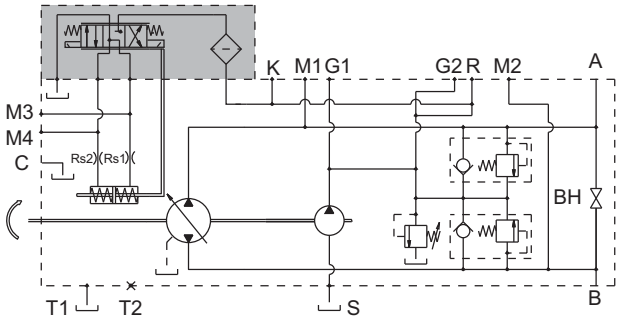
The feedback function is obtained by a lever that connects the swashplate and the servo piston.
To avoid sudden accelerations and stoppages w introduce restrictors (Rs_1 and Rs_2) between the servo piston and the servo control.

At every position of the potentiometer lever, there is a corresponding swashplate position.
The flow rate direction depends on which coil is excited.

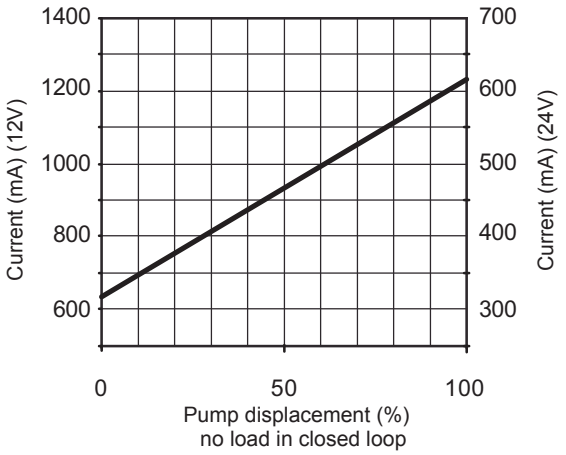
The reaction time can be controlled by ramps installed on the card and by restricters positioned between the electro-valve and the servo control.

The feed back system permit to maintain costant the displacement of the pump if the pressure change between pump and hydraulic motor.





Electrovalve current vs Displacement



Solenoids specification		
Operating voltage	12 VDC	24 VDC
Current	1500 mA	750 mA
Resistance at 20°C *[68°F]*	5,3 Ω ± 5%	21,2 Ω ± 5%
Connector type	Hirschman DIN 43650 (standard) Deutsch DT04-2P	
Protection	IP6K6 / IPX9K	

See page 7 for other dimensions and page 6 for port characteristics.

OPTIONS

Roller bearing

P	M	3	0	1	2	3	4	5	6	7	8	9	10	11
														CR

It is an optional high capacity bearing.
Depending on the characteristics of shaft load, the duty cycle of the application and the expected life time of your application, Roller bearing might be needed.

Consult your Poclain Hydraulics application engineer.

Customized identification plate

P	M	3	0	1	2	3	4	5	6	7	8	9	10	11
														DP

It is possible to provide our products with dedicated plate (your part number engraved on the plate) when requested.

This option is available only for minimum volume of 50 pieces.

Consult your Poclain Hydraulics application engineer for other possibilities.

Mechanical inching

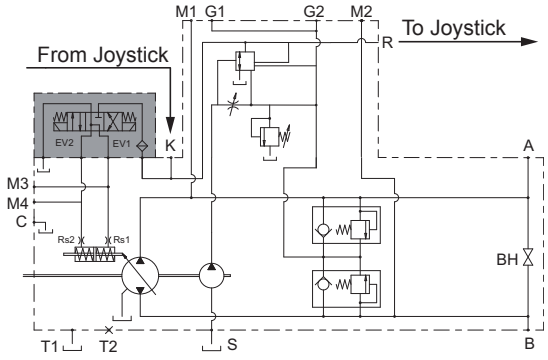
P	M	3	0	1	2	3	4	5	6	7	8	9	10	11
						D12 or D24								IC

For hydraulic automotive control D. An "Inching" lever is available to reduce the pilot pressure independently of the pump rotation speed.
See Hydraulic automotive control D (page 33).

