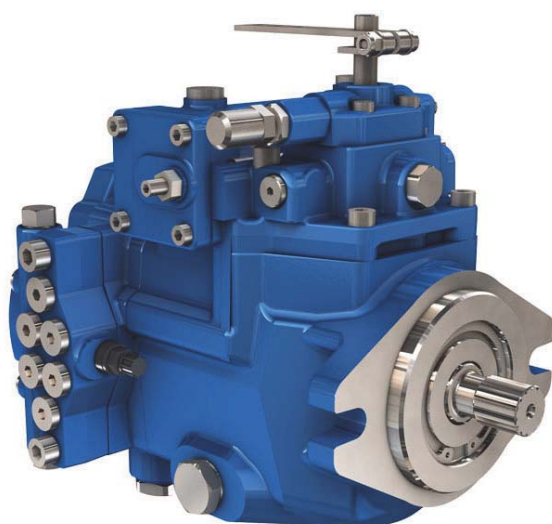


# PM65

VARIABLE DISPLACEMENT PUMP  
CLOSED LOOP CIRCUIT



T E C H N I C A L   C A T A L O G



# OVERVIEW

PM65 is a variable displacement, axial piston pump, with swashplate system, for closed loop hydrostatic transmissions.

It provides a continuously variable flow rate between zero and maximum in forward and reverse direction. Flow rate is proportional to rotation speed and swashplate angle.

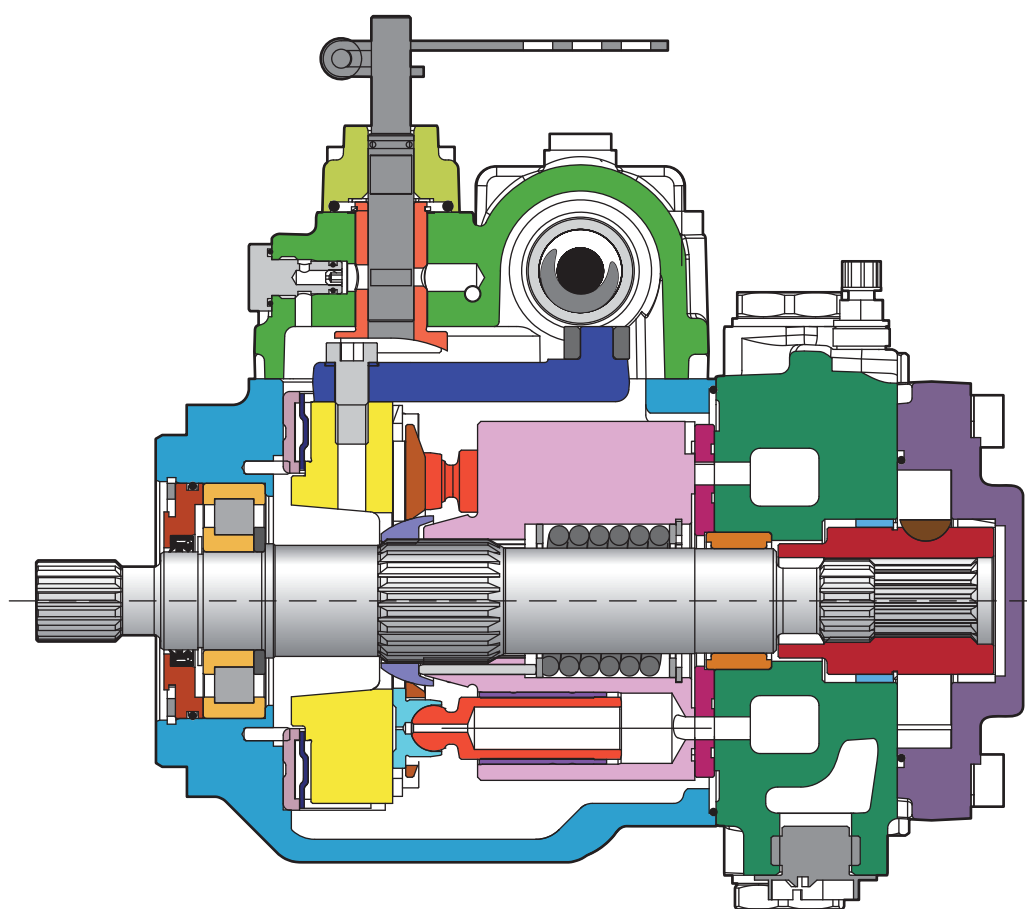
It can feature a charge pump to keep the circuit pressurised. This avoids risk of cavitations and ensures a good performance of the transmission.

It offers several types of control: servo mechanical, servo hydraulic, hydraulic automotive, electrical and electro-proportional.

It is equipped with high pressure relief valves and can be delivered with auxiliary gear pumps.

It is available in single or tandem versions.

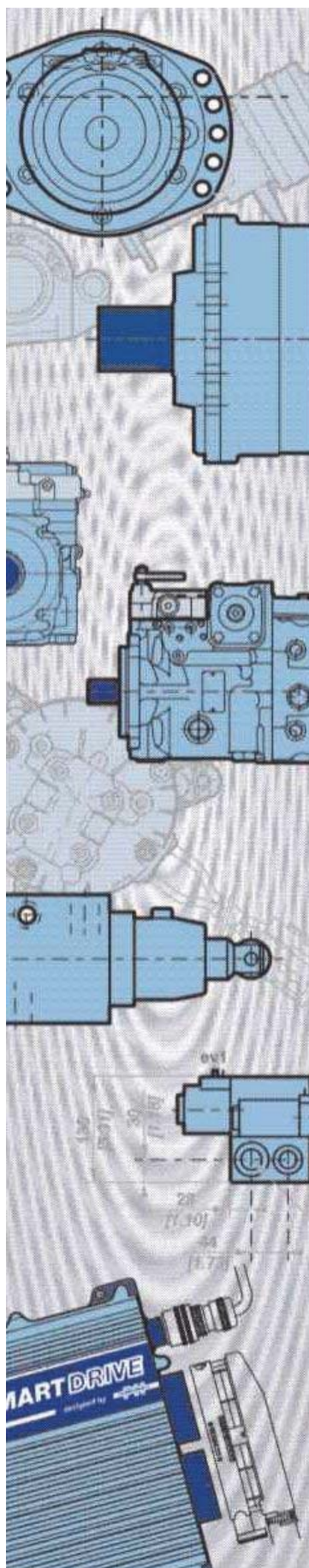
As options, PM65 can be featured with flushing valve, filter on charge pressure line and safety devices to ensure safe operation of the machine.



		PM65-55	PM65-60	PM65-65
Displacement	cm³/rev [in³/rev.]	55,2 [3.37]	60,8 [3.71]	65 [3.97]
Theoretical Flow at rated speed	L/min [GPM]	198,7 [52.49]	218,9 [57.83]	234 [61.82]
Rated speed	rpm	3 600		
Rated pressure	bar [PSI]	250 [3 626]		
Max. Pressure	bar [PSI]	350 [5 076]		
Mounting flange		SAE B, SAE BB		
Controls		Servo mechanical, servo hydraulic, hydraulic automotive, electrical, electro-proportional		
Mass	kg [lb]	30,5 [67.2] with servo control A		
Rotation		Clockwise or Counterclockwise		



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Model  
CodeTechnical  
specificationsOperating  
ParametersSystem design  
Parameters

Features

Controls

Options



## MODEL



1

Displacement cm <sup>3</sup> /rev [in <sup>3</sup> /rev]	
55,2 [3.37]	55
60,8 [3.71]	60
64,7 [3.95]	65

2

Mounting flange and shaft	
SAE BB; splined shaft z = 15, 16/32 D.P.	S4
SAE B; Key shaft Ø 22,22 mm [dia. 0.87 in]	C3
Shaft for secondary tandem pump	T1

3

Control	
Mechanical servo control with feed back	A
Hydraulic servo control	S
Hydraulic automotive control 12V	D12
Hydraulic automotive control 24V	D24
Electrical on-off servo control with return spring without electrovalve	B00
Electrical on-off servo control with return spring and electrovalve 12V	B12
Electrical on-off servo control with return spring and electrovalve 24V	B24
Electrical on-off servo control without electrovalve	C00
Electrical on-off servo control with electrovalve 12V	C12
Electrical on-off servo control with electrovalve 24V	C24
Electro-proportional servo control 12V	P12
Electro-proportional servo control 24V	P24

5

High pressure relief valve setting	
Max. system pressure bar [PSI]	
Without valve (only check valve)	00
150 [2 175]	15
200 [2 900]	20
250 [3 625]	25
300 [4 351]	30
350 [5 076]	35

4

Restrictor mm [in]	
Without restrictor	00
Ø 0,6 [dia. 0.023]	06
Ø 0,7 [dia. 0.027]	07
Ø 0,8 [dia. 0.031]	08
Ø 0,9 [dia. 0.035]	09
Ø 1,0 [dia. 0.039]	10
Ø 1,2 [dia. 0.047]	12

6

Rotation	
Clockwise	R
Counter clockwise	L



# CODE

7 8 9 10 11

**7**  
**Charge relief valve setting bar [PSI]**  
Without charge relief valve 00  
26 [377] 26

**8**  
**Charge pump displacement cm<sup>3</sup>/rev [in<sup>3</sup>/rev]**  
Without charge pump 00  
11 [0.67] 11  
16,9 [1.03] 17

**9**  
**Auxiliary mounting pad**  
Without auxiliary mounting pad S  
SAE A flange; z = 9 A  
SAE A flange; z = 11 E  
SAE B flange; z = 13 B  
SAE BB flange; z = 15 C  
Tandem (without charge pump) T

**10**  
**Gear pump cm<sup>3</sup>/rev [cu.in/rev]**  
Without gear pump 00  
4,0 [0.24] 04  
6,0 [0.37] 06  
8,5 [0.52] 08  
11,0 [0.67] 11  
14 [0.85] 14  
16,5 [1.00] 17  
19,5 [1.19] 20  
22,5 [1.37] 22  
26 [1.59] 26  
  
SAE-A flange  
(if digit 9 = A)

**11**  
**Options**

Without option	00
Filter on pressure line without clogging indicator	F0
Filter on pressure line with clogging indicator	F2
External connections for filter	F3
UNF Threads ports	FU
SAE flange ports	FS
Mechanical inching for control D	IC
Pressure cut-off valve	LP
Neutral position switch for control A	MI
Flushing valve	VS
Finishing coat	PA
Customized identification plate	DP
Anti-stall valve	SD



It is possible to combine several options.  
Consult your Poclain Hydraulics application  
engineer for more information.

Model  
Code

Technical  
Specifications

Operating  
Parameters

System design  
Parameters

Features

Controls

Options



# TECHNICAL SPECIFICATIONS

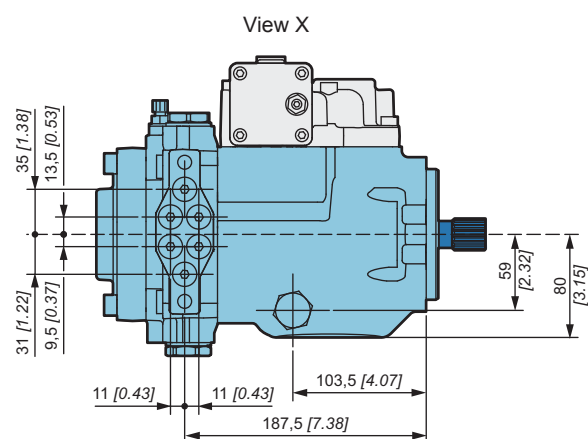
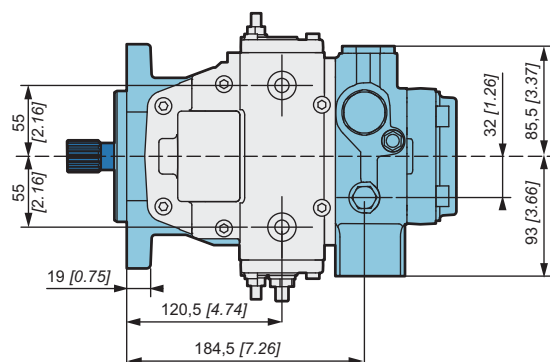
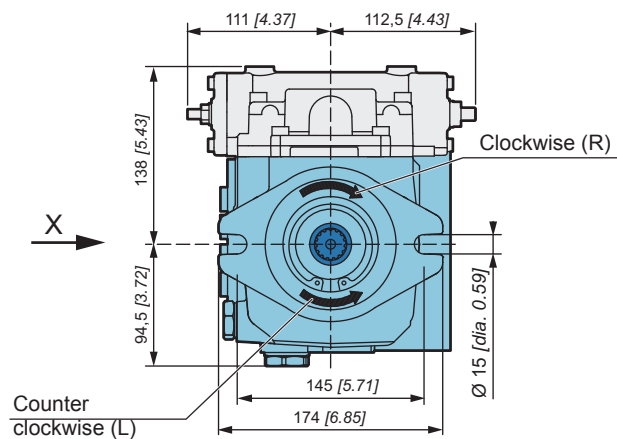
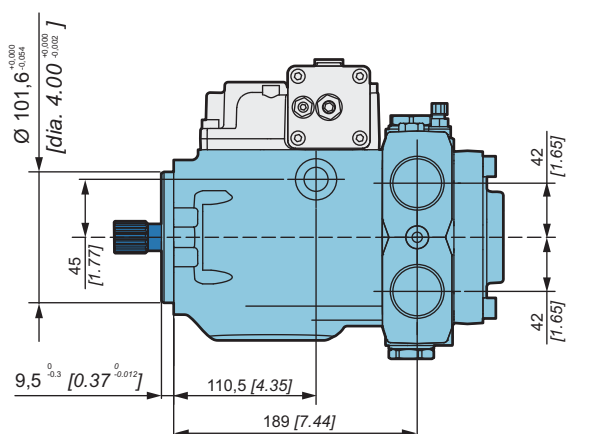
## Features

		PM65-55	PM65-60	PM65-65
<b>Displacement</b>	cm <sup>3</sup> /rev [ <i>in<sup>3</sup>/rev.</i> ]	55,2 [3.37]	60,8 [3.71]	65 [3.97]
<b>Theoretical flow at rated speed (3600 rpm)</b>	L/min [ <i>GPM</i> ]	198,7 [52.49]	218,9 [57.83]	234 [61.82]
<b>Max. Theoretical absorbed power at 320 bar [4 641 PSI]</b>	KW	106,0	116,7	124,8
<b>Theoretical absorbed torque at 100 bar [1 450 PSI]</b>	N.m [ <i>in.lbf</i> ]	87,9 [777]	96,8 [856]	103,5 [916]
<b>Moment of inertia</b>	kg.m <sup>2</sup> [ <i>slug.ft<sup>2</sup></i> ]		0,0054 [0.0038]	
<b>Internal charge pump</b>	cm <sup>3</sup> /rev [ <i>in<sup>3</sup>/rev</i> ]		11 [0.67] or 16,9 [1.03]	
<b>Charge relief valve setting</b>	bar [ <i>PSI</i> ]		From 15 [217.5] to 30 [435]	
<b>High pressure relief setting</b>	bar [ <i>PSI</i> ]		Max. 350 [5 076]	
<b>Mounting flange</b>			SAE B or SAE BB	
<b>Mass</b>	kg [ <i>lb</i> ]		30,5 [67.2] with servo control A	