Hydraulic inching

P	M	3	0	1	2	3	4	5	6	7	8	9	10	11
														HI

The function of the HI is to reduce the displacement of pump with hydraulic automotive control D (page 33) with a pressure reducer valve connected with K port. We can provide the pedal type VB3-002 in case of only inching function or VB3-012 in case of inching and service brake.



Filter on pressure line

The PM30 pumps can have a pressure filter without clogging indicator (F0) or with clogging indicator (F2). The flow thru the filter is only the flow that entry in the close loop. The filter fitness is of 10 micron.

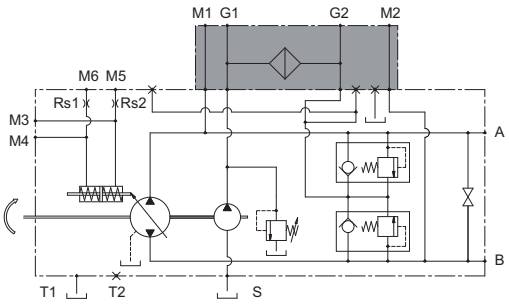
The max. working pressure is 30 bar *[435 PSI]*.

Maximum pressure difference between filter cartridge input and output is 2 bar *[29 PSI]*. When reaching 2 bar *[29 PSI]*, the cartridge has to be changed.

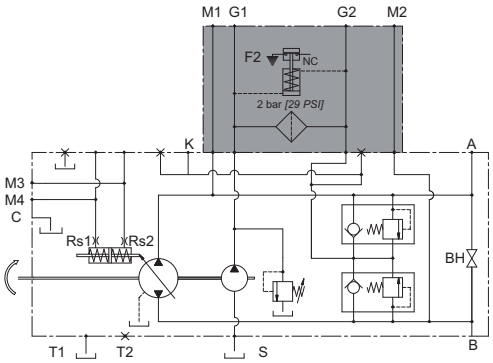
Tightening torque: 35 Nm *[309 in.lbf]*.

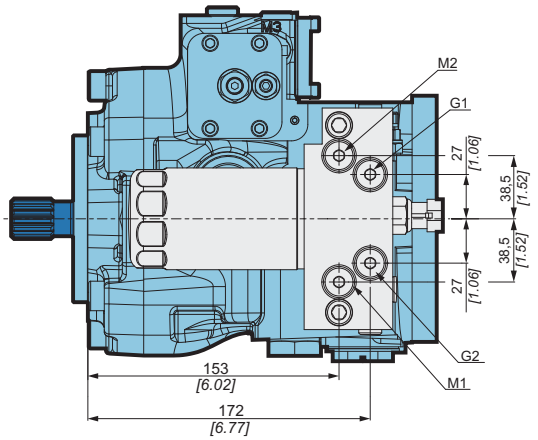
	1	2	3	4	5	6	7	8	9	10	11
P	M	3	0									

F0 **Without clogging indicator**



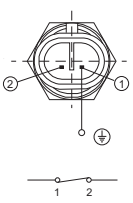
F2 **With clogging indicator**



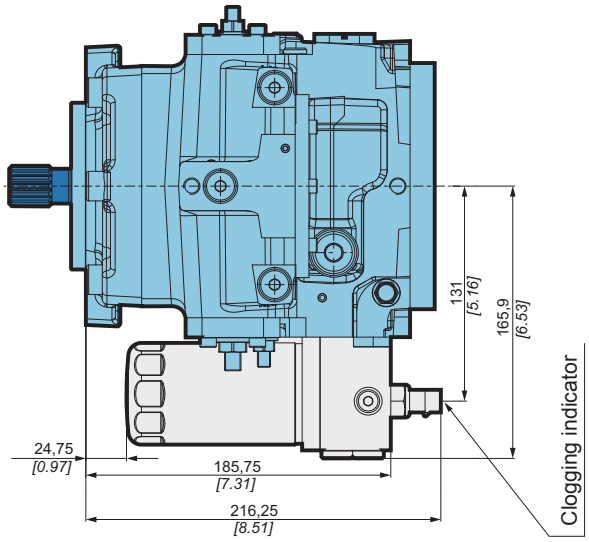


Clogging indicator specification

Differential working adjustment	3 ± 0,2 bar *[44 ± 3 PSI]*
Working temperature	-30°C ~ 110 °C *[-22°F ~ 230°F]*
Max. vibration level	50 g
Connector type	AMP super seal, 2 way
Current range	0,1-0,2 A max.

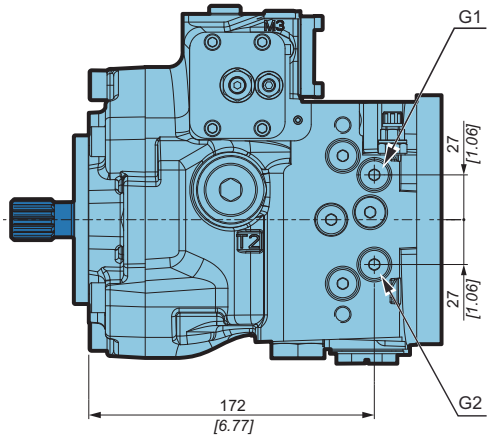


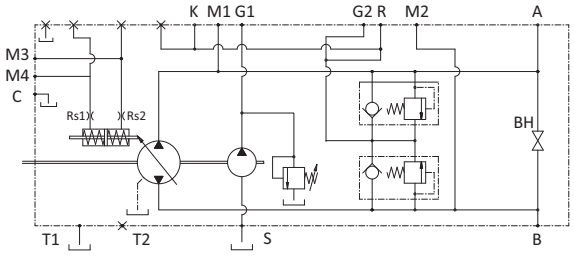
Normally closed contact.
Thread of the clogging indicator is internally connected to the ground.



External connections for filter

P	M	3	0	1	2	3	4	5	6	7	8	9	10	11
														F3

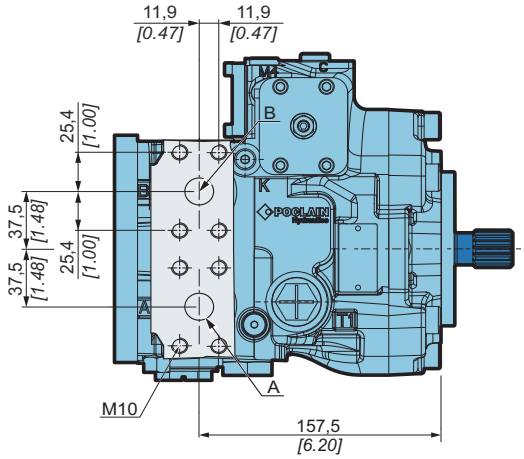




G1 = to filter on line
G2 = Return from filter on line

SAE flange ports

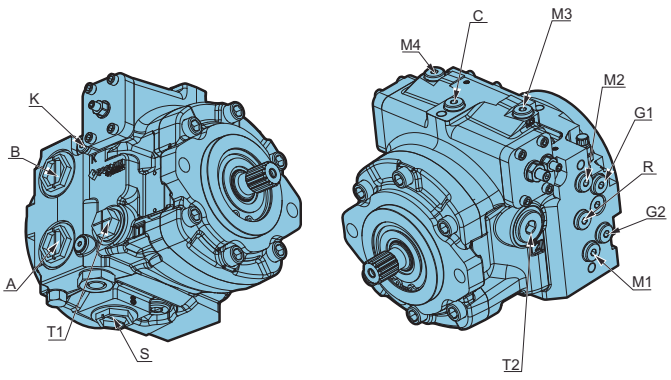
P	M	3	0	1	2	3	4	5	6	7	8	9	10	11
														FS



Port	Function	SAE flange
A-B	Services	SAE PSI 6 000 4xM10
C	Case pressure	1/4'' GAS
G1/G2	Auxiliary/Charge pressure	1/4'' GAS
M1/M2	A/B pressure	1/4'' GAS
M3/M4	Servo control	1/4'' GAS
K	External servo pilot	1/8'' GAS
R	Servo pilot pressure	1/4'' GAS
S	Suction	1'' GAS
T1/T2	Drain	3/4'' GAS