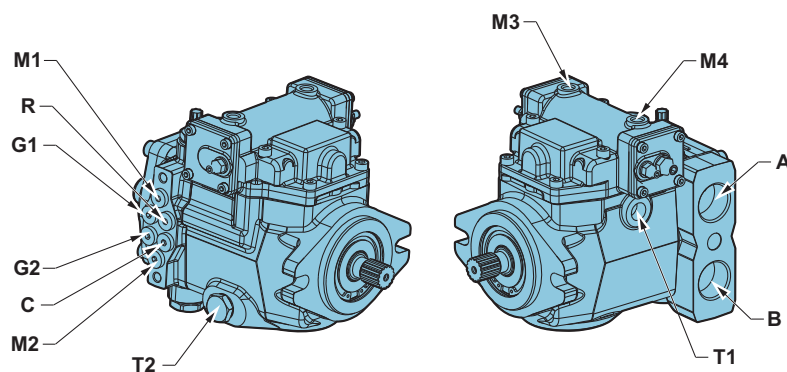


## Main dimensions

PM 65 - SAE BB - splined shaft with servo hydraulic control and without auxiliary mounting pad



## Port characteristics



Port	Function	ISO 1179-1 (BSPP)
A-B	Services	1" 1/4" GAS
G1/G2	Auxiliary	1/4" GAS
M1/M2	A-B pressure	1/4" GAS
M3/M4	Servo control	1/4" GAS
S	Suction	1" GAS
T1/T2	Drain	1/2" GAS
R	Servo pilot pressure	1/4" GAS
C	Case pressure	1/4" GAS

See options FS and FU page 37 for other port sizes.







# OPERATING PARAMETERS

## Operating parameters

			PM65-55	PM65-60	PM65-65
<b>Speed ratings</b>	Minimum			700	
	Max. without load	min <sup>-1</sup> (rpm)		3 600	
	Max. with load			3 400	
<b>System pressure</b>	Rated			250 [3 625]	
	Maximum	bar [PSI]		350 [5 076]	
	Minimum low loop			15 [217]	
<b>Inlet pressure</b>	Mini continuous	bar (abs.)		0,8 [11.6]	
	Mini (cold start)	[PSI abs.]		0,5 [7.2]	
<b>Case pressure</b>	Continuous	bar [PSI]		1,5 [21.7]	
	Maximum (cold start)			2,5 [36.2]	
<b>Charge pressure</b>	Standard version	bar [PSI]		26 [377]	
	Max. charge pressure			30 [435]	
<b>Servo case pressure</b>	Maximum	bar [PSI]		30 [435]	

## Charge pressure

A charge flow is required to maintain a positive pressure in the low pressure loop of a closed loop hydrostatic transmission. Charge pressure ensures proper lubrication and rotating group operation. It is recommended to maintain the charge pressure at a minimum of 15 bar [217 PSI] above case pressure. For more details, refer to charge pump paragraph, page 18.

## Case pressure

Case pressure must be maintained within the limits shown in the table "Operating parameters". Ensure housing is always filled with hydraulic fluid and especially during start-up of the machine.

## Pressure ratings

### Maximum peak pressure

It is the maximum allowable pressure. It is equivalent to the maximum setting of the maximum high pressure relief valve. A self-propelled machine can reach the maximum peak pressure value no more than 1-2% of that work cycle.

### Work cycle

A fundamental factor for ensuring correct hydrostatic transmission sizing is the machine work cycle (pressure-time ratio, seasonality, pressure vs. percentage of time at max. displacement, machine type). Part service life depends on the correct choice in relation to the work cycle.

### Overloads

It is mandatory to protect parts against any possible overloads.

## Speed ratings

The table "Operating parameters" gives minimum and maximum rated speeds. Note that all displacements might operate under different speed limits. Definitions of these speed limits appear below.

**Maximum speed** is the highest operating speed allowed. Over speeding reduces pump life time, can lead to loss of hydrostatic power and braking capacity. Never exceed the maximum speed limit under any operating conditions.

**Nominal speed** is the speed offering the maximal efficiency.

Model  
CodeTechnical  
specificationsOperating  
ParametersSystem design  
Parameters

Features

Controls

Options



## Inlet pressure

Charge pump inlet pressure is key for acceptable pump life and performances. A continuous inlet pressure of not less than 0,8 bar abs. [11.6 PSI abs.] is recommended. A continuous inlet pressure less than 0,5 bar abs. [7.2 PSI abs.] indicates inadequate inlet design or a restricted filter. Pressures less than 0,5 bar abs. [7.2 PSI abs.] can happen at cold start, but should increase with oil temperature.

## Theoretical output

Theoretical output flow is a function of pump displacement and speed. It is relevant to size the rest of the circuit. Theoretical flow does not take into account losses due to leakage or variations in displacement. Refer to performances, page 6, for volumetric and overall efficiencies at various operating speeds and pressures.

## Poclain Hydraulics recommendations for fluid



Poclain hydraulics recommends the use of hydraulic fluids defined by the ISO 15380 and ISO 6743-4 standards. For temperate climates, the following types are recommended.

- HM 46 or HM 68 for fixed installations.
- HV 46 or HV 68 for mobile installations.
- HEES 46 for mobile installations.

These specifications correspond to category 91H of the CETOP standard, parts 1, 2 and 3 of the DIN 51524 standard, and grades VG32, VG 46 and VG68 of the ISO 6743-4 standards.



It is also possible to use ATF, HD, HFB, HFC or HFD type hydraulic fluid upon Poclain Hydraulics specific approval of the components' operating conditions.

Standardized designations for the fluids

- **HM** : Mineral fluids having specific antioxidant, anticorrosion and antiwear properties (HLP equivalent to DIN 51524 parts 1 and 2).
- **HV** : HM mineral fluids providing improved temperature and viscosity properties (DIN 51524 part 3).
- **HEES** : Biodegradable fluids based on organic esters.



**It is also possible to use a fluid that meets the biodegradability criteria and is compatible in the event of accidental food contact. The BIOHYDRAN FG 46 fluid designed by the company Total has undergone testing of its properties and performance on our test benches. Since this type of fluid has not yet been categorized, it is the responsibility of machine manufacturers to validate its compatibility with all of the components used in order to guarantee that the intended functions will be fulfilled and this for the desired life time of all equipment items.**



**For biodegradable fluids, consult your Poclain Hydraulics' application engineer**



**During operation, the temperature of the oil must be between 0°C [32°F] and 80°C [176°F]; the minimum and maximum temperatures may be exceeded momentarily by ± 20°C [± 68°F] for a duration of less than 30 minutes. For all applications outside these limits, please consult with your Poclain Hydraulics' application engineer.**



## Fluid and filtration

The contaminating particles suspended in the hydraulic fluid cause the hydraulic mechanisms moving part wear. On hydraulic pumps, these parts operate with very small dimensional tolerances. In order to reach the part life, it is recommended to use a filter that maintains the hydraulic fluid contamination class at a max. of:

9 according to NAS 1638  
20/18/15 according to ISO 4406:1999

According to the type of application decided for the pump, it is necessary to use filtration elements with a filtration ratio of:

$\beta_{20 \text{ to } 30} \geq 100$

Making sure that this ratio does not worsen together with the increasing of the filter cartridge differential pressure.

If these values cannot be observed, the component life will consequently be reduced and it is recommended to contact the Poclain Hydraulics Customer Service.

### Filters on charge circuit

Filters on the charge circuit (F0-F2) are designed without by-pass. The max. pressure drop on the filtration part must not exceed 2 bar [29 PSI] (3 bar [43.5 PSI] in case of cold starting) at pump full rating. To monitor the pressure drop, it is recommended to use the clogging indicator on the filtration element (F2 option). Contact your Poclain Hydraulics Application engineer, each time the pump is not charged by its internal charge pump.

Filters on charge circuit are mounted on the pump special support.

### Filters assembling

The suction filter is mounted on the suction line. Check that the pressure before the charge pump is 0.8 bar abs. [11.6 PSI abs.], measured on the pump suction port (0.5 bar [7.2 PSI] for cold starting).

## Viscosity range

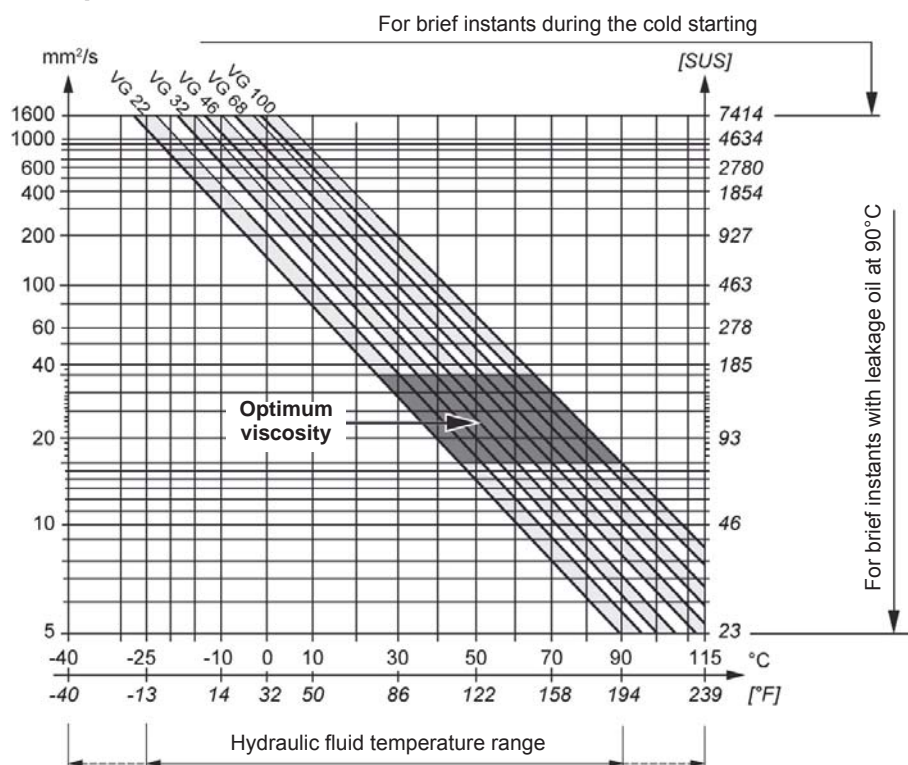
For both max. efficiency and life of the unit, the operative viscosity should be chosen within the optimum range of:

$\sqrt{\text{opt}}$  = optimum operating viscosity from 16 to 36 mm<sup>2</sup>/s [from 74.1 to 166.8 SUS] referred to the closed loop temperature.

**Working conditions:** the following limits of viscosity apply

$\sqrt{\text{min}}$  = 5 mm<sup>2</sup>/s [23 SUS] short-duration at a max. permissible leakage oil temperature of 90° C [194°F]

$\sqrt{\text{max}}$  = 1000 mm<sup>2</sup>/s [4 634 SUS] short-duration, on cold start.



Ensure fluid temperature and viscosity limits are concurrently satisfied.



# SYSTEM DESIGN PARAMETERS



Consult your Poclain Hydraulics application engineer to validate your design parameters before using the pump in your application.

## Sizing equations

The following equations are helpful when sizing hydraulic pumps. Generally, the sizing process is initiated by an evaluation of the machine system to determine the required motor speed and torque to perform the necessary work function. First, the motor is sized to transmit the maximum required torque. The pump is then selected as a flow source to achieve the maximum motor speed.

SI units	Output flow Q	$= \frac{V_g \cdot n \cdot \eta_v}{1000}$	(l/min)
	Input torque M	$= \frac{V_g \cdot \Delta p}{20 \cdot \pi \cdot \eta_m}$	(N.m)
	Input power P	$= \frac{M \cdot n \cdot \pi}{30\,000} = \frac{Q \cdot \Delta p}{600 \cdot \eta_t}$	(kW)
US units	Output flow Q	$= \frac{V_g \cdot n \cdot \eta_v}{231}$	[GPM]
	Input torque M	$= \frac{V_g \cdot \Delta p}{2 \cdot \pi \cdot \eta_m}$	[lbf.in]
	Input power P	$= \frac{M \cdot n \cdot \pi}{198\,000} = \frac{Q \cdot \Delta p}{1714 \cdot \eta_t}$	[hp]

$V_g$  = Displacement per revolution  $\text{cm}^3/\text{tr}$  [ $\text{in}^3/\text{rev}$ ]  
 $\Delta p = p_o - p_i$  (system pressure) bar [PSI]  
 $n$  = Speed  $\text{min}^{-1}$  [rpm]  
 $\eta_v$  = Volumetric efficiency  
 $\eta_m$  = Mechanical efficiency  
 $\eta_t$  = Overall efficiency ( $\eta_v \cdot \eta_m$ )

## Redundant braking system requirement



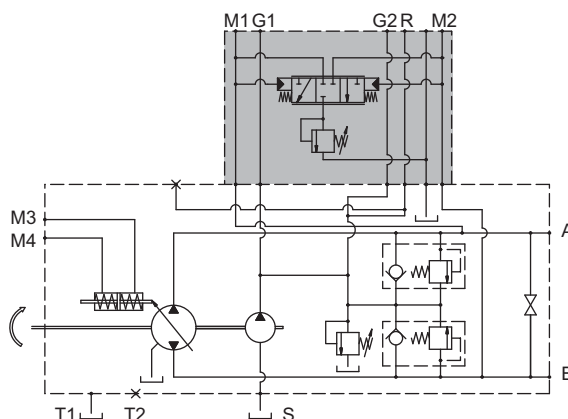
**Unintended vehicle or machine movement hazard.**

The loss of hydrostatic drive line power, in any mode of operation (forward, neutral, or reverse) may cause the system to lose hydrostatic braking capacity. You must provide a braking system, redundant to the hydrostatic transmission, sufficient to stop and hold the vehicle or machine in the event of hydrostatic drive power loss.