UNF threads ports

P	M	3	0	1	2	3	4	5	6	7	8	9	10	11
														FU



Port	Function	UNF ISO 11926-1
A/B	Services	1" 5/16-12 UNF
C	Case pressure	7/16-20 UNF
G1/G2	Auxiliary/Charge pressure	7/16-20 UNF
M1/M2	A/B pressure	7/16-20 UNF
M3/M4	Servo control	7/16-20 UNF
K	External servo pilot	7/16-20 UNF
R	Servo pilot pressure	7/16-20 UNF
S	Suction	1" 5/16-12 UNF
T1/T2	Drain	1" 1/16-12 UNF

Finishing coat

P	M	3	0	1	2	3	4	5	6	7	8	9	10	11
														PA

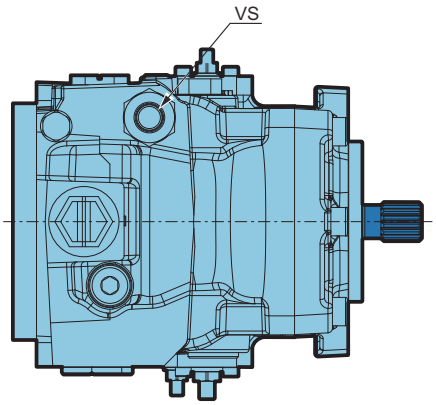
The pumps can be delivered with finishing coat when requested. Standard paint is RAL 9005 (black color).

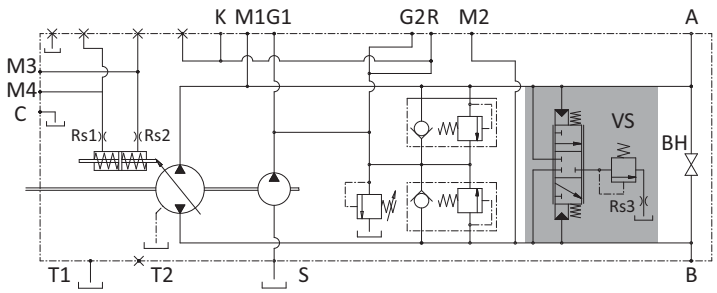
Consult your Poclain Hydraulics application engineer for other colors of topcoat.

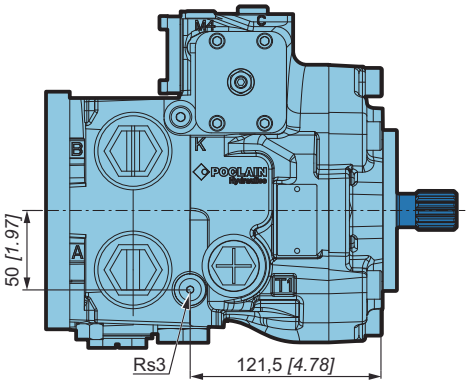
Flushing valve

P	M	3	0	1	2	3	4	5	6	7	8	9	10	11
														VS

On the pump cover, a flushing valve can be fitted with discharge inside the pump casing through a relief valve of the flushing valve. The exchange valve is useful in case the temperature of the oil in the closed circuit is too high.







Flushing flow L/min *[gal/min]*

		Orifice diameter* Rs3 mm *[inch]*		
		1,4 *[0.055]*	1,8 *[0.071]*	2,2 *[0.087]*
Delta pressure bar *[PSI]*	20 *[290]*	2,8 *[0.75]*	4,5 *[1.19]*	5,5 *[1.46]*
	25 *[363]*	3,6 *[0.96]*	5,9 *[1.55]*	7,2 *[1.90]*
	30 *[435]*	4,3 *[1.13]*	7,0 *[1.85]*	8,5 *[2.26]*

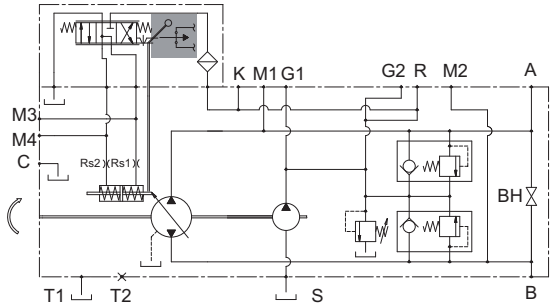
*Standard setting of orifice 2,2 mm

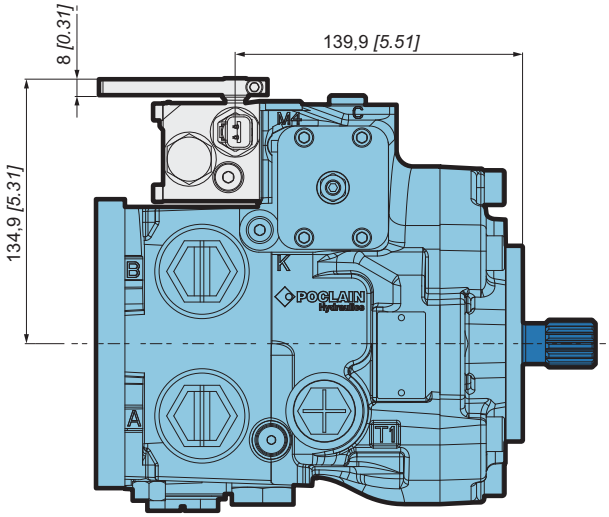
Refer to Poclain Hydraulics service manual for info about restrictor Rs3 exchange.

Neutral position switch

P	M	3	0	1	2	3	4	5	6	7	8	9	10	11
														MI

For the control A (see page 27, Mechanical servo control with feed back) it is possible to obtain a micro switch to avoid the start of the engine if the lever of the control is not in center (zero position).



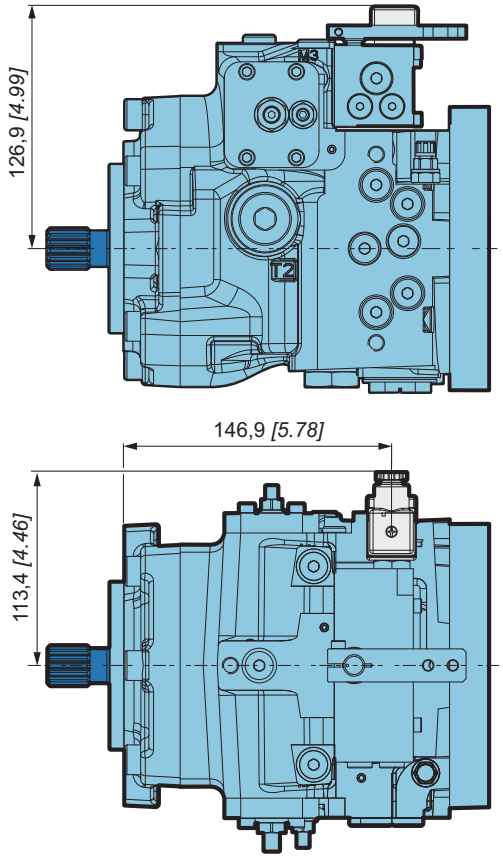


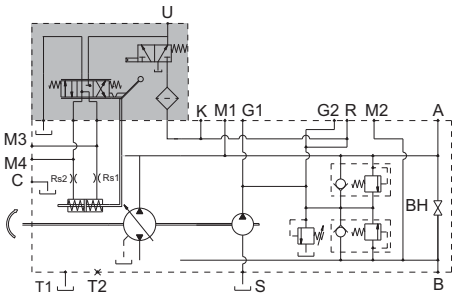
Electrical characteristics	
Type of connector	Deutsch DT04-2P
Output	NC and NO
Cable connections	PG 13,2
Max. current	10 A
Electric load type	Resistive
Operating temperature	from -25°C to 80°C *[-13°F to 176°F]*
Type of protection	IP 67

Safety valve

P	M	3	0			A					VPU
1	2	3	4	5	6	7	8	9	10	11	

The PM30 pump with control A can be provided with a safety valve VPU. Without current, the VPU disconnects the servo control from the charge pressure and engages negative brake.