## Loop flushing

Closed circuit may require a flushing valve to meet temperature and cleanliness requirements. A flushing valve takes a part of hot fluid flow from the low pressure loop of the system loop for cooling and filtering. Make sure that the charge pump provides adequate flow for the flushing valve flushing and the flushing valve does not cause charge pressure to drop below recommended limits..

See option VS page 41 for more information.





## Reservoir

The reservoir provides clean fluid, dissipates heat, and removes entrained air from the hydraulic fluid. It allows for fluid volume changes associated with fluid expansion and cylinder differential volumes. Minimum reservoir capacity depends on the volume needed to perform these functions. Typically, a capacity of one half the charge pump flow (per minute) is satisfactory for a closed reservoir. Open circuit systems sharing a common reservoir require greater fluid capacity.

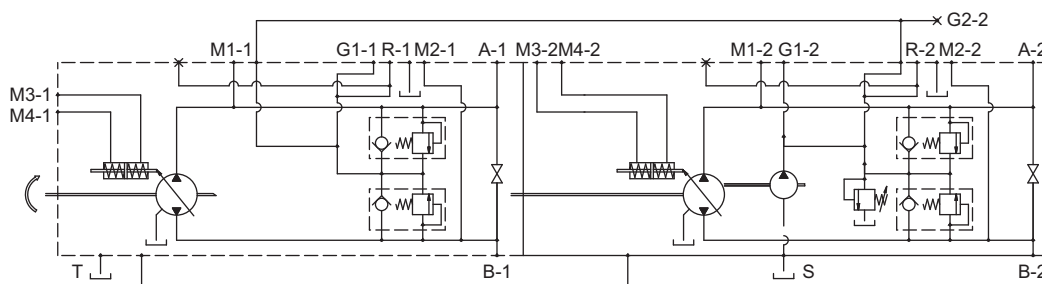
Locate the reservoir outlet (suction line) near the bottom, allowing clearance for settling foreign particles. Use a 100 - 125 µm screen covering the outlet port.

Place the reservoir inlet (return lines) below the lowest expected fluid level, as far away from the outlet as possible.

Use a baffle (or baffles) between the reservoir inlet and outlet ports to promote de-aeration and reduce fluid surging.

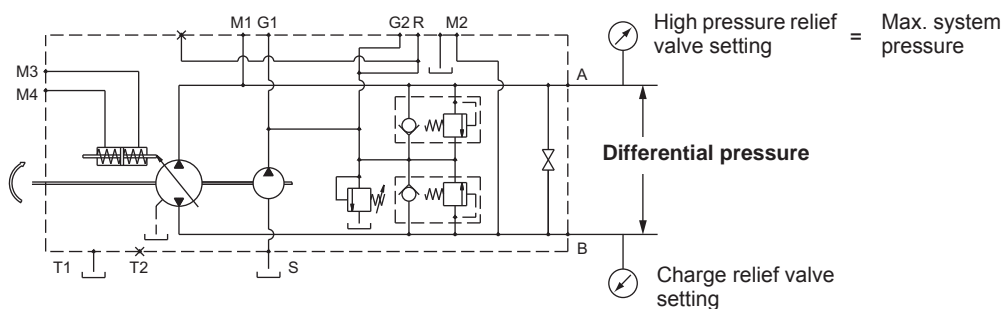
## Case drain usage for tandem pump

On tandem pumps, and to ensure lubrication of both pumps, excess flow from the second pump charge relief valve must be routed into the housing of the first pump.



## Differential pressure

The differential pressure is the High pressure relief valve setting minus Charge relief valve setting.





## Bearing life and external shaft loading

### Bearing life:

Bearing life is a function of speed, pressure, swashplate angle and external loads. Oil type and viscosity impact bearing life.

Bearing life (B <sub>10</sub> hours)	
PM65-55	35 100
PM65-60	26 300
PM65-65	20 100

### Shaft Loads

Normal bearing life in B<sub>10</sub> hours is shown in the above table. Figures have been calculated under the following operating conditions : A continuous differential pressure of 180 bar [2 611 PSI], 1 800 rpm shaft speed, maximum displacement, without any external shaft side load. The data is based on a 50% forward, 50% reverse duty cycle, standard charge pump size, and standard charge pressure.

PM65 pumps are designed with bearings that can accept external radial and thrust loads. The external radial shaft load limits depend on the load position, orientation, and operating conditions of the unit.

The maximum permissible radial load (Re), is based on the maximum external moment (Me), and the distance (L) from the mounting flange to the load. It may be determined using the table and formula below. Thrust (axial) load limits are also shown.

$$Re = Me / L$$

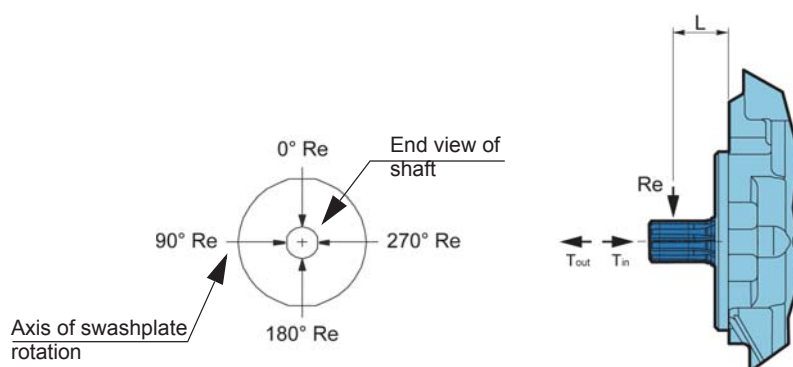
All external shaft loads affect bearing life. In applications with external shaft loads, minimize the impact by positioning the load at 90° or 270° as shown in the figure.

Contact your Poclain Hydraulics representative for an evaluation of unit bearing life if:

- Continuously applied external loads exceed 25 % of the maximum allowable radial load Re.
- The pump swashplate is positioned on one side of center all or most of the time.
- The unit bearing life (B<sub>10</sub>) is critical.

	External moment (Me)	Maximum shaft thrust
	N.m [in.lbf] (Based on shaft deflection)	N [lbf] (at ΔP 180 bar [2 611 PSI] and 3 400 rpm)
PM65-55	108 [956]	920 [206.8]
PM65-60	93 [823]	810 [182.1]
PM65-65	78 [690]	710 [159.6]

### Radial and thrust load position



For an accurate calculation, consult your Poclain Hydraulics application engineer.



## Hydraulic unit life

Hydraulic unit life is the life expectancy of the hydraulic components. It depends on speed and system pressure even if , system pressure is the dominant operating variable. High pressure, generated by high load, reduces hydraulic unit life.

Design the hydraulic system according to the expected machine duty cycle. Take in consideration the expected percentages of time at various loads and speeds. Ask your Poclain Hydraulics representative to calculate an appropriate pressure based your hydraulic system design. If duty cycle data is not available, input power and pump displacement are used to calculate system pressure.

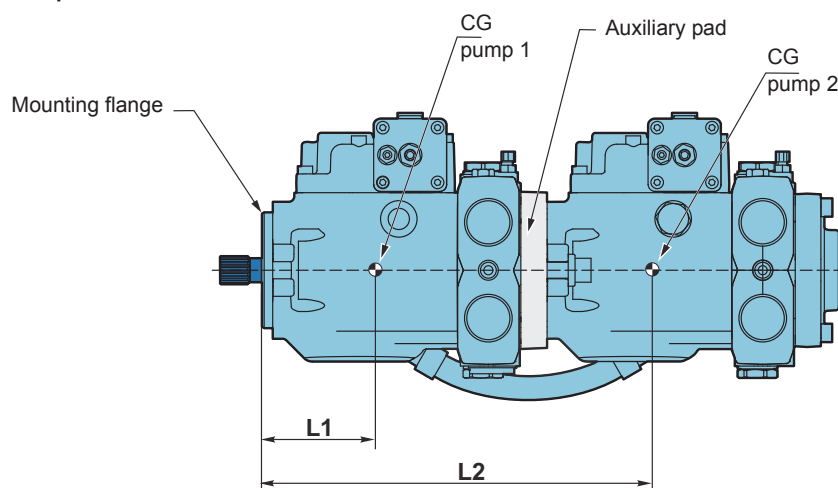
All pressure limits are differential pressures (referenced to charge pressure) , taking a normal charge pressure in consideration.

PM65 pumps will meet satisfactory life expectancy if applied within the parameters specified in this technical documentation. For more detailed information on hydraulic unit life see Operating Parameters in page 9.

## Mounting flange loads

Adding tandem mounted pumps, and/or tandem auxillary pump(s), subjecting pumps to shock loads may generate excessive loads on the front mounting flange. The overhung load moment for multiple pump mounting can be estimated as shown in the figure bellow

### Overhung load example



### Estimating overhung load moments

W = Weight of pump (kg)

L = Distance from mounting flange to pump center of gravity (CG)

$$M_R = G_R (W_1 L_1 + W_2 L_2 + \dots + W_n L_n)$$

$$M_S = G_S (W_1 L_1 + W_2 L_2 + \dots + W_n L_n)$$

Where:

$M_R$  = Rated load moment (N.m)

$M_S$  = Shock load moment (N.m)

$G_R^*$  = Rated (vibratory) acceleration (G's) (m/sec<sup>2</sup>)

$G_S^*$  = Maximum shock acceleration (G's) (m/sec<sup>2</sup>)

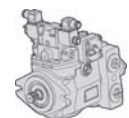
\*Calculations will be carried out by multiplying the gravity ( $g = 9.81 \text{ m/sec}^2$ ) with a given factor. This factor depends on the application.

Allowable overhung load moment are shown in the above table. Exceeding these values requires additional pump support.

	Rated moment (MR) N.m [in.lbf]	Shock load moment (MS) N.m [in.lbf]
PM65-55	900 [7 966]	2 000 [17 701]
PM65-60	900 [7 966]	2 000 [17 701]
PM65-65	900 [7 966]	2 000 [17 701]



For an accurate calculation, consult your Poclain Hydraulics application engineer.



# FEATURES

## High pressure relief valve

The High pressure relief valves maintain circuit pressure in the proper range. The check valves allow charge flow to replenish the low pressure loop of the circuit. The high pressure relief valves ensure a high pressure protection of the high pressure loop of the circuit.

High pressure relief valves are available in a range of settings.

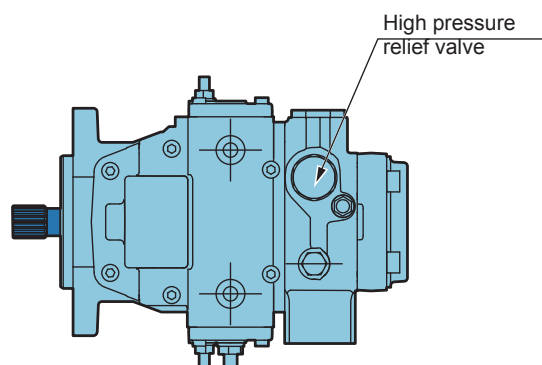
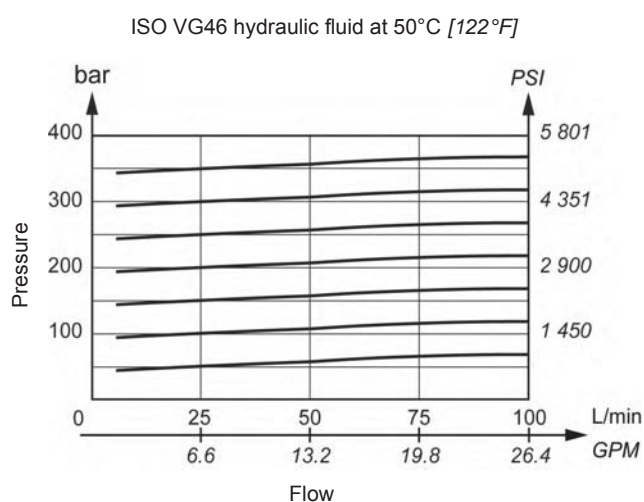
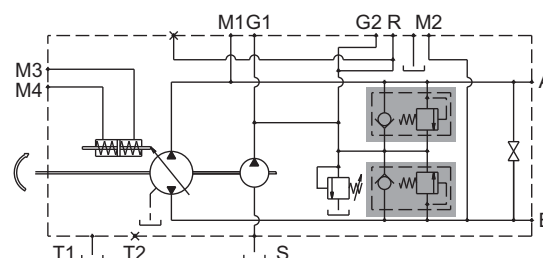
When high pressure relief valves are not desired, pumps is equipped with charge circuit check valves only.



High pressure relief valves are intended for transient overpressure protection and are not intended for continuous pressure control. Flow over relief valves for extended periods of time may result in severe heat build up. High flows over relief valves may result in pressure levels exceeding the nominal valve setting and potential damage to system components.



High pressure relief valve	Available setting bar [PSI]	
Without	-	00
	150 [2 175]	15
	200 [2 900]	20
With	250 [3 625]	25
	300 [4 351]	30
	350 [5 076]	35



The high pressure relief valve setting is not the differential pressure between A and B ports (see page 13).





Charge relief valve

The charge pressure relief valve provides a relief outlet for charge circuit. This valve is used to set the charge pressure of the circuit. Flow through the valve is ported to case.

The nominal charge relief setting is referenced to case pressure.



Incorrect charge pressure settings may result in the inability to build required system pressure and/or inadequate loop flushing flows. Ensure correct charge pressure under all conditions of operation to maintain pump control performance.

P

M

6

5

1

2

3

4

5

6

7

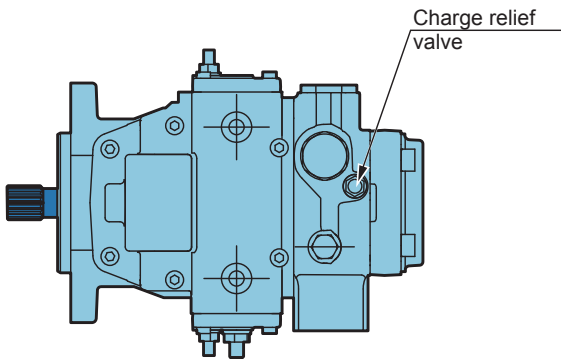
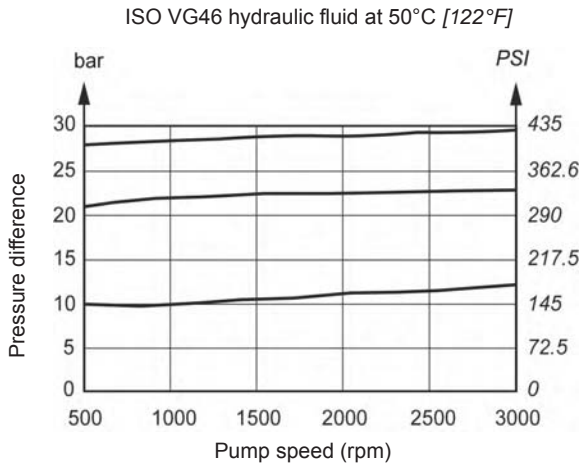
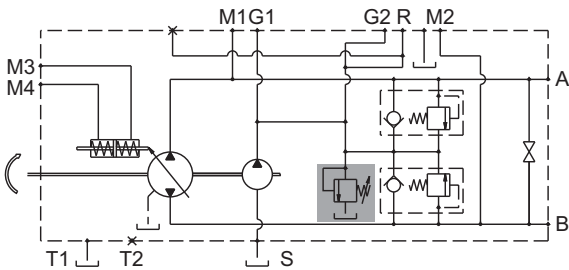
8

9

10

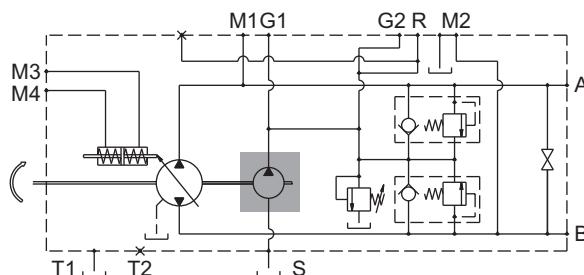
11

Charge relief valve	Available setting bar [PSI]	
Without	-	00
With	26 [377]	26





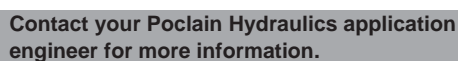
Unusual application conditions may require a more detailed review of charge pump sizing. Charge pressure must be maintained at a specified level under all operating conditions to prevent damage to the transmission. Poclain Hydraulics recommends testing under actual operating conditions to verify this.



In most applications a general guideline is that the charge pump displacement should be at least 20% of the main pump displacement.

P	M	6	5											
				1	2	3	4	5	6	7	8	9	10	11

Charge pump	Displacement cm <sup>3</sup> /rev [ <i>in<sup>3</sup>/rev</i> ]	Rated speed (rpm)	
Without	-	-	00
With	11 [0.67]	3600	11
	16,9 [1.03]	3600	17





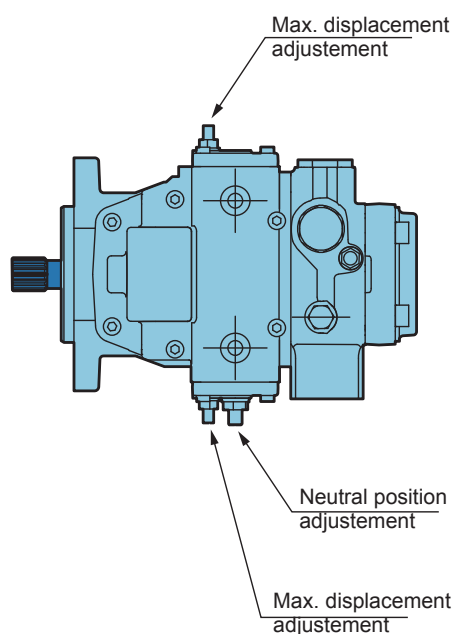
## Displacement limiters

PM65 are designed with mechanical displacement (stroke) limiters. You can limit maximum displacement of the pump to a certain per-cent of its maximum displacement to near zero in both direction.

The displacement limiters are located on the both sides of the servo piston and are adjustable by screw.

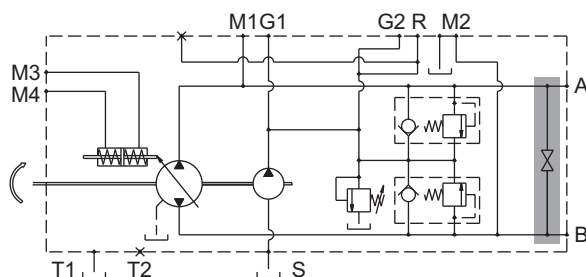


Take care in adjusting displacement limiters to avoid an undesirable condition of output flow or speed. Retorque the sealing lock nut after every adjustment to prevent an unexpected change in output conditions and to prevent external leakage during pump operation.



## By-pass

PM65 features a by-pass function. By-passing Port A and Port B is achieved by unscrewing a screw located on the cover. The by-pass connect the ports A-B and must be use only in emergency case and only for short movement.



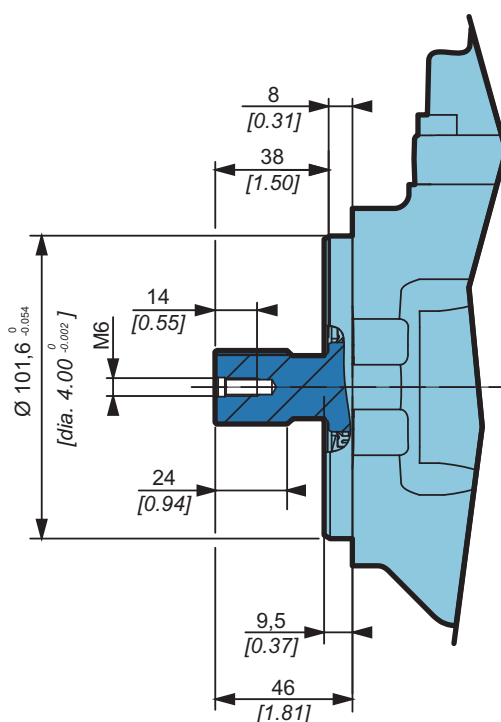
To avoid leakage, do NOT exceed two turns of the screw.



By-pass valve is intended for moving a machine for very short distances at very slow speeds. It is NOT intended as tow valve.

**Mounting flange and shafts****SAE BB - Splined shaft**

15 teeth; Max. torque: 360 Nm [3 186 in.lbf]



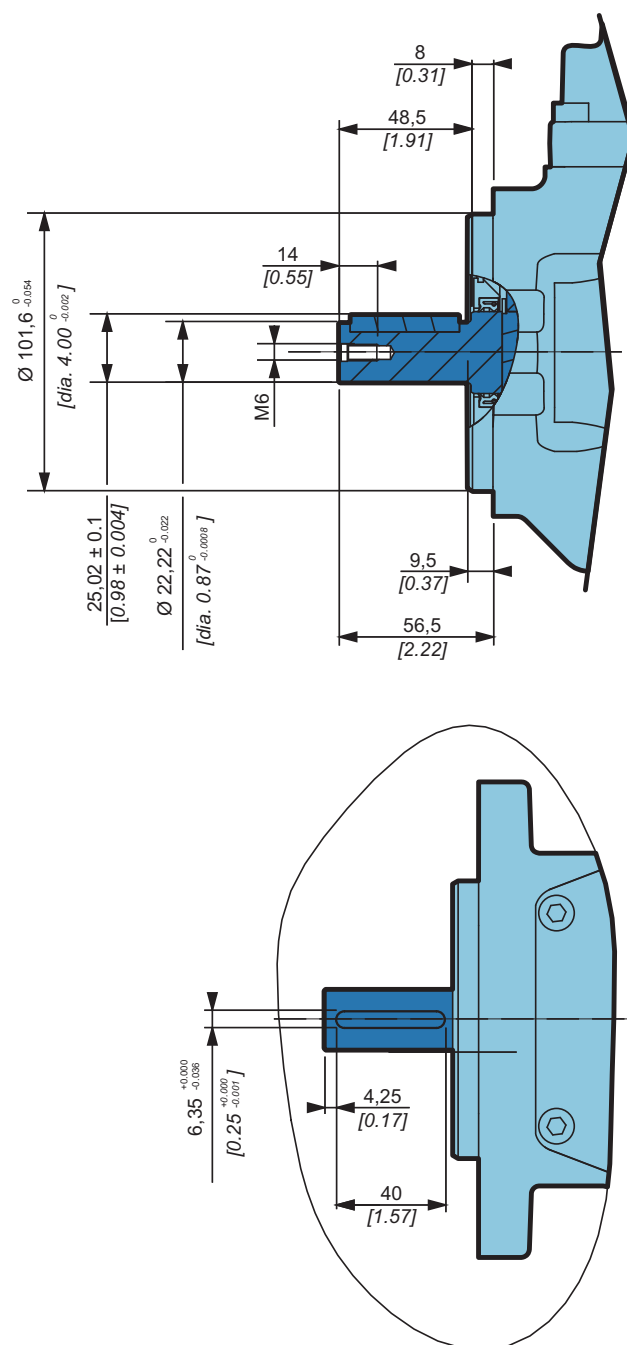
Splined ANSI B92.1a-1976  
Pitch 16/32" DP  
Pressure angle 30°  
Tolerance class: 5



SAE B - Key shaft



Ø 22,22 mm [0.87 in]; Max. torque: 220 Nm [1947 in.lbf]

Model  
CodeTechnical  
specificationsOperating  
ParametersSystem design  
Parameters

Features

Controls

Options



## Auxiliary mounting pad

### SAE A flanges



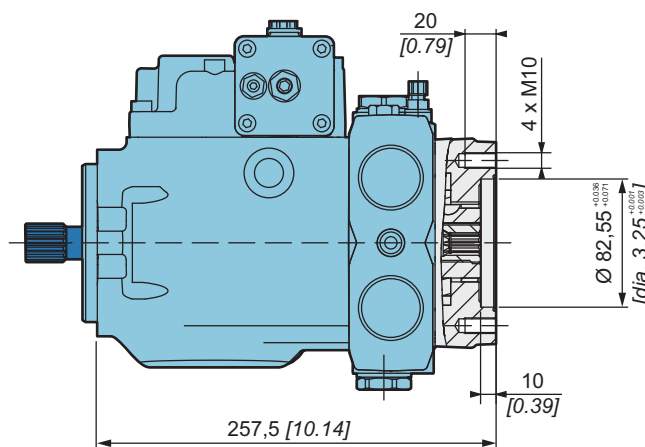
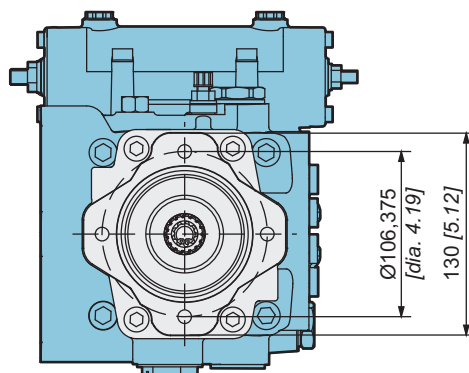
Flange type	Number of teeth	Pitch	Max. torque N.m [in.lbf]	
SAE A	9	5/8" pitch 16/32" DP	80 [708]	A
	11	3/4" pitch 16/32" DP	160 [1 416]	E

**00** Without charge pump

**11** With charge pump: 11,0 cm<sup>3</sup>/rev [0.67 in<sup>3</sup>/rev]

**17** With charge pump: 16,9 cm<sup>3</sup>/rev [1.03 in<sup>3</sup>/rev]

Splined ANSI B92.1a-1996  
5/8" Pitch 16/32" DP  
Pressure angle 30°  
Tolerance class: 5



Do not rotate the thru shaft cover.



## SAE-B and SAE-BB flanges

P	M	6	5	1	2	3	4	5	6	7	8	9	10	11
---	---	---	---	---	---	---	---	---	---	---	---	---	----	----

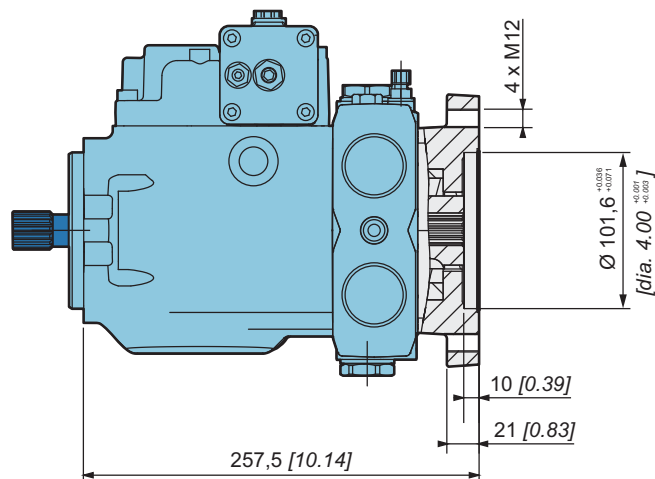
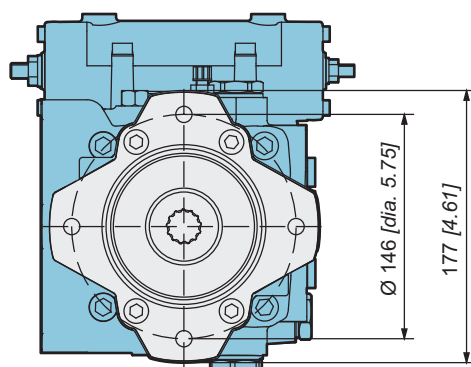
Flange type	Number of teeth	Pitch	Max. torque N.m [in.lbf]	
SAE B	13	7/8" pitch 16/32" DP	230 [2 036]	B
SAE BB	15	1" pitch 16/32" DP	360 [3 186]	C

00 Without charge pump

11 With charge pump: 11,0 cm<sup>3</sup>/rev [0.67 in<sup>3</sup>/rev]

17 With charge pump: 16,9 cm<sup>3</sup>/rev [1.03 in<sup>3</sup>/rev]

Splined ANSI B92.1a-1996  
5/8" Pitch 16/32" DP  
Pressure angle 30°  
Tolerance class: 5



Do not rotate the thru shaft cover.