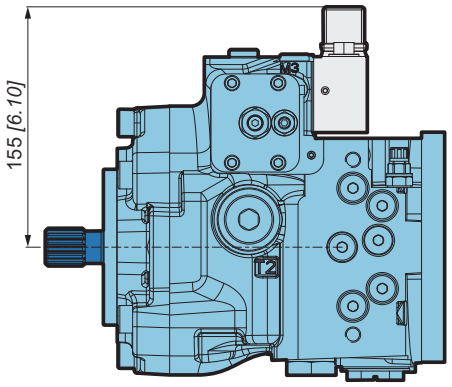
Coil specification	
Type of connector	DIN 43650
Nominal voltage	12V DC
Power	18W
Type of protection	IP 65
Ambient temperature range	from -30°C to 60°C *[-22°F to 140°F]*
Magnet wire insulation	Class H -> 200°C *[392°F]*
Heat insulation	Class H -> 180°C *[356°F]*
Mass	0,19 kg *[0.42 lb]*
Lead wires	600V rating with strain relief

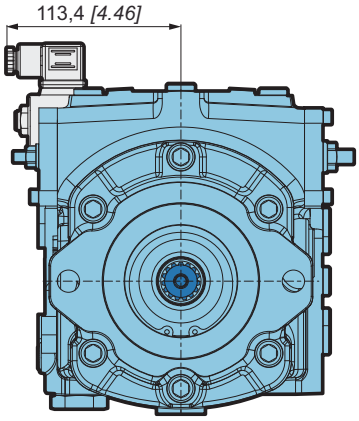
Connector specification	
AC rated voltage	250V max.
DC rated voltage	300V max.
Pin contact rated flow	10A
Pin contact max. flow	16A
Max. cable section	1,5 mm² *[0.002 in²]*
Ø Cable gland PG09-M16x1,5	6 to 8 mm *[0.24 to 0.31 in]*
Type of protection	IP65 EN60529
Insulation class	VDE 0110-1/89
Operating temperature	from -40°C to 90°C *[-40°F to 194°F]*

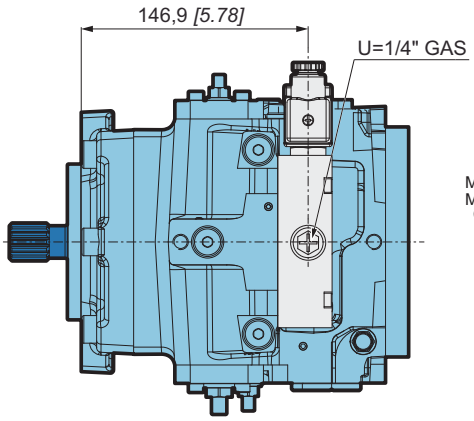
Safety valve

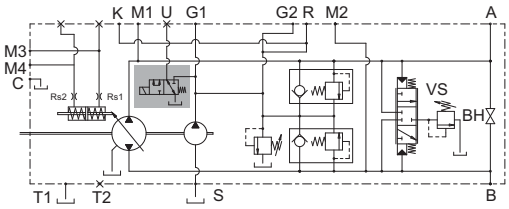
	1	2	3	4	5	6	7	8	9	10	11
P M 3 0			S								VPU

The PM30 pump with control S can be provided with a safety valve VPU. Without current, the VPU disconnects the servo control from the charge pressure and engages negative brake









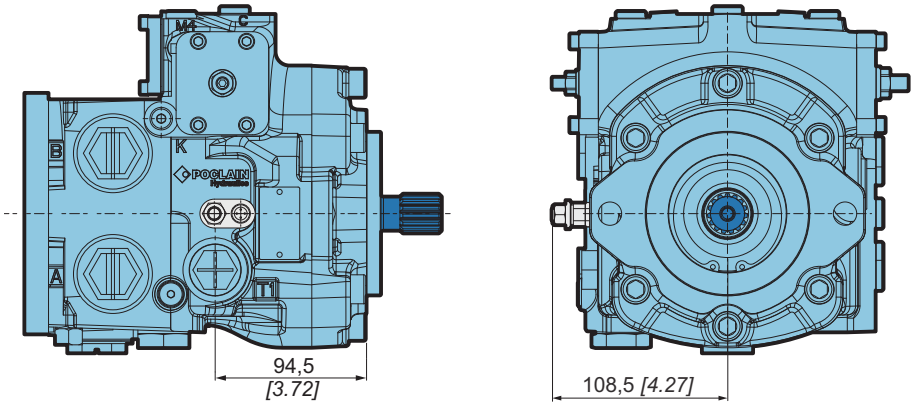
Coil specification	
Type of connector	DIN 43650
Nominal voltage	12V DC
Power	18W
Type of protection	IP 65
Ambient temperature range	from -30°C to 60°C *[-22°F to 140°F]*
Magnet wire insulation	Class H -> 200°C *[392°F]*
Heat insulation	Class H -> 180°C *[356°F]*
Mass	0,19 kg *[0.42 lb]*
Lead wires	600V rating with strain relief