Model Code

Technical specifications

Operating Parameters

System design Parameters

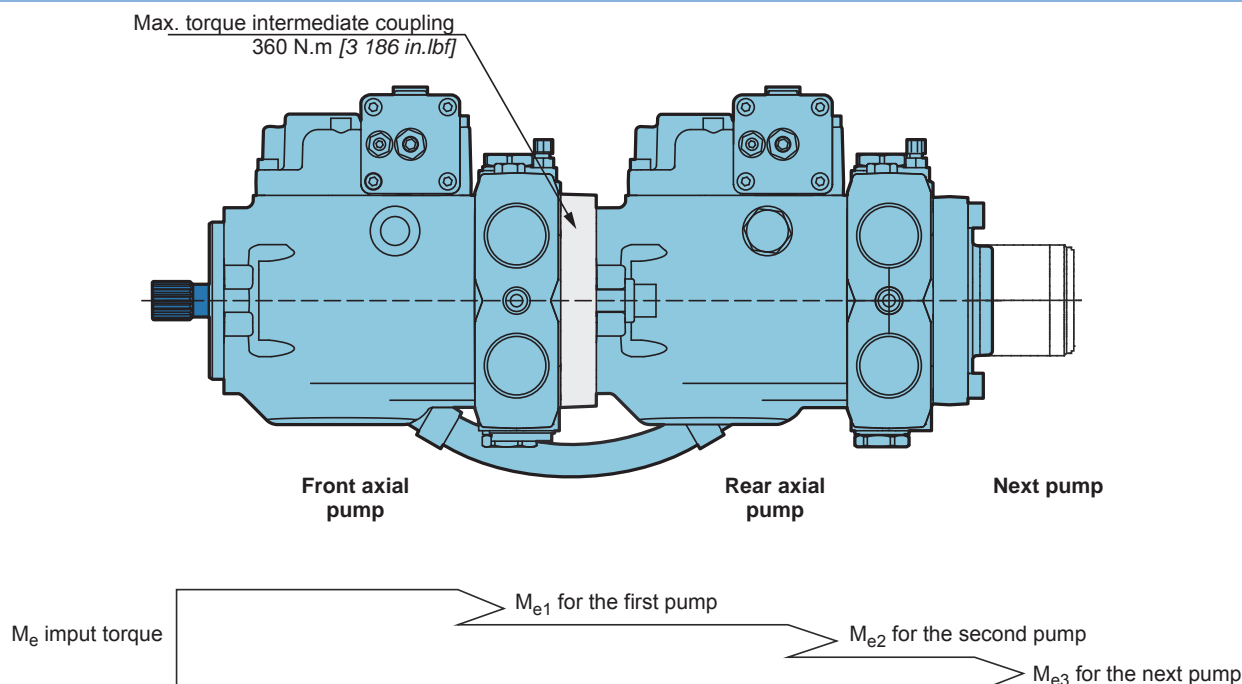
Features

Controls

Options



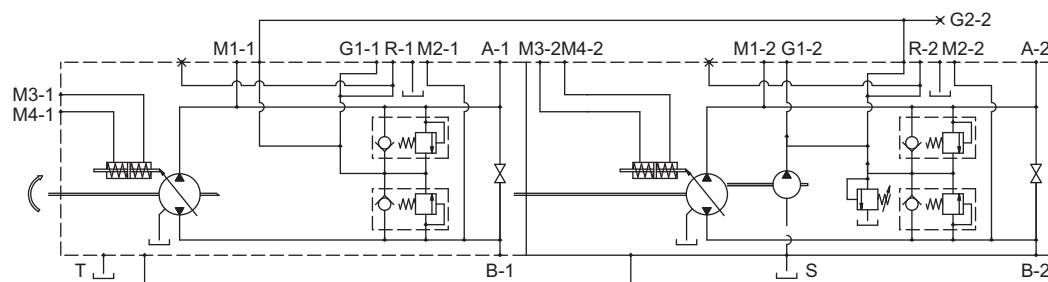
## Tandem pumps



Torque required by gear pumps is additive.  
Ensure requirements don't exceed shaft torque ratings.

Front axial pump	<div><div>P</div><div>M</div><div>6</div><div>5</div></div>	<div>1</div> <div><div>2</div><div>S4</div></div> <div>3</div> <div>4</div> <div>5</div> <div>6</div> <div>7</div> <div>8</div> <div>9</div> <div>10</div> <div>11</div>					
Rear axial pump	<div><div>P</div><div>M</div><div>6</div><div>5</div></div>	<div>1</div> <div><div>2</div><div></div></div> <div>3</div> <div>4</div> <div>5</div> <div>6</div> <div>7</div> <div>8</div> <div>9</div> <div>10</div> <div>11</div>					
Number of charge pump in the tandem	Axial pump	Mounting flange and shaft	Charge pump	Auxiliary mounting flange			
0 charge pump	Front	SAE BB; 15 teeth	S4	Without	00	Tandem fitting	T
	Rear	Shaft for secondary tandem pump	T1	Without	00	Without fitting	S
						SAE A; 9 teeth	A
						SAE A; 11 teeth	E
						SAE B; 13 teeth	B
1 charge pump	Front	SAE BB; 15 teeth	S4	Without	00	Tandem fitting	T
	Rear	Shaft for secondary tandem pump	T1	With	11 or 17	Without fitting	S
						SAE A; 9 teeth	A
						SAE A; 11 teeth	E
						SAE B; 13 teeth	B
2 charge pumps	Front	SAE BB; 15 teeth	S4	With	11 or 17	SAE BB; 15 teeth	C
	Rear	SAE BB; 15 teeth	S4	With	11 or 17	Without fitting	S
						SAE A; 9 teeth	A
						SAE A; 11 teeth	E
						SAE B; 13 teeth	B





Ports T and G of the first pump must be connected with ports T and G of the second pump.

## Gear pumps



Auxiliary mounting flange

Gear pump

	Displacement cm <sup>3</sup> /rev [cu.in/rev]	Pressure			Dimension			Mass Kg [lb]	Efficiency %
		Continuous max. pressure	Max. intermittent pressure	Max. peak pressure	A	B	C		
		bar [PSI]	bar [PSI]	bar [PSI]	mm [in]	mm [in]	mm [in]		
04	4,0 [0.24]	250 [3 625]	270 [3 915]	290 [4 205]	93 [3.66]			2,30 [5.07]	
06	6,0 [0.37]	250 [3 625]	270 [3 915]	290 [4 205]	96,3 [3.79]			2,45 [5.40]	
08	8,5 [0.52]	250 [3 625]	270 [3 915]	290 [4 205]	100,5 [3.96]			2,60 [5.73]	
11	11,0 [0.67]	250 [3 625]	270 [3 915]	290 [4 205]	104,6 [4.12]			2,70 [5.95]	
14	14,0 [0.85]	250 [3 625]	270 [3 915]	290 [4 205]	109,6 [4.31]	130,4 [5.13]	95 [3.74]	2,80 [6.17]	95*
17	16,5 [1.00]	230 [3 335]	240 [3 480]	250 [3 625]	113,8 [4.48]			2,95 [6.51]	
20	19,5 [1.19]	210 [3 045]	220 [3 190]	230 [3 335]	118,8 [4.68]			3,10 [6.84]	
22	22,5 [1.37]	190 [2 755]	200 [2 900]	210 [3 045]	123,8 [4.87]			3,25 [7.17]	
26	26 [1.59]	170 [2 465]	180 [2 610]	190 [2 755]	129,6 [5.10]			3,40 [7.50]	

\* Value collected during the testing at 1500 rpm



Gear pumps are always delivered flanged on the axial pump. They can not be sold alone.



# CONTROLS

## Mechanical servo control with feed back



The variation in pump displacement is obtained by rotating the drive lever situated on the servo control. An internal channel, linked to the charge pump, feeds a hydraulic servo valve which supplies oil into the cylinder which is in turn linked to the pump swashplate. The maximum rotation of the lever, with respect to 0 is  $42,5^\circ$  for both rotation directions; thus permitting the optimum control of the displacement.

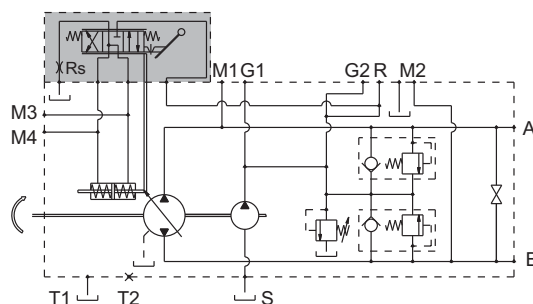
At every lever angle there is a corresponding pump displacement.

On the (T) return "arm" of the rotating distributor a restrictor (Rs) is mounted which regulates the servo control shifting speed, thus avoiding sudden accelerations and stoppages.

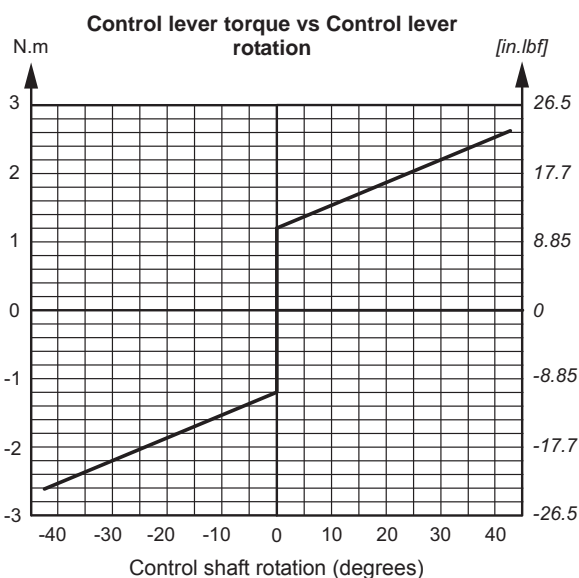
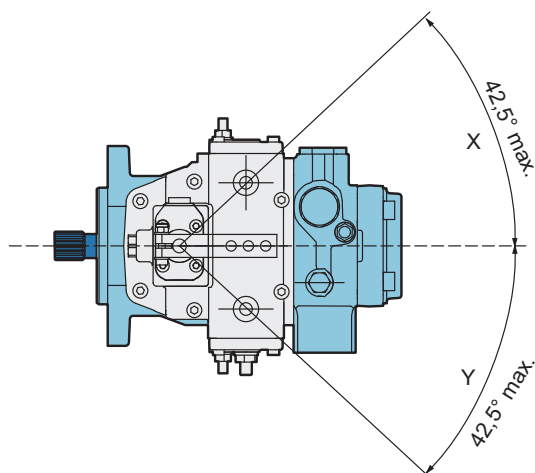
The effort of moving the lever is independent of the pressure and rpm.

### Flow rate determination

Rotation	Control	Output	Input
Clockwise (R)	X	A	B
	Y	B	A
Counter clockwise (L)	X	B	A
	Y	A	B



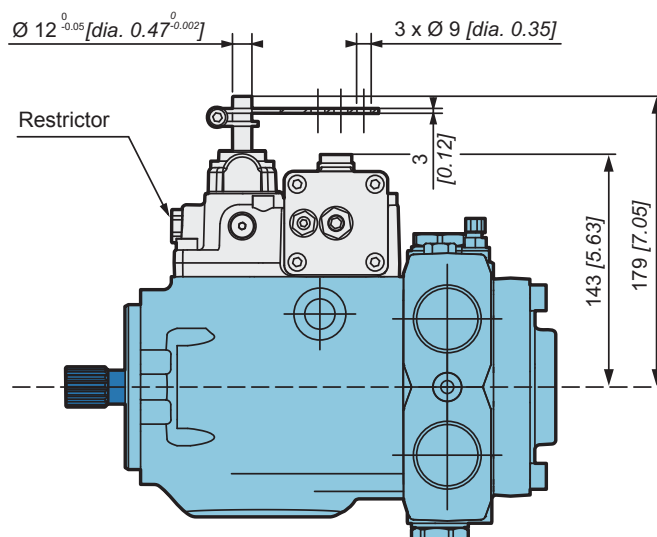
To prevent damage to the control A a positive mechanical stop must be provided for the control A linkage.



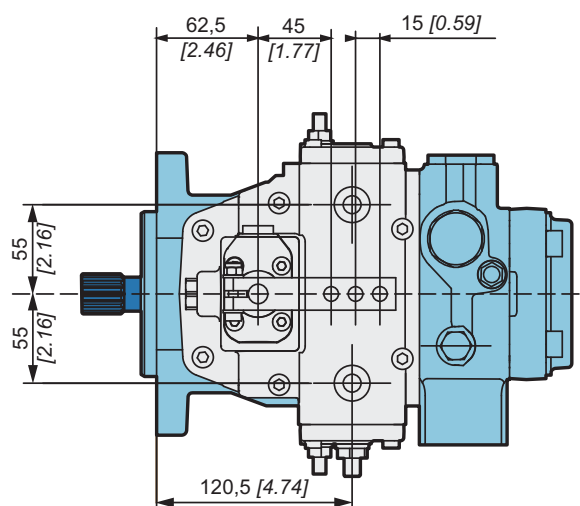
The spring return feature in the control unit is not a safety device.



## Dimensions



See page 7 for other dimensions and port characteristics.



See option MI page 40 to add neutral position switch.

Model  
Code

Technical  
specifications

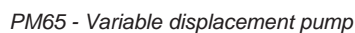
Operating  
Parameters

System design  
Parameters

Features

Controls

Options



## Hydraulic servo control

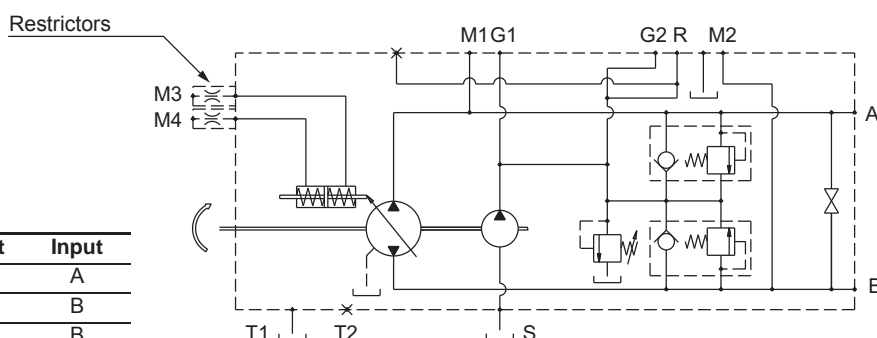


The variation in pump displacement is obtained by adjusting the pressure on the M3 and M4 servo control connections by means of a hydraulic proportional joystick (containing pressure reduction valves).

The joystick supply can be obtained by taking pressure from the auxiliary pump (G connection).

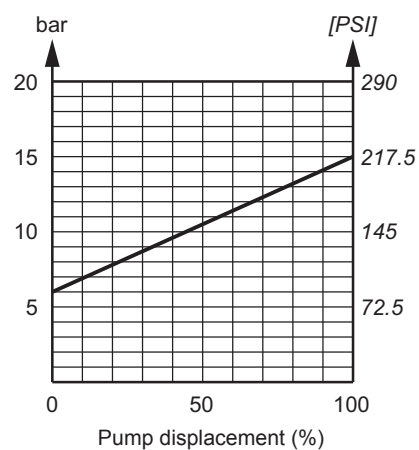
The servo control response time can be adjusted by inserting a restrictor on the joystick supply line (from 0,6 to 1,2 mm [from 0.02 to 0.05 in]).

The servo control operation curve in both control directions goes from 6 to 15 bar [from 87 to 217 PSI]. The adjustment curve of the hydraulic control system has to be wider (from 5 to 16 bar [from 72.5 to 232 PSI]).



### Flow rate determination

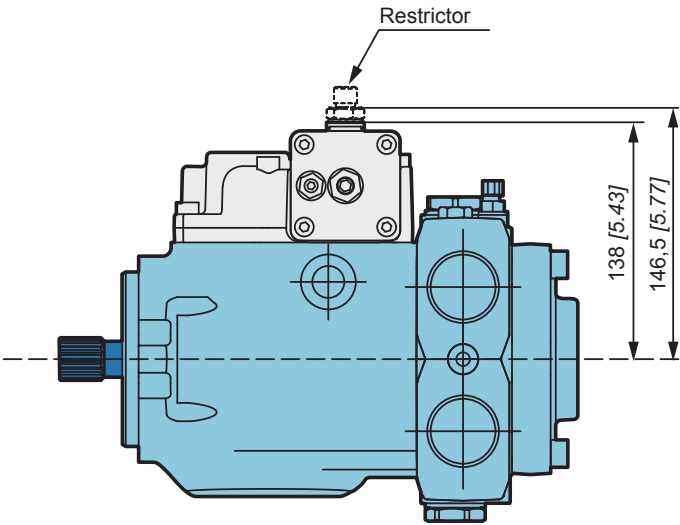
Rotation	Pressure	Output	Input
Clockwise (R)	M3	B	A
	M4	A	B
Counter clockwise (L)	M3	A	B
	M4	B	A



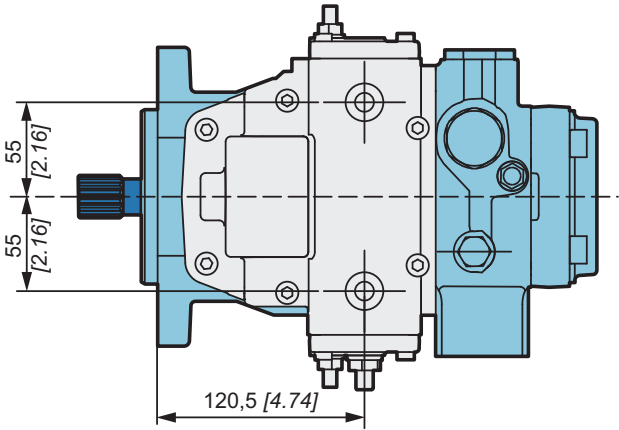
**The spring return feature in the control unit is not a safety device.**



Dimensions



See page 7 for other dimensions and port characteristics.



Model Code
Technical specifications
Operating Parameters
System design Parameters
Features
Controls
Options



## Electrical on-off servo control

### Control with return spring

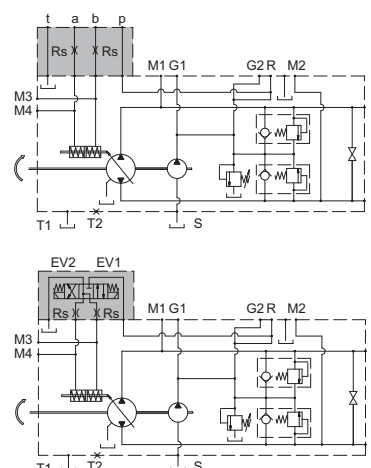


The reaching of the maximum displacement in a time defined by the restrictors (Rs) which are positioned between the electrovalve and the (T) drain is obtained by the continuous starting of an ON-OFF electrovalve with an open-circuit CETOP 3 connection.

If the electro-valve motion is stopped, the pump goes back to "0" position thanks to the servo control springs.

The pump can be supplied either without electrovalve (B00) or with electrovalve (B12, B24).

Supply voltage	
without	B00
12V	B12
24V	B24



### Control without return spring



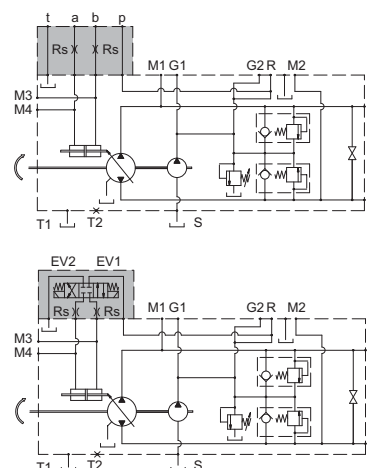
The variation in pump displacement is obtained by the energizing of an ON-OFF electrovalve with a closed center CETOP 3 connection.

The displacement reached is in relation to the starting time of the electro-valve and to the diameter of the restrictors (Rs) which are placed between the electrovalve and the drain (T).

The pump can be supplied either without electrovalve (C00) or with electrovalve (C12, C24).

The servo control is without springs and the setting of the pump at a certain displacement is guaranteed by the closed center of the electrovalve.

Supply voltage	
without	C00
12V	C12
24V	C24



### Flow rate determination

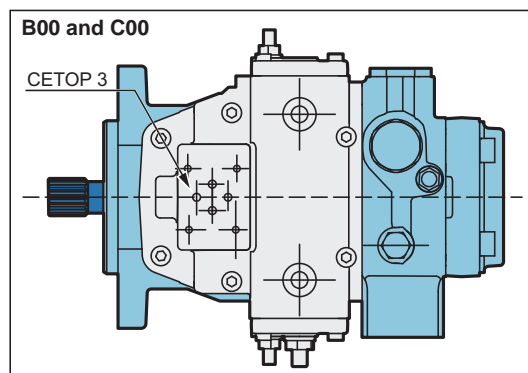
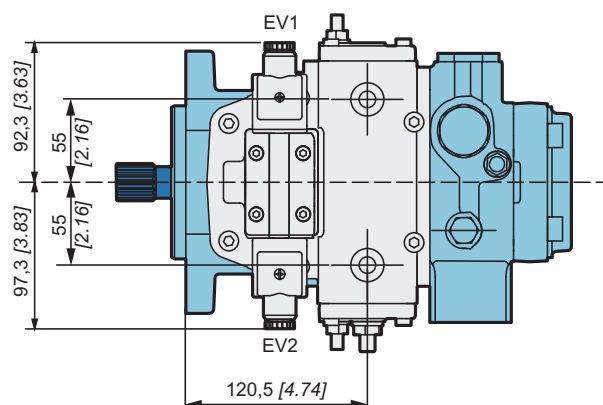
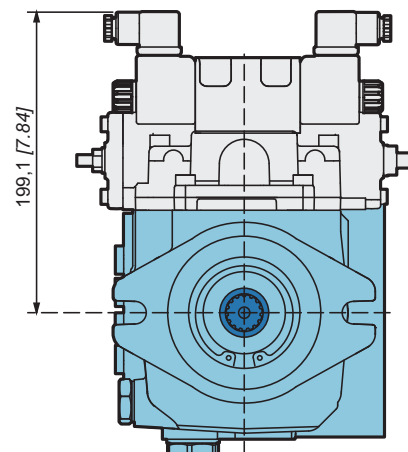
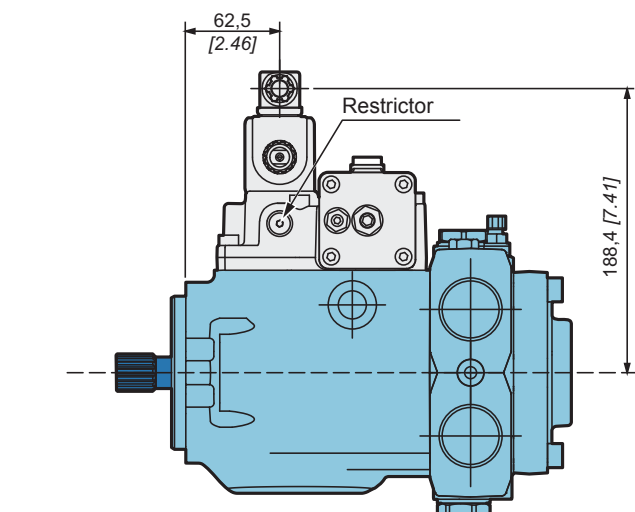
Rotation	Control	Pressure	Output	Input
Clockwise (R)	EV1	A	A	B
	EV2	B	B	A
Counter clockwise (L)	EV1	A	B	A
	EV2	B	A	B



The spring return feature in the control unit is not a safety device.



## Dimensions



Type of connector: DIN 43650

See page 7 for other dimensions and port characteristics.

Model  
Code

Technical  
specifications

Operating  
Parameters

System design  
Parameters

Features

Controls

Options



## Electrico-proportional servo control



By means of a potentiometer and a control card, a voltage signal is applied to the proportional electrovalve coils which adjust the pressure of the servo control connected to the pump swashplate.

At every position of the potentiometer lever there is a corresponding swashplate position.

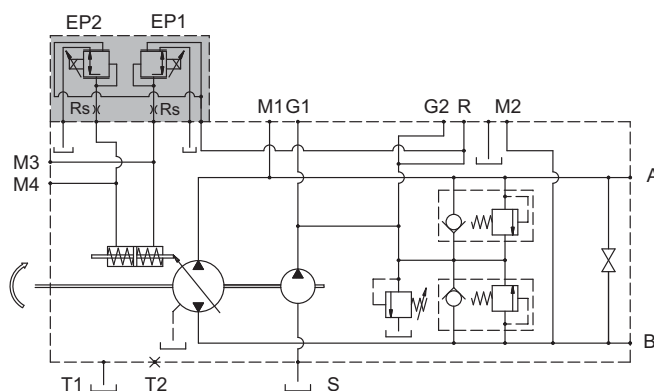
The flow rate direction depends on which coil is excited.

The adjustment speed can be controlled by ramps installed on the card and by restrictors (Rs) positioned between the electrovalve and the servo control.

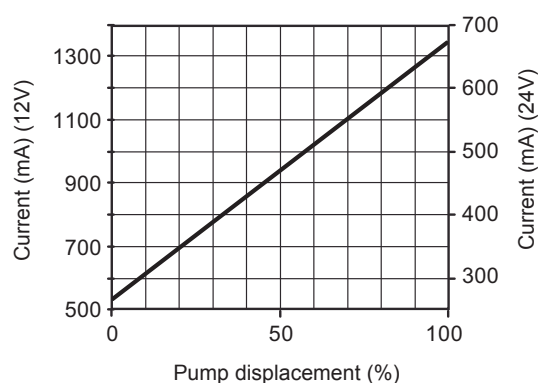
Supply voltage	
12V	P12
24V	P24

### Flow rate determination

Rotation	Pressure	Output	Input
Clockwise (R)	EP1	B	A
	EP2	A	B
Counter clockwise (L)	EP1	A	B
	EP2	B	A



The current must not exceed 1500 mA under 12V and 800 mA under 24V.

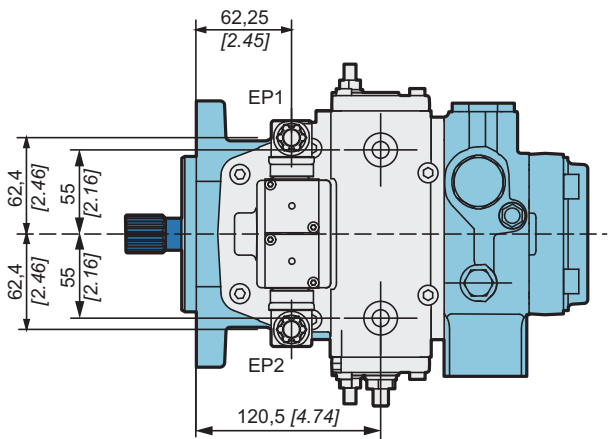
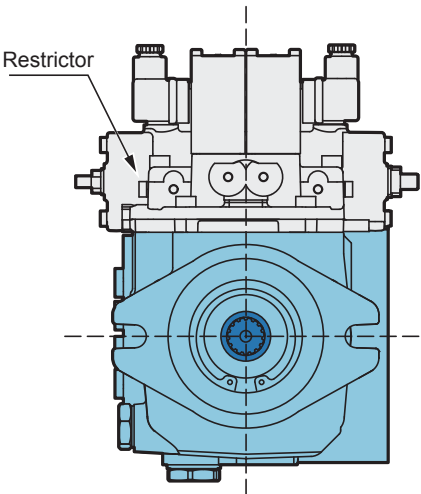
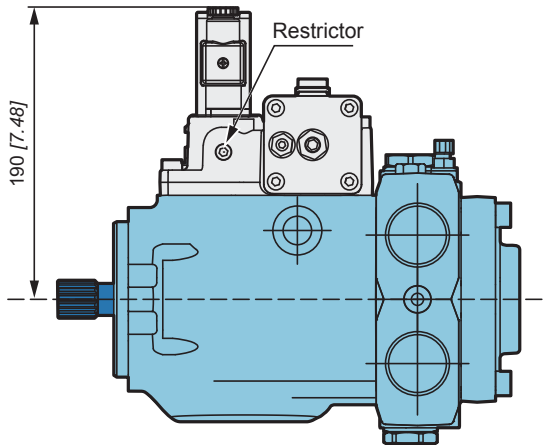


The spring return feature in the control unit is not a safety device.





Dimensions



See page 7 for other dimensions and port characteristics.

Type of connector: DIN 43650

Model Code
Technical specifications
Operating Parameters
System design Parameters
Features
Controls
Options



## Hydraulic automotive control



In relation to the input rotation rate, the pump swashplate positioning cylinder is actuated by the pressure of the adjustment valve and a 4/3 electro-hydraulic valve, progressively positioning the swashplate. This provides a continuously variable pump displacement. The direction of the supplied flow is determined by which of the two solenoids is energized.

The pilot pressure increases proportionally to the rotation rate. A pump displacement increase corresponds to the higher pilot pressure.

In case the prime mover is overloaded, the rotation rate decreases and the pilot pressure is reduced causing a pump displacement reduction with a corresponding drop in absorbed power.