Connector specification	
AC rated voltage	250V max.
DC rated voltage	300V max.
Pin contact rated flow	10A
Pin contact max. flow	16A
Max. cable section	1,5 mm² *[0.002 in²]*
Ø Cable gland PG09-M16x1,5	6 to 8 mm *[0.24 to 0.31 in]*
Type of protection	IP65 EN60529
Insulation class	VDE 0110-1/89
Operating temperature	from -40°C to 90°C *[-40°F to 194°F]*

Speed sensor

	1	2	3	4	5	6	7	8	9	10	11
P M 3 0	☐	☐	☐	☐	☐	☐	☐	☐	☐	☐	SS

A speed sensor can be installed on PM30 pump.



Look at the "Mobile Electronic" N° A01889D technical catalogue for the sensor specifications and its connection.

Speed sensor sends a signal of 9 pulses per revolution.

Fluorinated elastomer seals

	1	2	3	4	5	6	7	8	9	10	11
P M 3 0	☐	☐	☐	☐	☐	☐	☐	☐	☐	☐	EV

Standard NBR sealing are designed to resist to temperature up to 90°C *[194°F]* and to HV type oils. If your application is outside these limits, fluorinated elastomer seals might be recommended.

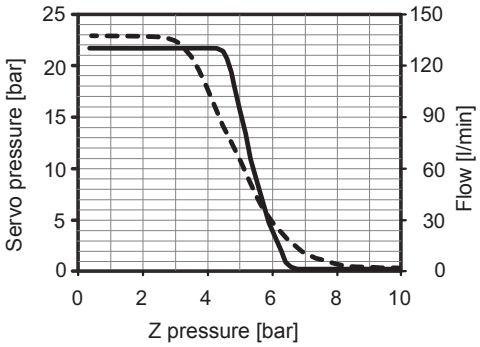
For application of this option please contact your Poclain Hydraulics application engineer.

Brake inching

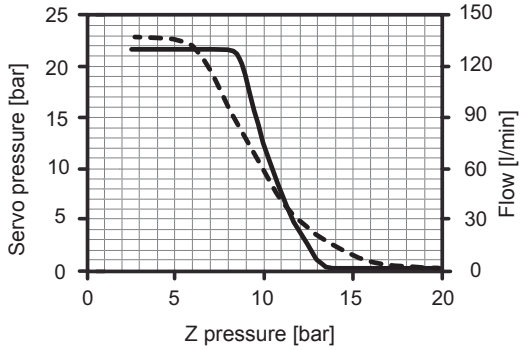
The function of the B1/B2 brake inching is to reduce the displacement of pump with Hydraulic automotive control (page 33) with a brake pedal connected to Z port. We can provide the pedal type VB3-010 in case of only inching function or inching and service brake function.

P	M	3	0	1	2	3	4	5	6	7	8	9	10	11

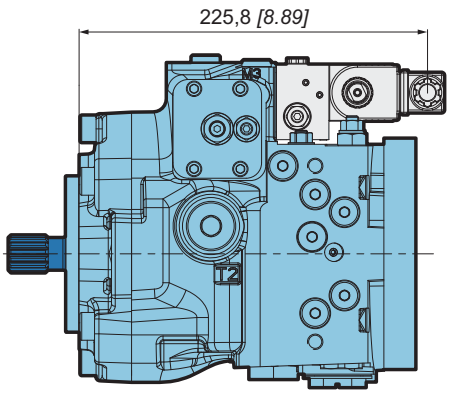
B1 **Hydraulic inching spring 1,3 mm *[0.05 in]***