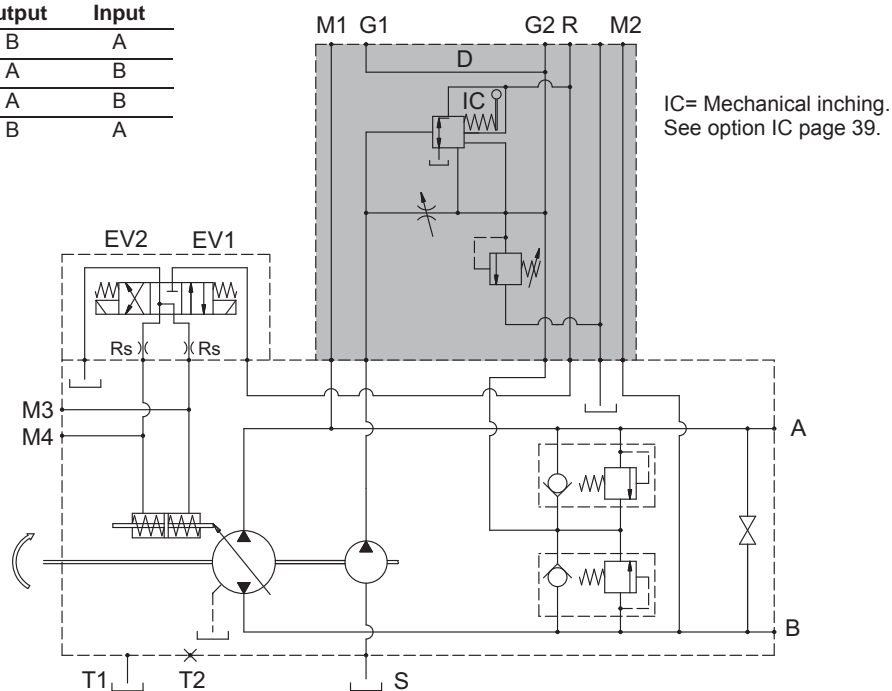
An "Inching" lever (option IC) is available to reduce the pilot pressure independently of the pump rotation speed.

**Supply voltage**

12V	D12
24V	D24

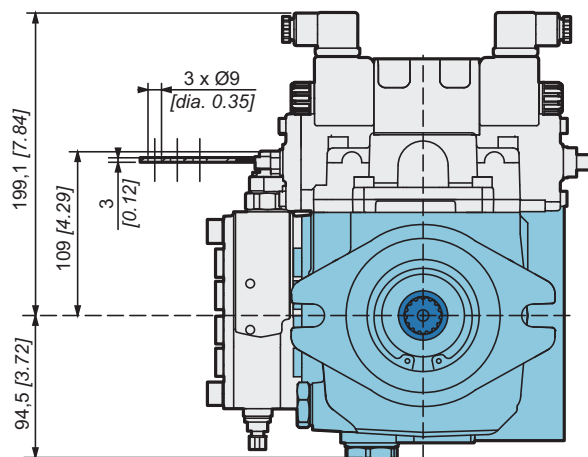
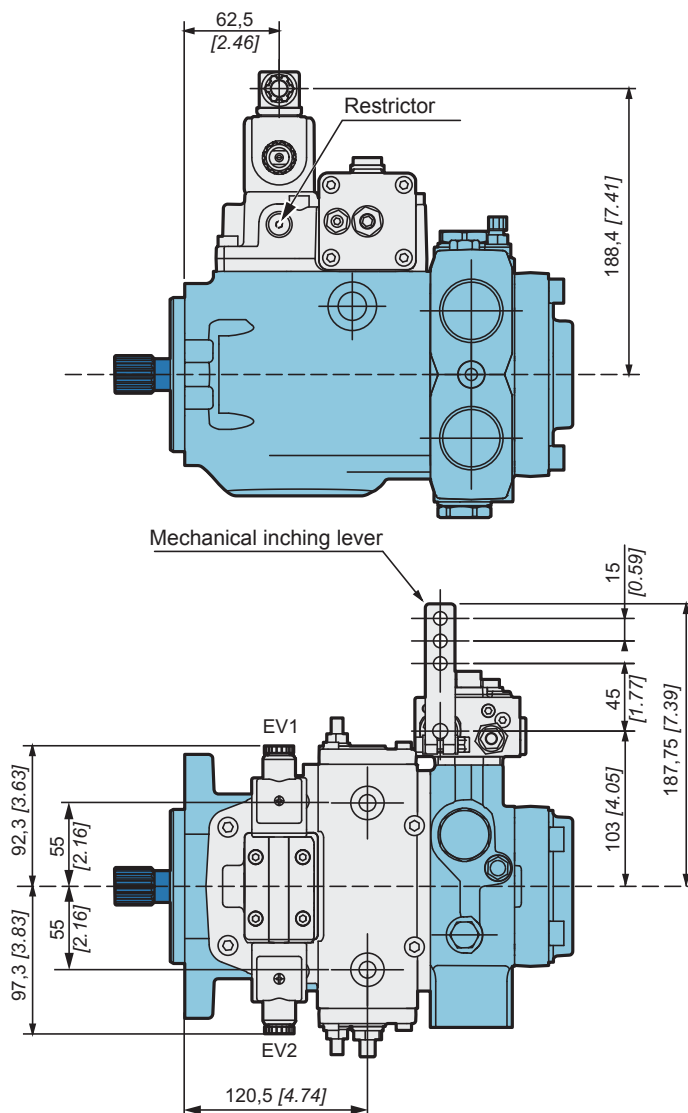
### Flow rate determination

Rotation	Pressure	Output	Input
Clockwise (R)	EV1	B	A
	EV2	A	B
Counter clockwise (L)	EV1	A	B
	EV2	B	A





### Dimensions (with option IC Mechanical inching)



See page 7 for other dimensions and port characteristics.

Model  
Code

Technical  
specifications

Operating  
Parameters

System design  
Parameters

Features

Controls

Options

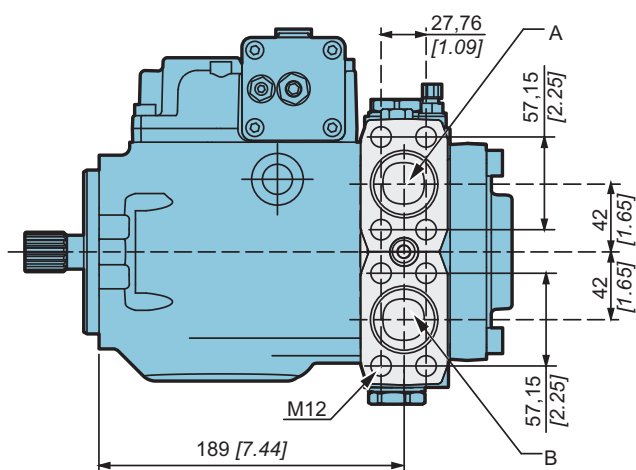




# OPTIONS

## SAE flange ports

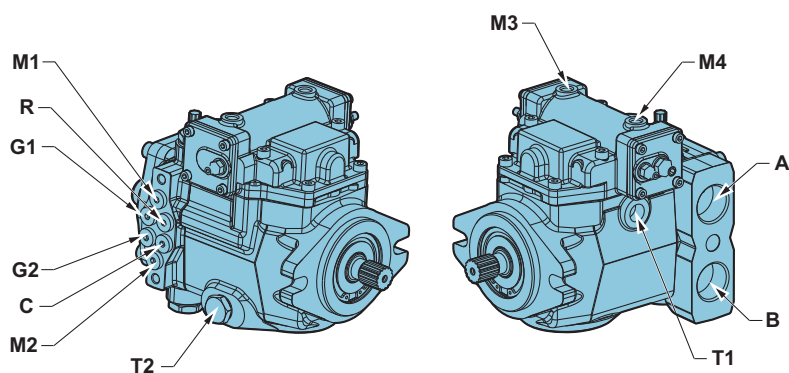
P	M	6	5	1	2	3	4	5	6	7	8	9	10	11
														FS



Port	Function	SAE
A-B	Services	1" flange SAE (414 bar [6 000 PSI])
G1/G2	Auxiliary	1/4" GAS
M1/M2	A-B pressure	1/4" GAS
M3/M4	Servo control	1/4" GAS
S	Suction	1" GAS
T1/T2	Drain	1/2" GAS
R	Servo pilot pressure	1/4" GAS
C	Case pressure	1/4" GAS

## UNF threads ports

P	M	6	5	1	2	3	4	5	6	7	8	9	10	11
														FU



Port	Function	UNF
A-B	Services	1 5/8 - 12
G1/G2	Auxiliary	1/2 - 20
M1/M2	A-B pressure	1/2 - 20
M3/M4	Servo control	1/2 - 20
S	Suction	1 5/16 - 12
T1/T2	Drain	7/8 - 14
R	Servo pilot pressure	1/2 - 20
C	Case pressure	1/2 - 20

## Mechanical inching

P	M	6	5	1	2	3	4	5	6	7	8	9	10	11
						D12 or D24								IC

For hydraulic automotive control D. An "Inching" lever is available to reduce the pilot pressure independently of the pump rotation speed. See Hydraulic automotive control D page 34.

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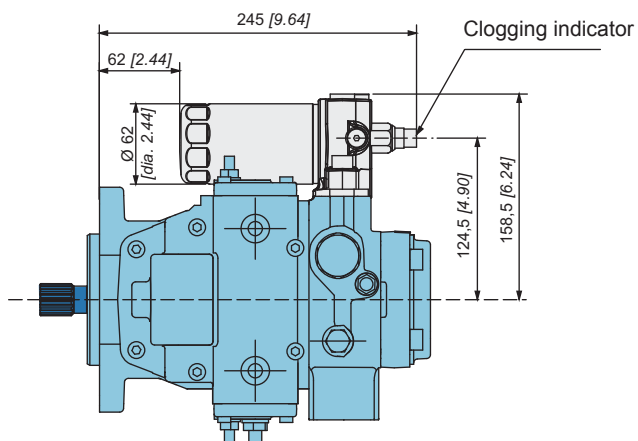
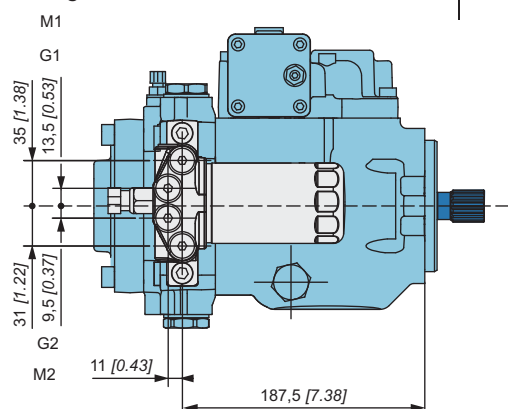
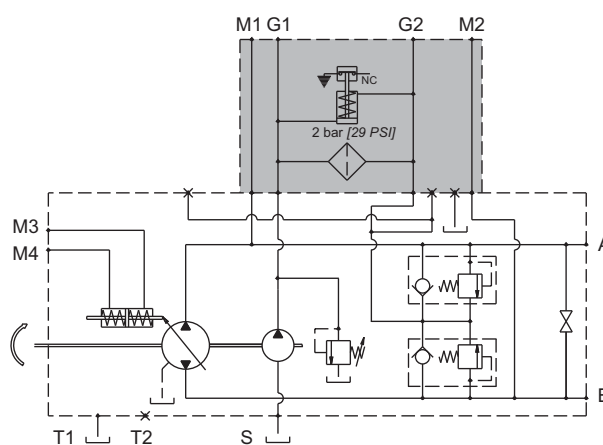
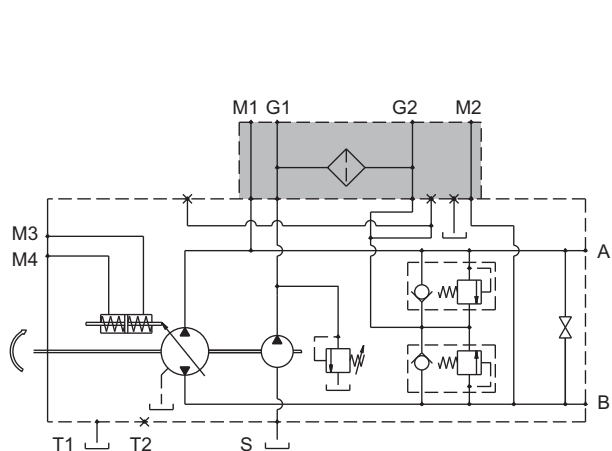
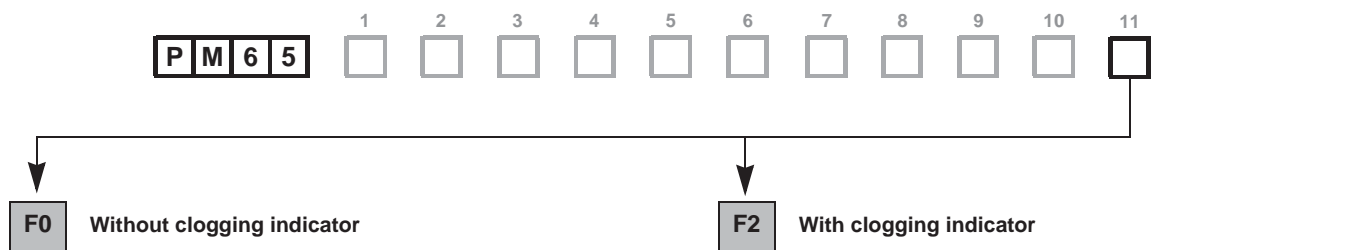
## Filter on pressure line

The PM65 pumps can have a pressure filter without clogging indicator (F0) or with clogging indicator (F2). The flow thru the filter is only the flow that entry in the close loop. The filter fitness is of 10 micron.

The max. working pressure is 30 bar [435 PSI].

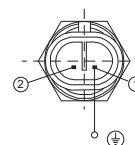
Maximum pressure difference between filter cartridge input and output is 2 bar [29 PSI]. When reaching 2 bar [29 PSI], the cartridge has to be changed.

Tightening torque: 35 Nm [309 in.lbf].



### Clogging indicator specification

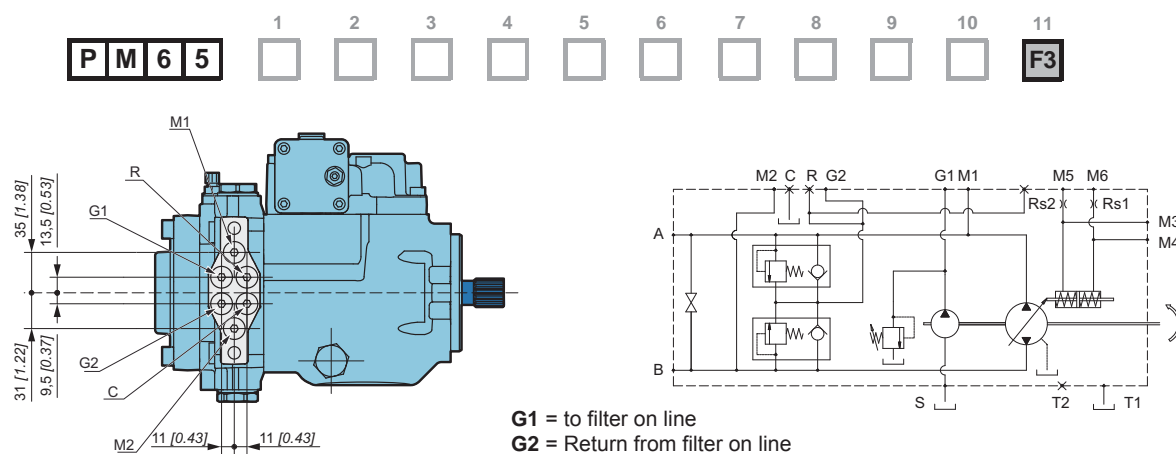
Differential working adjustment	3 ± 0,2 bar [44 ± 3 PSI]
Working temperature	-30°C ~ 110 °C [-22°F ~ 230°F]
Max. vibration level	50 g
Connector type	AMP super seal, 2 way
Current range	0,1-0,2 A max.



Normally closed contact.  
Thread of the clogging indicator is internally connected to ground.



### External connections for filter



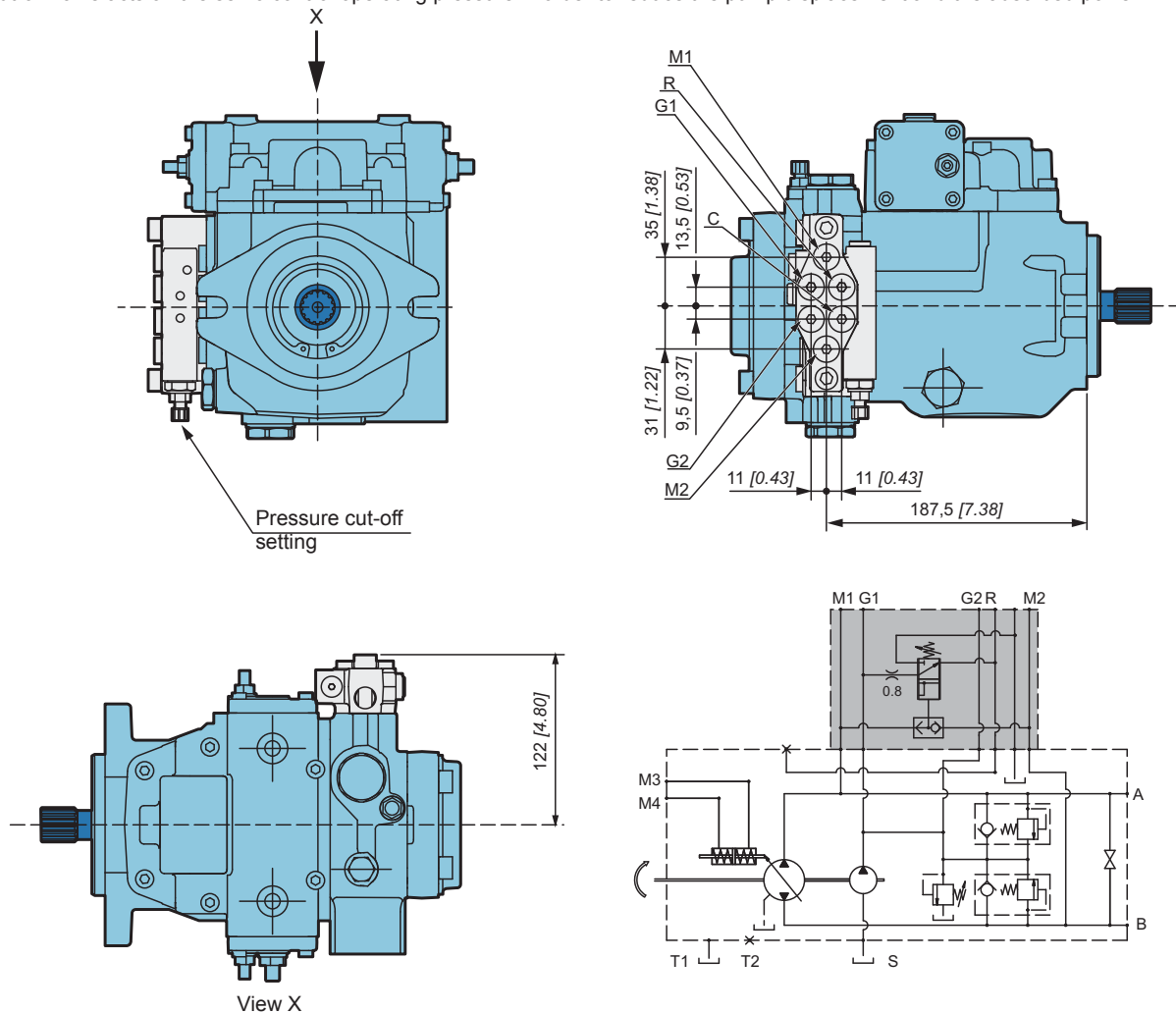
## Pressure cut-off valve



The function of the cut-off valve is to avoid that the pump absorbed power exceeds the machine engine power.

The cut-off valve is connected to A and B piston pump's high pressure lines and is usually set at 20 to 30 bar [290 to 435 PSI] lower than the maximum relief valve of the closed circuit.

The cut-off valve acts on the servo control operating pressure in order to reduce the pump displacement and the adsorbed power.

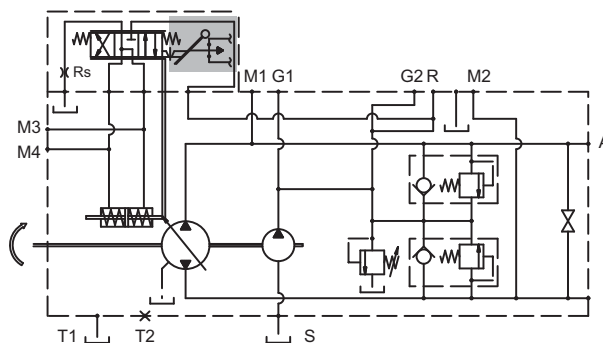
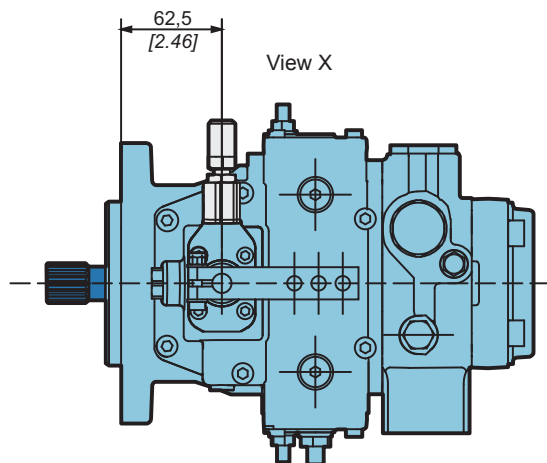
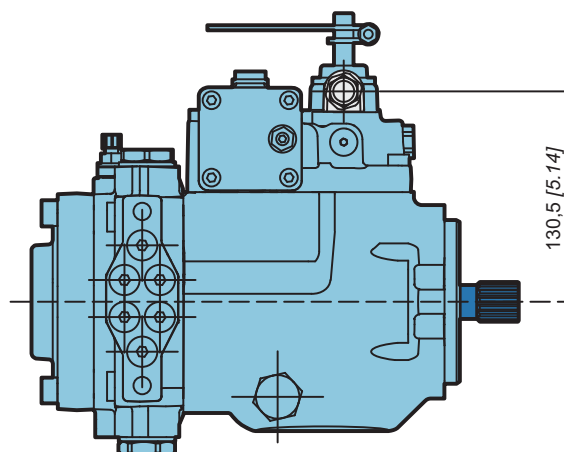
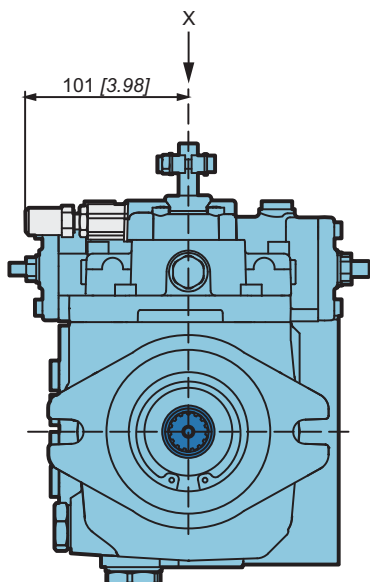




## Neutral position switch



For the control A (see page 26 Mechanical servo control with feed back) it is possible to obtain a micro switch to avoid the start of the engine if the lever of the control is not in center (zero position).



Type of connector: Deutsch DT04-2P

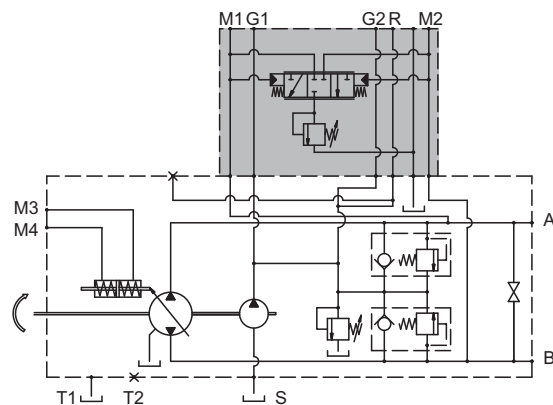
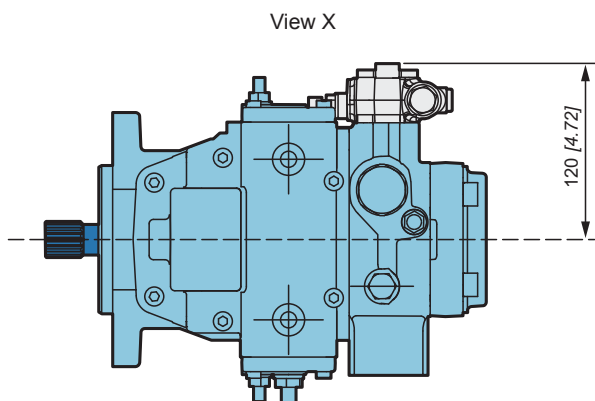
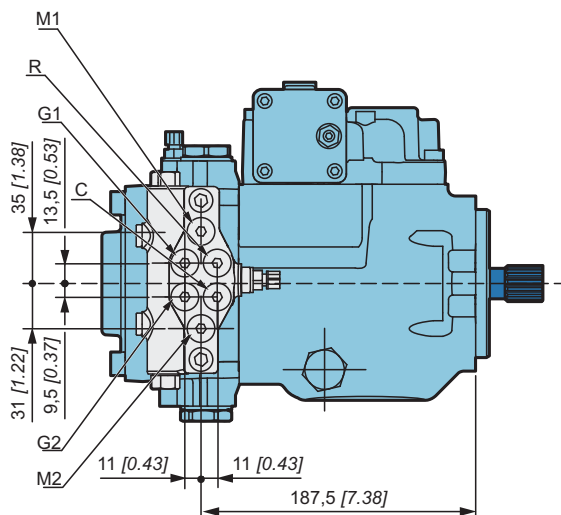
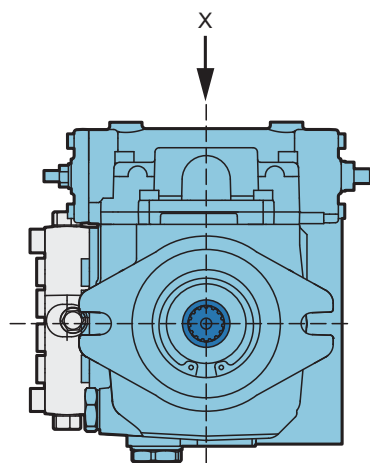




## Flushing valve



Inside the pump cover, a purge valve can be fitted with discharge inside the pump casing by means of a calibrated hole. The exchange valve is useful in case the temperature of the oil in the closed circuit is too high.



## Finishing coat



The pumps can be delivered with finishing coat when requested. Standard paint is RAL 9005 (black color).



Consult your Poclain Hydraulics application engineer for other colors of topcoat.

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## Customized identification plate



It is possible to provide our products with dedicated plate (your part number engraved on the plate) when requested.



This option is available only for minimum volume of 50 pieces.



Consult your Poclain Hydraulics application engineer for other possibilities.

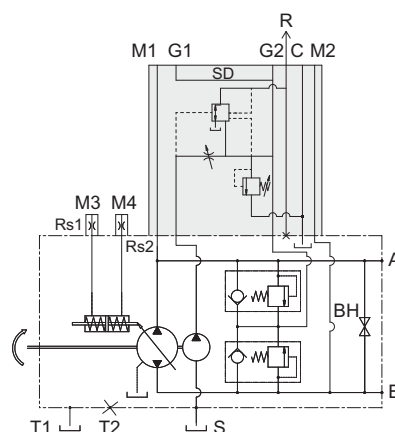
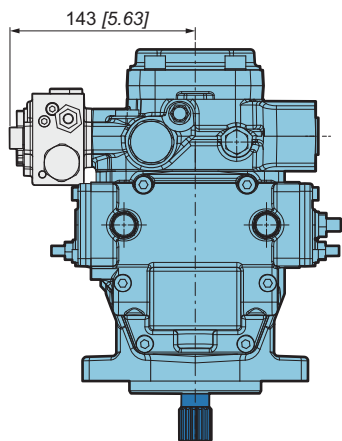
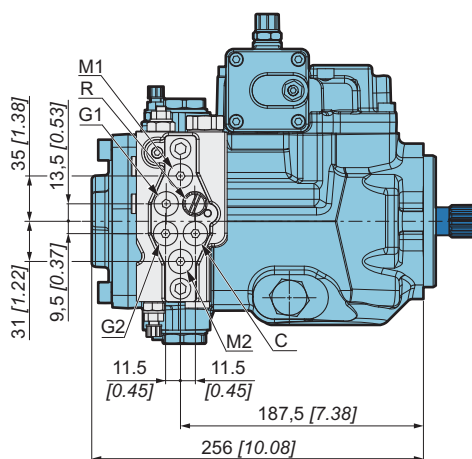
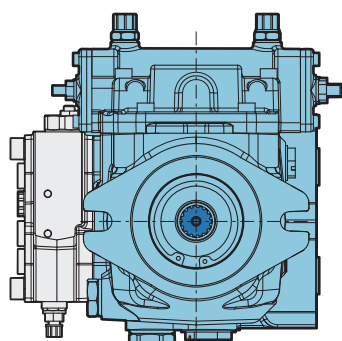
## Anti-stall valve



SD option consists of a block valve (same body as automotive valve) which provide a pressure signal for the servo piston of the pump related to the speed of engine. In case of engine overload and consequent rpm reduction the SD valve reduces the pressure for the servo piston and the pump de-stroke consequentially with an anti-stall effect.



For application of this option please contact your Poclain Hydraulics application engineer.





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