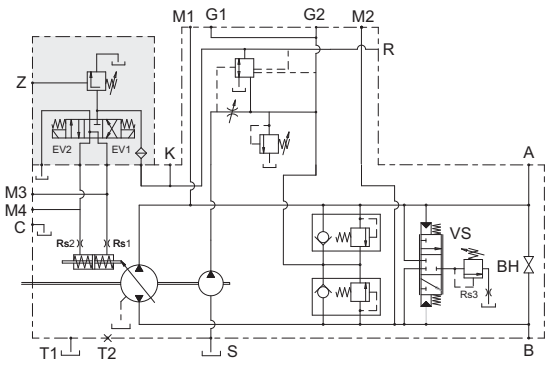


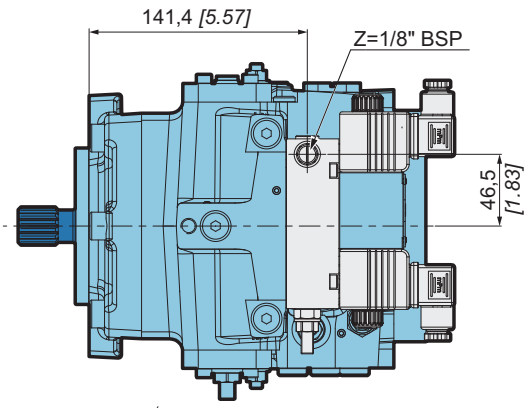
B2 **Hydraulic inching spring 1,5 mm *[0.06 in]***



Flow
Servo pressure







Solenoids specification		
Operating voltage	12 VDC ± 10%	24 VDC ± 10%
Current	1500 mA	750 mA
Resistance at 20°C *[68°F]*	5,3 Ω ± 7%	21,2 Ω ± 7%
Connector type	DIN 43650	
Power	27 W	
Type of protection	IP65	
Mass	0,215 kg *[0.47 lb]*	

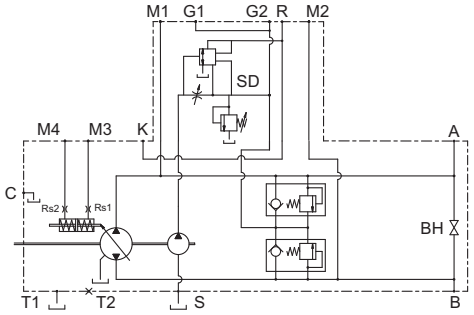
The hydraulic inching valve B1/B2 does not provide any sealing between closed loop circuit and pilot circuit. When choosing this function, please be sure that oil to pilot the inching is coming from the same tank as the closed loop.

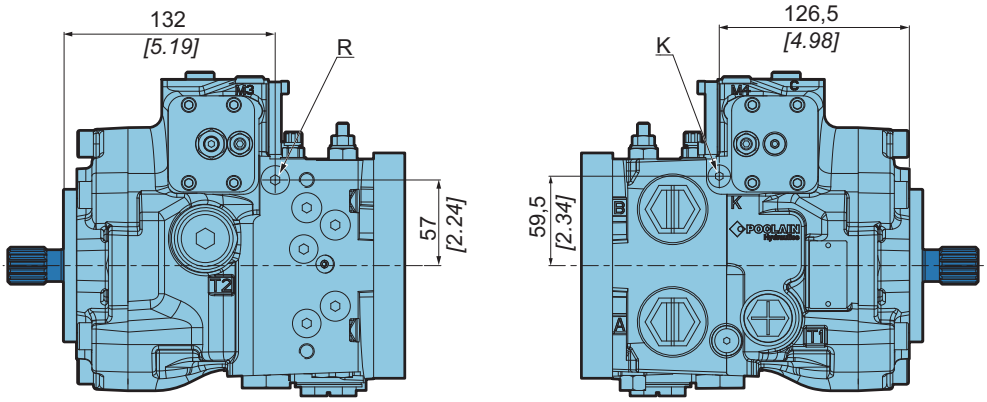
Anti-stall valve

P	M	3	0	1	2	3	4	5	6	7	8	9	10	11
														SD

SD option consists a cartridge valve (same cartridge valve as automotive control) which provide a pressure signal for the servo piston of the pump related to the speed of engine.
In case of engine overload and consequent rpm reduction, the SD valve reduces the pressure for the servo piston and the pump de-stroke consequentially with an anti-stall effect.

For application of this option please contact your Poclain Hydraulics application engineer.





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